



## Bibliography on higher-order statistics

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### Introduction

The last fifteen years have witnessed a tremendous resurgence in research and applications in the area of *higher-order statistics* (HOS), a broad term encompassing statistical descriptors of orders greater than two: higher-order moments and cumulants, moment spectra and polyspectra, which are natural generalizations of second-order statistics (SOS) – the correlation and the spectrum.

Although the roots of HOS literature can be traced back to Kolmogorov (and possibly Gauss), the pioneering work of statisticians in North America and Eastern Europe in the 1960s was – apart from scattered contributions in the physical sciences – largely ignored by the signal processing community until the early 1980s. Following the saturation point of advances in spectral estimation methods, HOS held out the promise of addressing the following “non” topics associated with signals and systems: non-Gaussianity, non-minimum phase, non-causality, non-linearity, and more recently, non-additivity and non-stationarity.

Special purpose hardware and faster computers allow us to handle the increased dimensionality and computational complexity of HOS-based algorithms, which have been developed for a wide range of applications, such as: time-delay estimation in sonar, EEG signal analysis, imaging through turbulence, nonlinear ocean wave interactions, radar, seismic deconvolution, blind channel equalization, removal of atmospheric effects in astronomical data, harmonic retrieval, bio-signal processing, detection and classification of non-Gaussian signals, array and image data processing, (source) separation of mixtures of signals, analysis of chaotic systems, non-stationary and cyclo-stationary signal analysis.

The revived popularity of HOS is due to some *unique* features and advantages which they offer over SOS, namely:

- HOS of non-Gaussian linear processes convey not only amplitude, but also complete phase information and, as such, they have been used for time-series modeling, and identification of non-minimum phase and non-causal systems. Relevant applications include signal reconstruction from speckle images, seismic deconvolution, and equalization of communication channels.

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- Gaussian processes are completely described by SOS: the HOS of Gaussian signals vanish. Thus, HOS “measure” non-Gaussianity and can be used to separate additive mixtures of independent non-Gaussian signals and Gaussian noise. Therefore, it is natural that tests for (non-)Gaussianity are based on HOS; similarly, researchers have exploited HOS-domains for the detection and classification of non-Gaussian signals, and for the suppression of additive Gaussian noise, whose covariance function may not be known.
- HOS appear naturally in the spectral analysis of nonlinear processes, in the identification of nonlinear systems (Volterra kernels), and in tests for (non-)linearity.
- HOS-based tools are natural candidates for the modeling and analysis of chaotic systems, and their performance evaluation.
- HOS are useful to characterize the dependence on random signals and show up even in the performance analysis of SOS-based estimators.
- HOS facilitate the modeling, estimation, analysis and application of *polynomial phase* signals which appear to be useful in a variety of scenarios, ranging from Doppler radar to speech to bio-signal processing.
- Multiplicative noise models are useful to model certain kinds of non-stationary behavior; and, multiplicative noise, itself, arises naturally in several applications; examples include scattering of acoustic returns in active sonar, analysis of signals recorded from rotating machinery (failure prediction and condition monitoring), image processing, and bio-signal processing. Signal analysis, in the presence of multiplicative noise, naturally involves HOS.
- Short-time and evolutionary polyspectra, higher-order and generalized Wigner-Ville distributions, offer new perspectives on the data, in addition to those offered by their second-order counterparts.
- Blind identification of multi-channel systems and blind source separation are two other areas where higher-order statistics have made critical contributions. Blind identification of multi-channel systems based on second-order statistics is unique only to within multiplication by a unitary matrix; with higher-order statistics, the multiplication ambiguity is reduced to the class of signed permutation matrices.

Of course, HOS do not offer a panacea for all problems; and, one may have to use statistics and tools other than SOS and HOS.

The first bibliography on HOS was compiled by Tryon [1527] in 1981; it offers a collection of 134 papers – primarily on the bispectrum, and catalogs HOS-related research and applications in the 1960s and 1970s. The second bibliography by Nielsen and Walsh [1042] represents a collection of 258 entries. This bibliography contains 1759 entries, and is indicative of the explosive research in the area in the period 1984–1996.

