

FUNCTION c
ON AN ORDERED SYMMETRIC SPACE

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ABSTRACT

We prove by a direct computation an explicit formula for the c -function on the ordered symmetric spaces $SL(n, \mathbb{R})/SO(p, q)$. Our formula agrees with a formula conjectured in the general case by Faraut.

1. Ordered symmetric spaces and c -function.

In this section we present some basic facts concerning ordered symmetric spaces and their c -function. All these facts may be found in [FHO].

Let $M = G/H$ be a semisimple symmetric space where G is a connected semisimple Lie group with finite center and

$$(G^\sigma)_o \subset H \subset G^\sigma$$

for an involution σ of G .

Let the corresponding decomposition of the Lie algebra of G be

$$\mathfrak{g} = \mathfrak{h} + \mathfrak{q}.$$

A *causal structure* on M is a field of regular cones $M \ni x \rightarrow C_x \subset T_x M$. The space M is called *causal* if there exists on M a G -invariant causal structure or, equivalently, if there exists a regular $\text{Ad}(H)$ -invariant cone C in \mathfrak{q} . The space M is said to be *ordered* if it is causal and the causal structure on M is *global*, i.e. there is no non trivial closed causal curve.

Let θ be a Cartan involution of G commuting with σ and K the corresponding maximal compact subgroup. Let

$$\mathfrak{g} = \mathfrak{k} + \mathfrak{p}$$

be the related Cartan decomposition of \mathfrak{g} . The space G/H is ordered if and only if it is causal and $C \cap \mathfrak{k} = \{0\}$ or, equivalently, $(\mathfrak{p} \cap \mathfrak{q})^K \neq \{0\}$. In the case when the pair $(\mathfrak{g}, \mathfrak{h})$ is irreducible (i.e. there is no non trivial ideal in \mathfrak{g} which is invariant under σ) we have $\dim(\mathfrak{p} \cap \mathfrak{q})^{K \cap H} = 1$.

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Then there exists $X_o \in (\mathfrak{p} \cap \mathfrak{q})^{K \cap H}$ such that $\text{ad}X_o$ has eigenvalues $-1, 0, 1$ on \mathfrak{g} and

$$\mathfrak{g} = \mathfrak{g}_{-1} + \mathfrak{g}_0 + \mathfrak{g}_1$$

where $\mathfrak{g}_j = \{X \in \mathfrak{g} \mid \text{ad}X_o(X) = jX\}$, $j = -1, 0, 1$. There exists a Cartan subspace $\mathfrak{a} \subset \mathfrak{p} \cap \mathfrak{q}$ with $X_o \in \mathfrak{a}$. Let

$$\Delta_j = \{\alpha \in \Delta(\mathfrak{g}, \mathfrak{a}) \mid \mathfrak{g}_\alpha \subset \mathfrak{g}_j\} = \{\alpha \in \Delta(\mathfrak{g}, \mathfrak{a}) \mid \alpha(X_o) = j\}, \quad j = -1, 0, 1.$$

Denote by Δ_o^+ a positive root system in Δ_o and $\Delta^+ = \Delta_o^+ \cup \Delta_1$. Then one puts

$$\mathfrak{n}_o = \sum_{\alpha \in \Delta_o^+} \mathfrak{g}_\alpha, \quad \mathfrak{n}_1 = \sum_{\alpha \in \Delta_1} \mathfrak{g}_\alpha = \mathfrak{g}_1 \quad \text{and} \quad \mathfrak{n} = \mathfrak{n}_o + \mathfrak{n}_1.$$

$\mathfrak{n}, \mathfrak{n}_o$ and \mathfrak{n}_1 are nilpotent subalgebras of \mathfrak{g} ; moreover \mathfrak{n}_1 and $\bar{\mathfrak{n}}_1 = \mathfrak{g}_{-1} = \theta(\mathfrak{n}_1)$ are abelian. Denote by A, N, N_o, N_1 and \bar{N}_1 the analytic subgroups of G which have Lie algebras $\mathfrak{a}, \mathfrak{n}, \mathfrak{n}_o, \mathfrak{n}_1$ and $\bar{\mathfrak{n}}_1$ respectively. One knows that NAH is an open subset of G . If $g \in NAH$ one writes

