

# The Lewowicz number of linear diffeomorphisms on the torus

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**ABSTRACT.** We prove that 2 is a Lewowicz number of every linear Anosov diffeomorphism on the torus. This result is independent of any linear metric and provides an explicit Lyapounov function for the diffeomorphisms.

*Key words and phrases.* Manifold, Riemannian manifold, Anosov diffeomorphism, quadratic form, positive definite quadratic form.

*1991 Mathematics Subject Classification.* Primary 58F15 Secondary 15A3.

## 1. Introduction

For an Anosov diffeomorphism  $f$  defined on a compact Riemannian manifold, J. Lewowicz [1] has proved the existence of an integer  $m$  which provides information about properties of  $f$  like expansivity and persistence. Such number allows us to obtain a quadratic form  $a$  with the properties given below. That quadratic form has been used to define, via suspension of  $f$ , two-variable Lyapunov functions which can be used to establish structural stability of Anosov diffeomorphisms (see for instance [2]). In [3], Rueda observed such a number as associated to an invariant compact hyperbolic set, proving therefrom a kind of stability of those sets; which had also been noticed by Shubb [4] in 1968. In Theorem 1 below we compute explicitly the Lewowicz's Number for the class of linear diffeomorphisms on the torus relative to any quadratic form obtained,

on the tangent bundle, from a constant quadratic form on  $\mathbb{R}^2$ . In terms of applications, the size of  $m$  provides an idea of the difficulty to obtain  $a$ . However, for the cases considered here the second iteration is enough, as established by Theorem 1.

## 2. The Lewowicz number concept

Let  $q$  be a quadratic form on a compact manifold  $M$ , and suppose  $f$  is a diffeomorphism of  $M$ . Then we can define

$$(f^*q)(\vec{u}, \vec{v}) = q(Df(\vec{u}), Df(\vec{v})).$$

We shall be mainly concerned with the particular case when  $q$  is a quadratic positive definite form. We will write  $m \in L(q, f)$  if the following conditions are fulfilled:

1.  $a = \sum_{i=0}^{m-1} f^{*i}q$  is positive definite.
2.  $b = f^*a - a$  is non-degenerate everywhere on  $M$ .
3.  $c = f^*b - b$  is positive definite.

J. Lewowicz [1] has proved that

**Lemma 1.** (Lewowicz). *If  $f : M \rightarrow M$  is an Anosov diffeomorphism then for any positive definite quadratic form  $q$  in  $M$  there exists an integer  $m$  such that  $m \in L(q, f)$ .*

## 3. Linear diffeomorphisms on the torus

Let

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix},$$

where  $a, b, c, d$  are integers. Then  $A$  induces a function  $\varphi_A : T_2 \rightarrow T_2$  such that, when  $\det A \neq 0$ ,  $\varphi_A$  is a covering, and when  $\det A = \pm 1$ ,  $\varphi_A$  is a diffeomorphism. Furthermore,

$\det A$	$ \text{trace } A $	$\varphi_A$
1	$> 2$	Anosov
-1	$> 0$	Anosov

In order to verify that  $m \in L(q, \varphi_A)$  for a  $q$  with constant coefficients,

$$q(\vec{u}) = (u_1)^2 + 2su_1u_2 + r^2(u_2)^2,$$

we will resort to the non-negativity of certain polynomials. The use of a symbolic processor may be helpful.

**Theorem 1.** *Let  $A$  be such that  $\varphi_A$  is Anosov. Then*

- (1)  $1 \in L(q, \varphi_A)$  if  $q$  is positive definite and  $\det A = 1$ .
- (2)  $1 \in L(q, \varphi_A)$  if  $q$  is positive definite,  $\det A = -1$  and  $|\text{trace } A| = 2$ .
- (3)  $2 \in L(q, \varphi_A)$ , if  $q$  is positive definite.