We have made every effort to include conference and journal papers, and theses up to the end of December 1996; however, the area is rapidly expanding, and omissions are inevitable; we apologize for those papers which are not included here; some citations may have been omitted because we were unable to obtain enough information to ensure uniqueness. HOS-based publications are available in several other languages, but in order to ensure a list of widely accessible publications, we have limited most of our entries to publications in English.

The bibliography is divided into two parts: (1) Alphabetical/chronological; and (2) By subject. The classification keys reflect the authors' background (and hence, biases) in statistical signal processing, as do the journals which we have exhaustively searched (primarily the engineering databases). Corrections and additions may be e-mailed to the first author at [a.swami@ieee.org](mailto:a.swami@ieee.org).

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## 1. Theory

12 84 301 379 1471 1627 1678 1748

### 1.1. Estimators, asymptotics, and performance analysis

21 22 23 145 150 152 163 164 193 218 241 320 328  
 334 438 440 452 480 531 627 756 816 840 841 842  
 866 879 887 985 986 909 916 1017 1019 1015 1023  
 1098 1103 1119 1121 1129 1163 1170 1187 1198  
 1199 1224 1244 1246 1250 1280 1337 1351 1352  
 1355 1394 1395 1399 1452 1454 1510 1511 1526  
 1528 1640 1697 1707 1706 1740 1736 1741 1747  
 1749 1750

### 1.2. Detection and classification

1 6 41 68 77 89 90 208 211 286 302 313 325 333 341  
 343 344 369 391 392 389 403 485 502 503 521 549  
 550 551 552 548 647 650 665 684 689 699 710 737  
 784 786 787 808 809 872 909 910 935 987 992 1029  
 1043 1094 1112 1117 1135 1136 1134 1140 1141  
 1142 1152 1154 1156 1170 1216 1223 1266 1267  
 1268 1271 1273 1275 1276 1287 1293 1361 1364  
 1369 1372 1400 1457 1476 1481 1486 1500 1528  
 1531 1532 1533 1535 1536 1604 1605 1611 1613  
 1620 1634 1643 1659 1677 1680 1679 1684 1732  
 1737 1758

### 1.3. Identification

78 150 432 549 336 926 929 940 984 1152 1201 1202  
 1214 1253 1284 1466 1467 1474 1501 1512 1528  
 1563 1567 1568 1581 1591 1600 1610 1641 1658  
 1669 1675

#### 1.3.1. Linear model identifiability

311 355 454 457 459 520 521 522 546 1466 1474  
 1543 1618 1615 1673

#### 1.3.2. Nonlinear – Volterra expansion

27 40 81 87 100 103 114 116 117 134 139 140 151  
 155 272 352 363 670 699 795 796 798 797 802 805  
 844 1072 1150 1151 1181 1183 1184 1439 1537 1548

### 1.4. Information: entropy and prediction

43 139 243 244 247 248 246 292 340 376 496 547  
 612 874 1060 1157 1185 1641 1653 1656 1657 1676  
 1703 1750

### 1.5. Nonstationary processes

11 23 71 152 323 330 331 334 335 340 527 528 529  
 851 871 1114 1360 1439 1445 1477 1504 1682 1681  
 1711 1729 1740 1732 1759

### 1.6. Point processes

152 154 161 871 996 1298 1477 1504 1689

### 1.7. Statistical hypothesis testing

36 61 63 79 150 167 166 270 280 294 303 310 312  
 321 333 476 503 551 552 548 594 596 597 621 636  
 643 649 688 890 899 923 987 988 1170 1271 1437  
 1445 1513 1534 1535 1541 1598 1601 1604 1605  
 1609 1611 1617 1620 1624 1756 1754 1758

