Network Intrusion Detection Using an Improved Competitive Learning Neural Network

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Abstract

This paper presents a novel approach for detecting network intrusions based on a competitive learning neural network. In the paper, the performance of this approach is compared to that of the self-organizing map (SOM), which is a popular unsupervised training algorithm used in intrusion detection. While obtaining a similarly accurate detection rate as the SOM does, the proposed approach uses only one forth of the computation time of the SOM. Furthermore, the clustering result of this method is independent of the number of the initial neurons. This approach also exhibits the ability to detect the known and unknown network attacks. The experimental results obtained by applying this approach to the KDD-99 data set demonstrate that the proposed approach performs exceptionally in terms of both accuracy and computation time.

Keywords: Network Security, Network Intrusion Detection, Data Mining, Artificial Neural Network, Competitive Learning.

1. Introduction

Intrusion detection is a critical process in network security. Traditional methods of network intrusion detection are based on the saved patterns of known attacks. They detect intrusion by comparing the network connection features to the attack patterns that are provided by human experts. The main drawback of the traditional methods is that they cannot detect unknown intrusions. Even if a new pattern of the attacks were discovered, this new pattern would have to be manually updated into the system. On the other hand, as the speed and complexity of networks develop rapidly, especially when these networks are open to the public Web, the number and types of the intrusions increase dramatically. Human analysis becomes insufficient. This leads to the interest in using data mining techniques in network intrusion detection [3, 11].

Data mining-based intrusion detection techniques can be categorized into misuse detection and anomaly detection [11]. The misuse detection techniques build the patterns of the attacks by learning from the labelled data. The main drawback of the misuse detection techniques is that they cannot detect new attacks that have never occurred in the training data. On the other hand, the anomaly detection techniques establish normal usage patterns. They can detect the unseen intrusions by investigating their deviation from the normal patterns. The artificial neural networks provide a number of advantages in the detection of network intrusions[2]. The application of the neural network techniques has been considered for both the misuse detection model and the anomaly detection model [10, 15].

As an unsupervised neural network, the SOM has been applied in anomaly detection. It implicitly prepares itself to detect any aberrant network activity by learning to characterize the normal behaviors [15]. However, the SOM has a significant shortage: the number of neurons affects the network's performance. Increasing the number of output nodes will increase the resolution of the map, but the computation time will dramatically increase. In this paper, we propose an efficient clustering algorithm based on the competitive neural networks. This approach obtains accuracy similar to that of the self-organizing map while costing much less computation time.

The rest of the paper is organized as follows. In the next section, we briefly review the background of the application of artificial neural networks to network intrusion detection. Section 4 discusses the self-organizing maps and the proposed approach. In Session 5, experiments reveal the speed and accuracy of the proposed approach compared to the SOM. Finally, Section 6 gives a summary and concludes

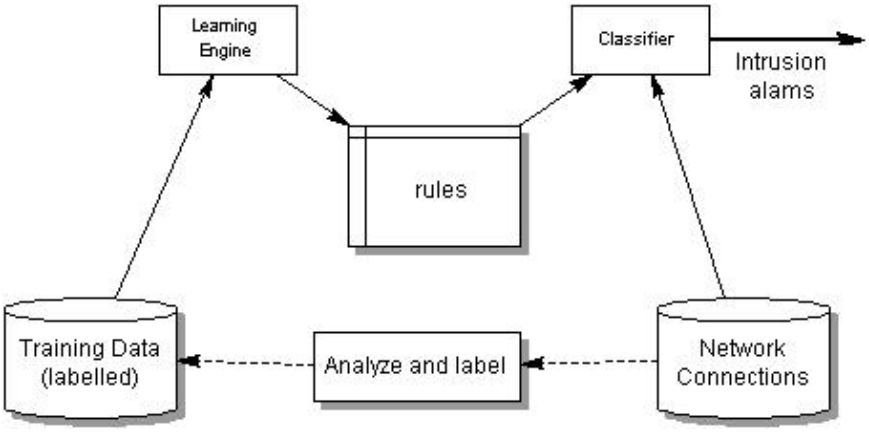


Figure 1. Network intrusion detection using labelled data

the current study.

2. Related Works

An increasing amount of research has been conducted on the application of neural networks for detecting network intrusions. The artificial neural networks have the potential to resolve a number of problems encountered by the other current approaches in intrusion detection. The neural networks gain experience by training the system to correctly identify the preselected examples of the problem.

A Multilayer Perceptron (MLP) was used in [5] for anomaly detection. The proposed model is a single hidden layer neural network. The performance of this model tested on the DARPA 1998 data set was a correct detection rate of 77% with 2.2% false alarms.

The MLP was also applied in [12]. Generic keywords were selected to detect the attack preparations and actions after the break-in. The back-propagation algorithm was used in the learning phase to adapt the weights of the neural network. This approach obtained a detection rate of 80% when it was tested on the DARPA 1998 data set.