*Proof.* Assume first  $\det A = 1$ . Then  $1 \in L(q, \varphi_A)$  if and only if

$$F = .q \left( A^2 \begin{pmatrix} x \\ y \end{pmatrix} \right) - 2q \left( A \begin{pmatrix} x \\ y \end{pmatrix} \right) + q \begin{pmatrix} x \\ y \end{pmatrix} > 0$$

for  $(x, y) \neq 0$ , and since  $F$  is a polynomial of degree 2 in  $x, y$ , say  $F = F_0x^2 - 2F_1xy + F_1y^2$ , the proof simply reduces to verifying that  $D = F_2F_0 - \left(\frac{F_1}{2}\right)^2 > 0$ . We can write  $b = \frac{-1+ad}{c}$ , because if  $A$  is a hyperbolic and integer matrix then  $c \neq 0$ . Then we consider  $D_1 = c^2D$ , where  $b$  has been replaced by its expression in terms of  $a, d$  and  $c$ . This is a polynomial of degree 4 in  $c$ . Its coefficients are polynomials in the variables  $a, d, s, r$ . However,  $D_1$  is a multiple of  $4 - (\text{trace } A)^2$ , and since  $\varphi_A$  is Anosov, we must have  $|\text{trace } A| > 2$ , and the problem reduces to establishing the positivity of  $Q = \frac{D_1}{(\text{trace } A)^2 - 4}$ . We note that since  $Q$  is a polynomial of second degree in  $a$ ,  $Q = Q_2a^2 - Q_2^a + Q_0$ , its positivity can be deduced from the fact that

$$L = Q_2Q_0 - \left(\frac{Q_1}{2}\right)^2 = -c^2(s-r)(s+r)(-2csd - 1 + d^2 + r^2c^2)^2$$

is positive. Because  $q$  being positive definite is equivalent to  $|s| < r$ , it is clear that  $L \geq 0$ . But  $L = 0$  implies that  $a = \frac{Q_1}{2Q_2}$ , which leads to  $\text{trace } A = 0$ . Thus,  $F$ , as a quadratic form whose coefficients are continuous in the variables  $a, c, d, s, r$ , has negative discriminant on the set

$$U = \{(a, d, c, s, r) / |a + d| \geq 3, |c| \geq 1, |s| < r\}.$$

But in each connected component of  $U$  there exists a point where the coefficient of  $x^2$  is positive. Then  $F$  is positive definite for every point in  $U$  (this holds for any integer matrix with determinant equal to 1) and the proof of (1) is finished. Now, if  $A$  is an integer hyperbolic matrix with determinant  $-1$ ,  $A^2$  is hyperbolic with determinant 1. Then, according to the definition of  $m$ ,  $2 \in L(q, \varphi_A)$  is equivalent to  $1 \in L(q, \varphi_{A^2})$ , and (3). in Theorem 1 is proved.

To prove (2), we note that  $D_1$  can be written in the case of  $\det A = 1$ , but  $D_1$  is not divisible by  $(\text{trace } A)^2 - 4$ . However, considered as a polynomial in the variable  $c$ ,  $D_1$  is of degree 4,  $D_1 = P_0 + P_1c + P_2c^2 + P_3c^3 + P_4c^4$ , and among  $P_0, P_1, P_2, P_3$  and  $P_4$ , the only one which is not divisible by  $(\text{trace } A)^2 - 4$  is  $P_2$ , which is

$$P_2 = ((\text{trace } A)^2 - 4)R(a, d, s, r) + 16(r^2 - s^2).$$

Then, if  $|\text{trace } A| = 2$ ,  $D_1$  is positive for every positive definite  $q$ . On the other hand,  $L$ , the coefficient of  $x^2$  in  $F$ , takes, after replacing  $b = \frac{1+ad}{c}$  and having taken into account that  $\text{trace } A = \pm 2$ , the form

$$L = 18 \mp 12d + 2c^2r^2 - 4csd + 2d^2 \pm 12cs = L_0 + L_1d + L_2d^2$$

with

$$L_0 = 18 + 2cR^2 \pm 12cs, \quad L_1 = \mp 12 - 4cs, \quad L_2 = 2.$$

Here the discriminant of  $L$  is  $D_L = L_2L_0 - (L_1/2)^2 = c^2(r^2 - s^2)$ , which is positive for all positive definite  $q$ . Since  $L_2$  is positive then  $L$  is positive. So, in all cases where  $q$  is positive definite,  $F$  has a positive coefficients in  $x^2$ , and since the discriminant of  $F$  has the same sign as  $D_1$ , then  $F$  is positive definite provided  $\text{trace } A = \pm 2$  and  $\det A = -1$ . The theorem is proved.  $\square$

Following a different line of argument we can improve Theorem 1 in the case of  $\det A = -1$ .