## 2. Modeling

300 708 780 791 1322 1489 1490 1491

### 2.1. Linear parametric (AR, MA, ARMA)

4 5 15 17 16 18 19 29 39 31 32 33 35 38 105 143  
 168 173 179 180 197 203 215 234 230 243 244 245  
 247 248 246 250 252 254 256 255 257 263 265 277  
 345 346 349 373 376 456 453 458 482 483 484 496  
 505 513 514 517 520 521 522 533 534 535 536 537  
 538 543 544 545 546 541 552 558 560 556 561 606  
 668 675 700 722 723 732 823 1251 854 856 862 863  
 865 867 868 876 888 915 948 959 971 995 1010 1011  
 1013 1018 1020 1022 1025 1026 1027 1028 1039  
 1046 1050 1051 1054 1055 1056 1066 1069 1070  
 1083 1084 1100 1125 1161 1167 1205 1208 1215  
 1218 1219 1220 1255 1259 1281 1283 1284 1285  
 1289 1294 1321 1339 1349 1408 1410 1413 1411  
 1412 1432 1433 1434 1442 1444 1445 1455 1462  
 1463 1464 1468 1470 1475 1485 1494 1497 1498  
 1510 1518 1525 1528 1555 1556 1557 1558 1559  
 1560 1561 1562 1564 1565 1566 1567 1568 1570

1571 1572 1573 1574 1579 1580 1581 1582 1591  
 1595 1598 1599 1606 1607 1554 1611 1619 1618  
 1616 1617 1623 1635 1645 1646 1647 1648 1649  
 1653 1654 1669 1676 1686 1709 1718 1716 1717  
 1721 1722 1727 1729 1730 1753 1751

## 2.2. Multichannel

34 169 171 172 180 184 192 226 287 289 291 292  
 297 298 532 539 663 672 674 673 678 680 681 704  
 337 906 907 917 921 976 1077 1128 1195 1203 1340  
 1359 1365 1408 1442 1459 1461 1503 1515 1516  
 1517 1519 1520 1521 1522 1524 1525 1528 1578  
 1605 1610 1615 1622 1650 1662 1699 1700 1707  
 1745 1746

## 2.3. Multidimensional

52 55 178 207 217 265 279 356 357 359 426 431  
 433 434 429 430 514 595 598 599 600 724 725 734  
 834 1200 1204 1265 1314 1317 1416 1442 1458 1460  
 1495 1497 1496 1531 1592 1594 1600 1602 1608  
 1637 1652 1701 1715 1732

## 2.4. Nonlinear

7 40 47 48 62 78 87 100 114 133 135 136 137 138  
 140 141 159 231 271 274 307 308 309 352 377 386  
 387 441 442 488 489 490 564 336 644 645 746 744  
 745 777 778 801 802 859 873 930 993 1031 1030  
 1085 1086 1182 1181 1183 1184 1211 1256 1344  
 1397 1415 1416 1435 1439 1636 1675 1714 1755

## 2.5. Polynomial

71 72 73 124 128 135 431 430 446 479 557 940 993  
 1086 1104 1106 1107 1108 1109 1110 1105 1158  
 1169 1230 1231 1360 1362 1367 1453 1454 1456  
 1498 1730 1735 1731 1744

## 2.6. Time-varying

123 126 323 324 326 317 463 509 527 528 561 1024  
 1192 1530 1538 1543 1596 1679 1729

## 3. Signals, systems and communications

### 3.1. Chaos, fractals and physical systems

2 10 11 62 411 410 417 419 449 450 492 508 573 581  
 890 896 898 959 960 969 970 1036 1130 1131 1132  
 1133 1295 1333 1334 1401 1644 1652 1655 1664

### 3.2. Channel estimation and equalization

25 91 92 93 94 95 96 97 98 102 103 104 105 109  
 107 143 171 174 179 225 228 236 237 257 258  
 309 361 364 365 372 373 407 436 471 494 536 537  
 553 561 567 569 576 583 608 609 611 612 613 615  
 616 617 618 619 673 700 701 702 732 804 813 819  
 823 851 853 863 862 864 894 901 915 918 917 943  
 975 990 1033 1049 1050 1051 1062 1118 1126 1127  
 1128 1148 1149 1162 1165 1167 1186 1187 1210  
 1227 1246 1247 1257 1258 1286 1311 1312 1313  
 1314 1346 1348 1349 1350 1396 1431 1480 1514  
 1523 1529 1530 1538 1539 1540 1544 1545 1547  
 1576 1577 1586 1587 1588 1589 1590 1596 1597  
 1599 1606 1607 1612 1616 1623 1630 1648 1657  
 1658 1667 1668 1669 1676 1713 1720 1723 1724  
 1725 1722 1727 1726 1753