$$g = n \exp(\mathcal{A}(g))h.$$

The function c on the ordered symmetric space M is given by the formula

$$c(\lambda) = \int_{\bar{N} \cap NAH} e^{(\rho+\lambda)(\mathcal{A}(\bar{n}))} d\bar{n}, \quad \lambda \in \mathfrak{a}_{\mathbb{C}}^*$$

if the integral converges; $\rho = \sum_{\alpha \in \Delta^+} m_\alpha \alpha$, m_α being the multiplicity of α . It is equal to the product

$$c(\lambda) = c_o(\lambda)c_{\mathcal{D}}(\lambda)$$

where c_o is the c -function of the Riemannian symmetric space G_o/K_o with $K_o = K \cap H$ and $G_o = N_oAK_o$ and $c_{\mathcal{D}}$ is given by

$$(1) \quad c_{\mathcal{D}}(\lambda) = \int_{\mathcal{D}} e^{(\rho+\lambda)(\mathcal{A}(\bar{n}))} d\bar{n}, \quad \lambda \in \mathfrak{a}_{\mathbb{C}}^*$$

with $\mathcal{D} = \bar{N}_1 \cap NAH$. The domains $\bar{N} \cap NAH$ and \mathcal{D} are bounded.

The knowledge of the function $c(\lambda)$ and of its domain is very important in the harmonic analysis on M . Spherical functions on M , defined by

$$\varphi_\lambda(x) = \int_H e^{(\rho-\lambda)(\mathcal{A}(hx))} dh$$

for $x \in \text{Int}(\exp(C)H) \subset NAH$, exist exactly for these $\lambda \in \mathfrak{a}_{\mathbb{C}}^*$ for which (1) converges. Function $c(\lambda)$ appears also in the asymptotic behaviour of φ_λ .

The c -function for an ordered symmetric space M has been determined for M of rank 1 and $M = G/H$ with G complex by Faraut, Hilgert and Olafsson ([FHO]) and for the symmetric spaces of Cayley type by Faraut ([F2]). In the last paper a formula for the c -function on an arbitrary ordered symmetric space has been conjectured.

In this note we compute the c -function on an important class of ordered symmetric spaces, the spaces $SL(n, \mathbb{R})/SO(p, q)$. These spaces may be identified with the spaces of symmetric matrices of determinant one with signature (p, q) . They appear naturally as the determinant one surfaces of connected components of the Euclidean Jordan algebra $V = Sym(n, \mathbb{R})$, different from the components of the identity matrix I and $-I$. They are also the determinant one surfaces of the non-Riemannian orbits of the structure group of V acting on V . Some results of harmonic analysis on such spaces, in the real and complex case, were obtained in [F1].

The formula that we obtain verifies the conjecture of Faraut ([F2]). Our method is based on an explicit computation of the function $\mathcal{A}(\bar{n})$ in the considered case. Computing of the integral (1) involves some algebraic identities of determinants.

As the function c on Riemannian symmetric spaces is well known ([GK]), it is sufficient to determine the function $c_{\mathcal{D}}$ defined in (1).

2. Some properties of determinants.

In this section we prove some elementary algebraic results used in the calculus of the c -function in the next section.

LEMMA 1. — *Let $X = (x_{ij})_{\substack{i=1, \dots, q \\ j=1, \dots, p}}$ be a matrix of dimension $q \times p$. Set $z = x_{1p}$. Then $\det(XX^t - I)$ is a quadratic function of z :*

$$\det(XX^t - I) = az^2 + bz + c$$

such that $a = \det(Y Y^t - I)$ and its discriminant

$$(2) \quad b^2 - 4ac = -4 \det(AA^t - I) \det(BB^t - I)$$

where Y, A and B are the submatrices of the matrix X defined by

$$Y = (x_{ij})_{\substack{i=2, \dots, q \\ j=1, \dots, p-1}}, \quad A = (x_{ij})_{\substack{i=1, \dots, q \\ j=1, \dots, p-1}} \quad \text{and} \quad B = (x_{ij})_{\substack{i=2, \dots, q \\ j=1, \dots, p}}.$$

Proof. — Denote by L the line $[x_{11} \dots x_{1,p-1}]$ and by C the column $\begin{bmatrix} x_{2p} \\ \vdots \\ x_{qp} \end{bmatrix}$.