**Theorem 2.** *If  $\det A = -1$  and  $|\text{trace } A| \geq 3$ , then  $1 \in L(q, \varphi_A)$  for every positive definite  $q$ .*

*Proof.* Let  $q(\vec{u}) = x^2 + 2sxy + r^2y^2$ , where  $\vec{u} = (x, y)$ . Then

$$q(\vec{u}) = (x + sy)^2 + (r^2 - s^2)y^2,$$

and taking as new coordinates for  $\vec{u}$ ,  $x_1 = x + sy$  and  $y_1 = y\sqrt{r^2 - s^2}$ , this becomes

$$q(\vec{u}) = x_1^2 + y_1^2.$$

In order to emphasize the geometrical character of the argument we write  $\|\vec{u}\|_q = \sqrt{q(\vec{u})}$ . Now observe that if  $|\lambda|$  is the eigenvalue with absolute value bigger than 1 in the matrix  $A$ , then  $|\text{trace } A| = |\lambda| - \frac{1}{|\lambda|}$  and

$$|\lambda| \geq \frac{3 + \sqrt{13}}{2}.$$

It is clear that every vector  $\vec{u}$  can be written in the form  $\vec{u} = \vec{u}_1 + \vec{u}$  where  $\vec{u}_1$  and  $\vec{u}_2$  are eigenvectors corresponding to  $\lambda$ ,  $\lambda^{-1}$ , and that

$$(\|\vec{u}\|_q)^2 = (\|\vec{u}_1\|_q)^2 + (\|\vec{u}_2\|_q)^2 + 2\|\vec{u}_1\|_q\|\vec{u}_2\|_q \cos \varphi,$$

where  $\varphi$  is the angle between  $\vec{u}_1$  and  $\vec{u}_2$  in the scalar product corresponding to the norm. From

$$A(\vec{u}) = \lambda\vec{u}_1 - \frac{1}{\lambda}\vec{u}_2,$$

it follows that

$$(\|(A\vec{u})\|_q)^2 = \lambda^2(\|\vec{u}_1\|_q)^2 + \frac{1}{\lambda^2}(\|\vec{u}_2\|_q)^2 - 2\|\vec{u}_1\|_q\|\vec{u}_2\|_q \cos \varphi.$$

Hence, if we assume  $\|\vec{u}_1\|_q \geq \|\vec{u}_2\|_q$ , we obtain that

$$\begin{aligned} (\|A\vec{u}\|_q)^2 &= (\lambda - 8)(\|\vec{u}_1\|_q)^2 + 2(\|\vec{u}_1\|_q)^2 + 4\|\vec{u}_1\|_q\|\vec{u}_1\|_q + \frac{1}{\lambda^2}(\|\vec{u}_2\|_q)^2 \\ &\quad + (2\|\vec{u}_1\|_q\|\vec{u}_1\|_q - 2\|\vec{u}_1\|_q\|\vec{u}_2\|_q \cos \varphi) \\ &\geq (\lambda^2 - 8)(\|\vec{u}_1\|_q)^2 + 2(\|\vec{u}_2\|_q)^2 + 4\|\vec{u}_1\|_q\|\vec{u}_2\|_q \cos \varphi \\ &= 2((\|\vec{u}_1\|_q)^2 + (\|\vec{u}_2\|_q)^2 + 2\|\vec{u}_1\|_q\|\vec{u}_2\|_q \cos \varphi) + (\lambda^2 - 10)(\|\vec{u}_1\|_q)^2. \end{aligned}$$

Thus  $q(A\vec{u}) < 2q(\vec{u})$  if  $\lambda^2 \geq 10$ , and a similar analysis shows in the case  $q(\vec{u}_1) < q(\vec{u}_2)$  that  $q(A^{-1}(\vec{u})) < 2q(\vec{u})$ .

So, since  $\left(\frac{3+\sqrt{13}}{2}\right)^2 > 10$ , we are led to the alternative  $q(A\vec{u}) > 2q(\vec{u})$  or  $q(A^{-1}(\vec{u})) > q(\vec{u})$ . But

$$\begin{aligned} q(A^2(\vec{u})) - 2q(A\vec{u}) + q(\vec{u}) &= q(A(A\vec{u})) - q(A\vec{u}) + q(\vec{u}) \\ &= q(A^{-1}(A\vec{u})) - q(A\vec{u}) + q(A^2(\vec{u})). \end{aligned}$$

Then, by the preceding alternative applied to vector  $A(\vec{u})$ , we get

$$q(A^2(\vec{u})) - 2q(A\vec{u}) + q(\vec{u}) > 0$$

for every  $\vec{u} \neq 0$ , which completes the proof.  $\square$

**ACKNOWLEDGMENTS.** We thank the CONDES, Universidad del Zulia, Maracaibo, Venezuela, for financial support.

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(Recibido en julio de 1995)

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