### 3.3. Cyclostationarity

23 319 323 324 325 326 327 330 331 332 334 335  
 317 500 501 527 528 529 540 559 560 556 603 621  
 690 727 1024 1182 1270 1359 1361 1360 1362 1366  
 1367 1409 1530 1540 1599 1667 1680 1681 1729  
 1730 1735 1738 1739 1752

### 3.4. Coherence and coupling

46 85 106 153 156 198 214 222 266 362 415 418  
 420 439 438 555 577 586 587 591 590 592 629 650  
 729 770 775 808 810 859 1035 1041 1091 1096 1097  
 1099 1176 1179 1188 1196 1197 1200 1203 1236  
 1263 1292 1337 1376 1377 1378 1379 1380 1381  
 1397 1510 1740 1734 1738 1739 1741

### 3.5. Controls and state space

14 351 516 524 542 930 1344 1345 1382 1383 1384  
 1435 1469 1472 1555 1558 1636

**3.6. Delay and Doppler estimation**

174 259 262 263 295 323 329 396 398 402 425 436  
 580 601 648 687 779 785 850 875 999 1000 1057  
 1058 1075 1076 1141 1146 1147 1155 1186 1300  
 1301 1304 1305 1307 1308 1315 1327 1353 1361  
 1391 1392 1409 1569 1583 1585 1603 1621 1696  
 1697 1715 1740 1734

**3.7. Harmonic analysis and frequency estimation**

52 55 56 49 57 209 224 260 261 279 299 360 362 393  
 394 408 409 445 497 499 509 555 559 601 662 692  
 696 815 855 870 872 893 963 985 1082 1096 1097  
 1099 1168 1188 1221 1260 1304 1319 1323 1341  
 1354 1358 1363 1382 1385 1384 1388 1389 1435  
 1436 1442 1465 1473 1479 1484 1511 1679 1681  
 1714 1730 1740 1735 1741 1742 1731 1744

**3.8. Modulation and synchronization**

89 90 299 460 567 604 608 687 716 966 1041 1068  
 1124 1158 1223 1269 1597 1642 1714 1730 1740

**3.9. Multiplicative noise**

130 327 330 397 402 554 555 558 560 559 556 1085  
 1362 1367 1443 1448 1451 1453 1450 1454 1457  
 1729 1730 1740 1733 1734 1736 1738 1741

**3.10. Noise cancellation**

110 318 322 384 443 525 530 526 999 1038 1209 1276  
 1282 1341 1342 1343 1374 1387 1390 1483 1499

**3.11. Reconstruction of deterministic signals**

26 37 82 170 172 173 200 201 202 240 251 253 332  
 354 356 357 358 380 405 477 515 517 518 519 523  
 565 566 602 654 653 652 706 724 725 726 734 781  
 788 790 822 823 828 833 834 837 838 852 880 881  
 910 914 931 932 936 955 956 1037 1071 1081 1083  
 1084 1120 1122 1123 1127 1204 1215 1220 1239  
 1242 1265 1274 1276 1290 1335 1347 1393 1406  
 1407 1440 1441 1458 1484 1488 1492 1528 1531  
 1536 1584 1672 1683 1701

**3.12. Sampling issues**

30 213 579 642 835 1251 836 858 1040 1137 1138  
 1139 1145 1368 1369 1370 1371 1372 1449 1552