Then $X = \begin{pmatrix} L & z \\ Y & C \end{pmatrix}$ and one has $\det(XX^t - I) = az^2 + bz + c$ with

$$a = \begin{vmatrix} 1 & C^t \\ C & YY^t + CC^t - I \end{vmatrix} = \det(YY^t - I),$$

$$b = 2 \begin{vmatrix} 0 & C^t \\ YL^t & YY^t - I \end{vmatrix} \quad \text{and} \quad c = \begin{vmatrix} LL^t - 1 & LY^t \\ YL^t & YY^t + CC^t - I \end{vmatrix}.$$

Observing that

$$\det(BB^t - I) = \det(YY^t - I + CC^t) = \det(YY^t - I) - \begin{vmatrix} 0 & C^t \\ C & YY^t - I \end{vmatrix}$$

and that

$$c = \det(AA^t - I) - (LL^t - 1) \begin{vmatrix} 0 & C^t \\ C & YY^t - I \end{vmatrix} - \gamma, \quad \gamma = \begin{vmatrix} 0 & 0 & C^t \\ 0 & 0 & LY^t \\ C & YL^t & YY^t - I \end{vmatrix}$$

we use $\det(AA^t - I) = (LL^t - 1) \det(YY^t - I) + \begin{vmatrix} 0 & LY^t \\ YL^t & YY^t - I \end{vmatrix}$ and we see

that (2) is equivalent to

$$\begin{vmatrix} 0 & LY^t \\ C & YY^t - I \end{vmatrix}^2 - \begin{vmatrix} 0 & C^t \\ C & YY^t - I \end{vmatrix} \begin{vmatrix} 0 & LY^t \\ YL^t & YY^t - I \end{vmatrix} = -\det(YY^t - I)\gamma$$

which follows from the next lemma. \square

LEMMA 2. — *Let S be a symmetric matrix of dimension $n \times n$ and $\mathbf{x}_1, \mathbf{x}_2, \mathbf{y}_1, \mathbf{y}_2 \in \mathbb{R}^n$. Define*

$$H(\mathbf{x}_1, \mathbf{x}_2, \mathbf{y}_1, \mathbf{y}_2) = \begin{vmatrix} 0 & \mathbf{y}_1 \\ \mathbf{x}_1^t & S \end{vmatrix} \begin{vmatrix} 0 & \mathbf{y}_2 \\ \mathbf{x}_2^t & S \end{vmatrix} - \begin{vmatrix} 0 & \mathbf{x}_2 \\ \mathbf{x}_1^t & S \end{vmatrix} \begin{vmatrix} 0 & \mathbf{y}_2 \\ \mathbf{y}_1^t & S \end{vmatrix}$$

$$\text{and} \quad K(\mathbf{x}_1, \mathbf{x}_2, \mathbf{y}_1, \mathbf{y}_2) = -\det S \begin{vmatrix} 0 & 0 & \mathbf{x}_2 \\ 0 & 0 & \mathbf{y}_1 \\ \mathbf{x}_1^t & \mathbf{y}_2^t & S \end{vmatrix}.$$

Then $H(\mathbf{x}_1, \mathbf{x}_2, \mathbf{y}_1, \mathbf{y}_2) = K(\mathbf{x}_1, \mathbf{x}_2, \mathbf{y}_1, \mathbf{y}_2)$ for all $\mathbf{x}_1, \mathbf{x}_2, \mathbf{y}_1, \mathbf{y}_2 \in \mathbb{R}^n$.

Proof. — As S is a symmetric matrix, there exists an orthonormal matrix U such that $D = USU^t$ is diagonal. It is then easy to see that the equality of H and K is equivalent to the equality of analogous forms defined with D in place of S . Thus we may suppose that S is diagonal.