**3.13. Source localization and separation**

181 182 183 184 185 187 189 190 191 192 193 194  
 195 204 218 235 238 239 241 260 261 186 284 285  
 286 287 288 290 292 293 296 297 298 304 367 368  
 369 370 371 383 385 435 437 469 470 493 495 498  
 532 539 540 570 571 572 582 674 673 695 692 693  
 694 696 718 721 815 816 817 818 337 826 848 849  
 906 907 920 919 950 957 974 976 985 986 997 1096  
 1128 1164 1166 1188 1261 1262 1264 1277 1319  
 1326 1323 1324 1325 1340 1353 1355 1357 1358  
 1363 1364 1365 1366 1354 1383 1385 1384 1442  
 1459 1461 1465 1473 1481 1487 1503 1519 1520  
 1522 1524 1622 1662 1671 1685 1699 1700 1702  
 1704 1705 1707 1706 1715 1746

**3.14. System identification (I/O linear and nonlinear)**

13 14 32 47 48 52 53 51 67 74 87 91 100 99 103 114  
 115 116 117 118 119 120 135 138 151 159 170 176  
 266 267 269 271 272 273 274 347 348 350 351 352  
 374 386 423 424 478 489 490 526 542 564 336 578  
 666 667 669 671 676 677 679 684 698 747 749 753  
 774 758 759 760 792 795 796 797 798 800 801 802  
 803 811 805 827 839 859 892 912 913 926 929 930  
 937 993 1001 1002 1003 1004 1005 1006 1024 1072  
 1080 1085 1178 1212 1222 1328 1329 1330 1331  
 1398 1435 1450 1485 1501 1510 1512 1541 1545  
 1546 1547 1548 1549 1550 1551 1552 1575 1593  
 1616 1614 1625 1626 1628 1675 1695 1755

**3.15. Time-frequency representations**

43 44 71 122 123 124 126 128 127 129 130 131 132  
 388 444 461 462 463 464 465 466 467 468 472 473  
 474 507 529 832 1112 1224 1230 1231 1414 1446  
 1447 1538 1712

**3.16. Transient analysis**

43 41 86 264 461 462 603 637 662 682 683 687 685  
 686 464 467 944 1040 1087 1089 1088 1135 1136

1140 1141 1142 1144 1145 1143 1146 1147 1156  
1193 1224 1260 1293 1442 1659 1735

#### **4. Algorithms**

##### *4.1. Adaptive and recursive*

5 7 17 31 33 42 67 177 178 197 259 262 345 360 365  
377 456 455 481 526 614 665 746 744 745 776 748  
751 752 873 875 921 973 991 1004 1037 1113 1114  
1178 1216 1222 1242 1257 1288 1348 1373 1428  
1430 1442 1455 1456 1462 1463 1475 1480 1502  
1533 1539 1549 1564 1576 1577 1586 1621 1630  
1648 1668 1710 1718

##### *4.2. Architectures and implementation*

6 8 20 421 451 563 635 728 730 736 788 789 790  
846 845 904 905 903 951 1113 1189 1278 1279 1424  
1425 1426 1427 1428 1429 1430 1502

##### *4.3. Estimation: cumulants and polyspectra*

42 46 58 60 88 108 205 206 212 223 312 439 438  
491 501 531 560 568 579 610 640 664 709 714 783  
793 812 833 1252 842 846 858 860 861 869 902 953  
991 1008 1009 1044 1052 1101 1103 1112 1114 1172  
1195 1205 1206 1207 1208 1228 1250 1294 1302  
1320 1376 1380 1381 1432 1434 1435 1436 1469  
1478 1505 1506 1507 1508 1513 1553 1629 1631  
1682 1686 1719 1759

##### *4.4. Neural networks*

25 68 113 304 339 340 341 843 853 951 952 1171  
1663

#### **5. Applications – real data**

1402 1632

##### *5.1. Astronomy*

9 45 59 64 65 306 652 653 735 824 881 886 891 955  
954 998 1240 1243 1393 1672 1683

##### *5.2. Atmospheric sciences*

276 448 623 735 743 824 895 1159 1226 1508 1509

##### *5.3. Acoustics*

109 110 176 281 400 401 629 641 658 729 972 1032  
1193 1229 1296 1297 1305 1308 1310 1482 1550  
1551 1643 1665