Both forms H and K are bilinear forms in $\mathbf{x}_1, \mathbf{x}_2$ when $\mathbf{y}_1, \mathbf{y}_2$ are fixed and conversely. Thus in order to establish their equality it is enough to show that $H = K$ for $\mathbf{x}_1, \mathbf{x}_2, \mathbf{y}_1, \mathbf{y}_2$ in the canonical basis $\{\mathbf{e}_1, \dots, \mathbf{e}_n\}$ of \mathbb{R}^n . If S is diagonal with diagonal entries s_1, \dots, s_n , an easy direct computation gives for $i \neq j$

$$\begin{aligned} H(\mathbf{e}_i, \mathbf{e}_i, \mathbf{e}_j, \mathbf{e}_j) &= -\prod_{k \neq i} s_k \prod_{l \neq j} s_l = K(\mathbf{e}_i, \mathbf{e}_i, \mathbf{e}_j, \mathbf{e}_j) \\ H(\mathbf{e}_i, \mathbf{e}_j, \mathbf{e}_i, \mathbf{e}_j) &= \prod_{k \neq i} s_k \prod_{l \neq j} s_l = K(\mathbf{e}_i, \mathbf{e}_j, \mathbf{e}_i, \mathbf{e}_j) \end{aligned}$$

and $H = K = 0$ in other cases. \square

3. c -function on $SL(n, \mathbb{R})/SO(p, q)$.

In this section we deal with $M = G/H = SL(n, \mathbb{R})/SO(p, q)$ where $n = p+q$. The involution σ on G is given by $\sigma(g) = I_{pq}(g^t)^{-1}I_{pq}$ with $I_{pq} = \begin{pmatrix} I_p & 0 \\ 0 & -I_q \end{pmatrix}$. Then

$$\begin{aligned} H = G^\sigma, \mathfrak{h} = \mathfrak{so}(p, q) &= \left\{ \begin{pmatrix} A & B \\ B^t & D \end{pmatrix} \mid A \in \mathfrak{so}(p), D \in \mathfrak{so}(q), B \in M(p, q, \mathbb{R}) \right\} \\ \text{and } \mathfrak{q} &= \left\{ \begin{pmatrix} A & B \\ -B^t & D \end{pmatrix} \mid A, D \text{ symmetric, } \text{tr}A + \text{tr}D = 0, B \in M(p, q, \mathbb{R}) \right\}. \end{aligned}$$

The Cartan involution commuting with σ is given by $\theta(g) = (g^t)^{-1}$, the maximal compact subgroup $K = SO(n)$, $\mathfrak{k} = \mathfrak{so}(n)$, \mathfrak{p} is composed of symmetric matrices of trace 0.

$$\begin{aligned} \text{We have } \mathfrak{p} \cap \mathfrak{q} &= \left\{ \begin{pmatrix} A & 0 \\ 0 & D \end{pmatrix} \mid A, D \text{ symmetric, } \text{tr}A + \text{tr}D = 0 \right\} \text{ and} \\ (\mathfrak{p} \cap \mathfrak{q})^{K \cap H} &= \left\{ \begin{pmatrix} \alpha I_p & 0 \\ 0 & \beta I_q \end{pmatrix} \mid \alpha p + \beta q = 0 \right\} \text{ is of dimension 1.} \end{aligned}$$

If $X_o = \frac{1}{n} \begin{pmatrix} qI_p & 0 \\ 0 & -pI_q \end{pmatrix}$ then $X_o \in (\mathfrak{p} \cap \mathfrak{q})^{K \cap H}$ and $\text{ad}X_o$ has eigenvalues $-1, 0, 1$ on \mathfrak{g} . A Cartan space \mathfrak{a} contained in $\mathfrak{p} \cap \mathfrak{q}$ and containing X_o is the space of diagonal matrices of trace zero.

In the root system $\Delta = \Delta(\mathfrak{g}, \mathfrak{a}) = \{\alpha_{ij} \mid i \neq j\}$ with $\alpha_{ij}(\mathbf{t}) = t_i - t_j$ for $\mathbf{t} \in \mathfrak{a}$ with diagonal entries t_1, \dots, t_n we have the subsets

$$\begin{aligned} \Delta_o &= \{\alpha_{ij} \mid 1 \leq i \neq j \leq p \text{ or } p+1 \leq i \neq j \leq n\} \\ \Delta_1 &= \{\alpha_{ij} \mid 1 \leq i \leq p \text{ and } p+1 \leq j \leq n\} \\ \Delta_{-1} &= \{\alpha_{ij} \mid p+1 \leq i \leq n \text{ and } 1 \leq j \leq p\}. \end{aligned}$$

N is the upper triangular nilpotent group and \bar{N}_1 is the abelian nilpotent group of

matrices \bar{n} of the form

$$(3) \quad \bar{n} = \begin{pmatrix} I_p & 0 \\ X & I_q \end{pmatrix}$$

where $X \in M(q, p, \mathbb{R})$.

In order to evaluate the integral (1) defining the c -function of M we are going to determine explicitly the function $\mathcal{A}(\bar{n})$ for $\bar{n} \in \mathcal{D} = \bar{N}_1 \cap NAH$.

We will denote by X_k the matrix constructed from $X = (x_{ij})_{\substack{i=1, \dots, q \\ j=1, \dots, p}}$ by taking up its first $k-1$ lines and by X_{-l} the matrix which remains after taking up l columns on the right in X ($k = 1, \dots, q$; $l = 1, \dots, p-1$; $X_o = X_1 = X$):

$$X_k = (x_{ij})_{\substack{i=k, \dots, q \\ j=1, \dots, p}} \quad X_{-l} = (x_{ij})_{\substack{i=1, \dots, q \\ j=1, \dots, p-l}}.$$

LEMMA 3. — *If $\bar{n} \in \mathcal{D}$ is of the form (3) then $\mathcal{A}(\bar{n}) = \begin{pmatrix} t_1 & & 0 \\ & \ddots & \\ 0 & & t_n \end{pmatrix}$ with*

$$\begin{aligned} t_1 &= \frac{1}{2} \log \left(\frac{1}{\det(I - X_{-(p-1)} X_{-(p-1)}^t)} \right) \\ t_{p-l} &= \frac{1}{2} \log \left(\frac{\det(I - X_{-(l+1)} X_{-(l+1)}^t)}{\det(I - X_{-l} X_{-l}^t)} \right), \quad l = 0, \dots, p \\ t_{p+k} &= \frac{1}{2} \log \left(\frac{\det(I - X_k X_k^t)}{\det(I - X_{k+1} X_{k+1}^t)} \right), \quad k = 1, \dots, q-1 \\ t_n &= \frac{1}{2} \log(1 - X_q X_q^t). \end{aligned}$$

In particular $\bar{n} \in \mathcal{D}$ if and only if $\det(I - X_{-l} X_{-l}^t) > 0$, $l = 0, 1, \dots, p-1$ and $\det(I - X_k X_k^t) > 0$, $k = 1, \dots, q$.

Proof. — Suppose $\bar{n} = nah$ with $n \in N$, $a \in A$ and $h \in H$. Then

$$\bar{n} I_{pq} \bar{n}^t = n(I_{pq} a^2) n^t$$

and in order to write explicitly a and $\mathcal{A}(\bar{n}) = \log a$ we use the fact that the determinants of lower principal minors of $\bar{n} I_{pq} \bar{n}^t$ and $I_{pq} a^2$ are identical.

One has

$$\bar{n} I_{pq} \bar{n}^t = \begin{pmatrix} I_p & X^t \\ X & X X^t - I_q \end{pmatrix}.$$

Denote by D_j the determinant of the j -th lower principal minor of $\bar{n}I_{pq}\bar{n}^t$. One has

$$(4) \quad D_k = \det(X_{q-k+1}X_{q-k+1}^t - I), \quad k = 1, \dots, q$$

$$(5) \quad D_{q+l} = \det(X_{-l}X_{-l}^t - I), \quad l = 1, \dots, p-1$$

and

$$D_n = \det(\bar{n}I_{pq}\bar{n}^t) = (-1)^q.$$

In fact, (4) is obvious and in order to prove (5) we write

$$\bar{n} = \begin{pmatrix} I_p & 0 \\ X_{-l} & 0 & I_q \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ 0 & Z & 0 \end{pmatrix}$$

and we find $D_{q+l} = \begin{vmatrix} I & Z^t \\ Z & X_{-l}X_{-l}^t - I + ZZ^t \end{vmatrix} = \det(X_{-l}X_{-l}^t - I)$. Denoting by a_1, \dots, a_n the diagonal entries of a we have

$$D_1 = -a_n^2$$

$$D_k = (-1)^k a_{n-k+1}^2 \cdots a_{n-1}^2 a_n^2, \quad k = 1, \dots, q$$

$$D_{q+l} = (-1)^q a_{p-l+1}^2 \cdots a_p^2 \cdots a_n^2, \quad l = 1, \dots, p$$

and the lemma follows. □

Remark. — One knows from the general theory that the domain \mathcal{D} in our case is given by X belonging to the unit ball in $M(q, p, \mathbb{R})$, that is $\mathcal{D} = \{\bar{n} \mid I - XX^t \gg 0\}$. This coincides with the description of \mathcal{D} given in Lemma 3 used in the sequel.