##### *5.4. Biomedicine and physiology*

3 80 111 112 121 133 159 302 353 381 382 422 578  
628 655 658 659 664 666 698 729 739 738 779 794  
795 797 798 799 800 801 820 825 877 878 884 885  
902 905 903 911 912 958 994 999 1000 1067 1063  
1064 1065 1066 1091 1111 1225 1290 1291 1292  
1303 1336 1375 1377 1378 1379 1380 1476 1493  
1633 1634 1643 1690 1689

##### *5.5. Economics*

568 643 644 645

##### *5.6. Geophysics and seismic*

28 144 153 221 222 342 520 569 574 575 576 510  
620 640 733 813 829 862 899 922 1092 1093 1115  
1116 1656 1657 1658 1676 1708

##### *5.7. Images and vision*

3 10 54 50 52 66 83 196 210 216 232 305 306 341  
353 390 427 428 562 565 566 593 594 595 596 597  
598 599 600 654 653 691 703 705 706 719 720 731  
806 809 820 821 822 828 831 834 880 881 889 908  
914 931 932 933 934 956 1021 1034 1038 1071 1078  
1209 1213 1214 1243 1268 1272 1274 1296 1315  
1316 1318 1317 1335 1347 1393 1400 1406 1407  
1440 1488 1493 1495 1497 1496 1528 1531 1532  
1536 1602 1608 1666 1672 1687 1737

##### *5.8. Mechanical, turbulence, and fluid dynamics*

75 76 77 119 120 175 199 268 269 275 278 283 315  
316 401 589 587 591 590 588 592 622 623 624 625  
632 633 634 661 703 717 743 770 771 750 761 763  
768 765 757 764 766 767 762 754 755 769 772 807

828 861 869 887 892 893 900 923 934 935 939 942  
 963 962 964 965 966 967 968 1012 1014 1016 1073  
 1074 1174 1175 1177 1179 1180 1233 1234 1235  
 1236 1232 1237 1263 1299 1306 1309 1310 1404  
 1405 1417 1418 1419 1420 1421 1422 1423 1638  
 1639 1688 1698 1743 1757

#### *5.9. Oceanography*

142 165 166 227 315 316 363 409 413 414 412 416  
 420 586 607 630 631 660 814 927 928 937 938 939  
 989 996 1014 1035 1241 1693 1694 1691 1692

#### *5.10. Optics and lasers*

6 64 65 66 69 70 82 83 106 180 305 306 380 404 405  
 477 565 566 602 605 651 652 697 703 735 781 828  
 881 900 955 954 956 998 1239 1240 1242 1307 1655  
 1666 1672 1683

#### *5.11. Plasma and crystallography*

577 657 707 772 773 883 1102 1176 1237

#### *5.12. Radar*

656 710 711 712 713 715 743 830 831 850 897 1153  
 1154 1155 1169 1173 1403 1483 1660 1661 1671

#### *5.13. Sensor arrays*

185 186 188 191 194 204 219 220 239 242 367 368  
 370 371 383 539 572 582 695 696 721 818 923 919  
 950 1264 1277 1324 1356 1385 1522 1685 1705

#### *5.14. Sonar*

122 282 315 316 344 380 392 395 397 399 398 401  
 403 419 472 475 604 646 641 685 830 977 1169 1229  
 1238 1282 1300 1305 1486 1736

#### *5.15. Speech*

24 146 147 233 249 366 378 486 487 506 557 813 924  
 925 978 979 980 981 982 991 992 1007 1029 1079  
 1216 1217 1287 1288 1338 1651 1674 1677 1730

#### *5.16. Vibrations*

101 419 420 893 1386

### **6. Books and conference proceedings**

125 148 149 157 338 1042 406 447 504 512 511 585  
 626 742 941 961 983 1048 1059 1090 1160 1190 1438  
 1245 1249 1254 1332 1356 1527 1670 1675 1710  
 1748

### **7. Tutorials**

158 160 162 179 186 511 638 639 664 782 857 881  
 882 945 946 947 948 949 1045 1047 1053 1061 1191  
 1248 1356 1449