Denote by

$$p_\lambda(\bar{n}) = e^{(\lambda+\rho)(\mathcal{A}(\bar{n}))}, \quad \bar{n} \in \mathcal{D}$$

the function integrated in (1). Put

$$\Delta_j = \det(I - X_{-(p+1-j)}X_{-(p+1-j)}^t), \quad j = 2, \dots, p$$

$$\Delta_{p+k} = \det(I - X_kX_k^t), \quad k = 1, \dots, q.$$

Lemma 3 shows that $\mathcal{D} = \{\Delta_j > 0, j = 2, \dots, n\}$.

COROLLARY. — If $\bar{n} \in \mathcal{D} = \bar{N}_1 \cap NAH$, $\lambda \in \mathfrak{a}_{\mathbb{C}}^*$ and $\mathbf{s} = \frac{1}{2}(\lambda + \rho)$ then

$$(6) \quad p_\lambda(\bar{n}) = \Delta_2^{s_2 - s_1} \Delta_3^{s_3 - s_2} \cdots \Delta_n^{s_n - s_{n-1}}.$$

In the following computation of the c -function we will use extensively the following analytic lemma([F2]).

LEMMA 4. — *Let $f(z) = az^2 + bz + c$ be a quadratic function with $a < 0$ and a positive discriminant Δ . Let α, β be the roots of f . Then for $\operatorname{Re}(s) > -1$*

$$\int_{\alpha}^{\beta} f(z)^s dz = 2^{-2s-1} \Delta^{s+\frac{1}{2}} |a|^{-s-1} B(s+1, \frac{1}{2}).$$

THEOREM 1. — *The function $c_{\mathcal{D}}$ on the ordered symmetric space $M = SL(n, \mathbb{R})/SO(p, q)$ is given by*

$$c_{\mathcal{D}}(\lambda) = \prod_{\substack{p+1 \leq i \leq n \\ 1 \leq j \leq p}} B\left(\frac{\lambda_i - \lambda_j + 1}{2}, \frac{1}{2}\right) = \prod_{\alpha \in \Delta_{-1}} B\left(\frac{\langle \lambda, \alpha \rangle}{2} + \frac{1}{2}, \frac{1}{2}\right)$$

for λ such that $\operatorname{Re}(\lambda_i - \lambda_j) > -1$, $p+1 \leq i \leq n$; $1 \leq j \leq p$.

Proof. — We first remark that the unique entry of the matrix X defining \bar{n} by (3) which appears in only one factor of (6) is x_{1p} . It is natural to start computing of $\int_{\mathcal{D}} p_{\lambda}(\bar{n}) d\bar{n}$ by integrating with respect to x_{1p} .

By Lemma 1

$$\Delta_{p+1} = (-1)^q \det(XX^t - I) = ax_{1p}^2 + bx_{1p} + c$$

with $a = -\det(I - YY^t)$, where Y is the submatrix of X given by

$$Y = (x_{ij})_{\substack{i=2, \dots, q \\ j=1, \dots, p-1}}$$

and the discriminant equal to $4 \det(I - X_{-1}X_{-1}^t) \det(I - X_2X_2^t) = 4\Delta_p \Delta_{p+2} > 0$. As \mathcal{D} is bounded and $\Delta_{p+1} > 0$ on \mathcal{D} it follows that $a < 0$. Let $\alpha < \beta$ be the roots of $\Delta_{p+1}(x_{1p})$. Then $\bar{n} \in \mathcal{D}$ if and only if $\Delta_j > 0$, $j \neq p+1$, $\det(I - YY^t) > 0$ and $x_{1p} \in (\alpha, \beta)$. Using Lemma 4 we see that

$$\int_{\alpha}^{\beta} \Delta_{p+1}^{s_{p+1}-s_p} dx_{1p} = (\Delta_p \Delta_{p+2})^{s_{p+1}-s_p+\frac{1}{2}} \det(I - YY^t)^{-s_{p+1}+s_p-1} B(s_{p+1}-s_p+1, \frac{1}{2})$$

for $\operatorname{Re}(s_{p+1} - s_p) > -1$ and the integral diverges otherwise.

Next we integrate in the same way, using Lemma 1 and Lemma 4, successively with respect to $dx_{1,p-1}, \dots, dx_{12}$. In order to integrate with respect to dx_{11} we remark that

$$\Delta_2 = 1 - (x_{11}^2 + x_{21}^2 + \dots + x_{q1}^2)$$

and we use a change of variables

$$(7) \quad x_{11} = x \sqrt{1 - (x_{21}^2 + \dots + x_{q1}^2)}.$$

Finally, after the integration with respect to all the variables in the first line of X we obtain

$$(8) \quad \int_{\mathcal{D}} p_{\lambda}(\bar{n}) d\bar{n} = \prod_{j=1}^p B\left(s_{p+1} - s_j + \frac{p-j+2}{2}, \frac{1}{2}\right) \\ \times \int_{\tilde{\mathcal{D}}} \tilde{\Delta}_2^{s_2-s_1} \dots \tilde{\Delta}_p^{s_p-s_{p-1}} \Delta_{p+2}^{s_{p+2}-s_p+\frac{1}{2}} \Delta_{p+3}^{s_{p+3}-s_{p+2}} \dots \Delta_n^{s_n-s_{n-1}} dx_{21} \dots dx_{qp}$$

where $\tilde{\Delta}_j = \det(I - Y_{-(p-j)} Y_{-(p-j)}^t)$, $j = 2, \dots, p$ (one sets $Y_o = Y$) and $\tilde{\mathcal{D}} = \{\tilde{\Delta}_j > 0, j = 2, \dots, p, \Delta_k > 0, k = p+2, \dots, n\}$ is isomorphic to the unit ball in $M(q-1, p, \mathbb{R})$.

Let \tilde{c} be the c -function of the space $SL(n-1, \mathbb{R})/SO(p, q-1)$. Then (8) may be written

$$c_{\mathcal{D}}(\lambda) = \tilde{c}_{\tilde{\mathcal{D}}}(\tilde{\lambda}) \prod_{j=1}^p B\left(\frac{\lambda_{p+1} - \lambda_j}{2} + \frac{1}{2}, \frac{1}{2}\right)$$

where $\tilde{\lambda} = (\lambda_1 + \frac{1}{2}, \dots, \lambda_p + \frac{1}{2}, \lambda_{p+2} + \frac{1}{2}, \dots, \lambda_n + \frac{1}{2})$.

The theorem follows by induction if we prove it for the space $SL(p+1, \mathbb{R})/SO(p, 1)$. This is easy and follows by a series of changes of variables analogous to (7) and by Lemma 4. \square

Remark. — In the case of the ordered symmetric spaces $SL(n, \mathbb{C})/SU(p, q)$ of Hermitian matrices of signature (p, q) and determinant 1, using a similar argument as in the proof of Theorem 1, one derives for λ such that $\operatorname{Re}(\lambda_i - \lambda_j) > 0$, $p+1 \leq i \leq n$; $1 \leq j \leq p$ the formula

$$c_{\mathcal{D}}(\lambda) = \frac{(2\pi)^{pq}}{\prod_{\alpha \in \Delta_{-1}} \langle \lambda, \alpha \rangle}$$

which was obtained by a different method for all ordered symmetric spaces of Olshanskii type in [FHO].

One can apply our method of computation of the c -function to other ordered symmetric spaces which appear as the determinant one surfaces of the non-Riemannian orbits of the structure group on a Euclidean Jordan algebra: the spaces $SL(n, \mathbb{H})/SO(p, q, \mathbb{H})$ (quaternion case) and $SL(3, \mathbb{O})/SO(1, 2, \mathbb{O})$ (the exceptional octonion case).

In [F1] an integral formula for spherical functions φ_{λ} on $M = SL(n, \mathbb{R})/SO(p, q)$ was obtained. Theorem 1 allows to determine the set of $\lambda \in \mathfrak{a}_{\mathbb{C}}^*$ for which these spherical functions exist.

COROLLARY. — *The spherical functions φ_{λ} on $M = SL(n, \mathbb{R})/SO(p, q)$ are defined for λ such that $\operatorname{Re}(\lambda_i - \lambda_j) > -1$, $p+1 \leq i \leq n$; $1 \leq j \leq p$.*

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