A hybrid model of the SOM and the MLP was proposed in [2]. In that work, the self-organizing map was combined with the feed-forward neural network. This model was designed to detect the dispersing and possibly collaborative attacks.

The SOM was also applied to perform the clustering of network traffic and to detect attacks in [6, 14]. In [6], SOM was used to map the network connections onto 2-dimensional surfaces, which were displayed to the network administrator. The intrusions were easily detected in this view. However, the approach needs a visual interpretation by the network administrator. The SOM is trained by using the normal network traffic in [14]. The trained SOM reflects the distribution of the normal network connections. If the minimum distance between a network connection and the neurons of the trained SOM is more than a pre-set threshold, this connection is classified as an intrusion.

In addition, artificial neural networks have also been proposed in the detection of the computer viruses. A self-organizing map was selected in [4] for intrusion detection. In that work, the self-organizing map was designed to learn the characteristics of normal activities. The variations from normal activities provided an indication of a virus.

3. The Detection Process

The data source can be labelled or unlabelled based on the learning algorithm used in the data mining-based intrusion detections. Unsupervised algorithms can be applied to unlabelled data while supervised algorithms can only use labelled data.

In supervised learning, the training data must be labelled before they are presented to the training algorithm. Figure 1 shows the intrusion detection process using supervised learning algorithm. First, the original data must be analyzed and labelled as normal connections or attacks by human experts. After that, the learning algorithms generalize the rules from the training data. Finally, The classifier uses the generated rules to classify the new network connections. A difficulty of the supervised learning is labelling the data. If a large data set is used for training, the labelling duty could be very hard. If choosing a small portion as the training data, the selection of the training examples is crucial to the learning result.

Unlike supervised learning algorithms, which can only use labelled data, unsupervised learning algorithms have the ability to learn from unlabelled data. The algorithm we propose in this paper is a clustering method, a typical unsupervised learning algorithm. This approach can be applied on not only labelled data but also unlabelled data. The detec-

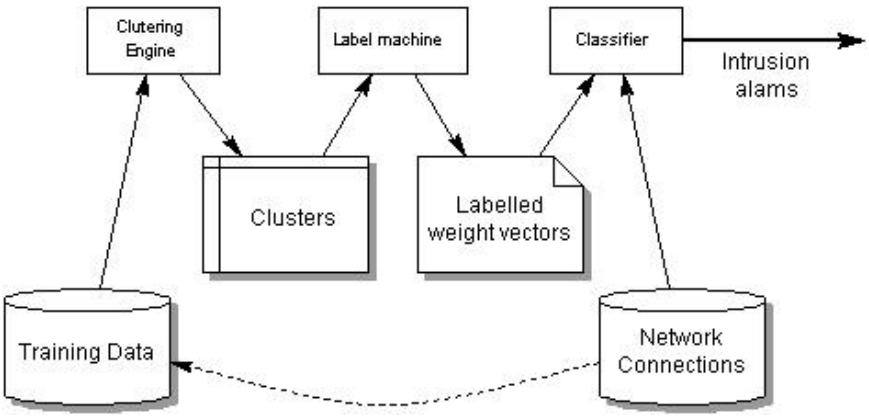
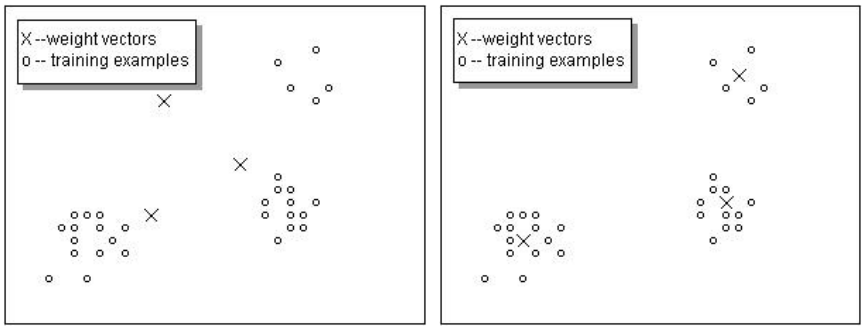


Figure 2. Network intrusion detection using unlabelled data



(a) initial weight vectors (b) clustering result

Figure 3. The principle of SCLN

tion process using the unlabelled data is illustrated in Figure 2. First, the training data are clustered by the clustering algorithm. Second, the clustered weight vectors can be labelled by a labelling process. Various methods can be applied to this process. One approach to label a cluster center is to select a sample group of the data from this cluster randomly and label this cluster with the major type of the sample. Finally, the labelled weight vectors can be used to classify the network connections.

The main difference between the two processes discussed above is the time and the number of examples for labelling. Unlike the first process, in which the data must be labelled before training, the second process has the ability to organize the unlabelled data and to provide the cluster centers for labelling. Therefore, the second process reduces the risk of selecting improper data as the training set.

4. Methodology

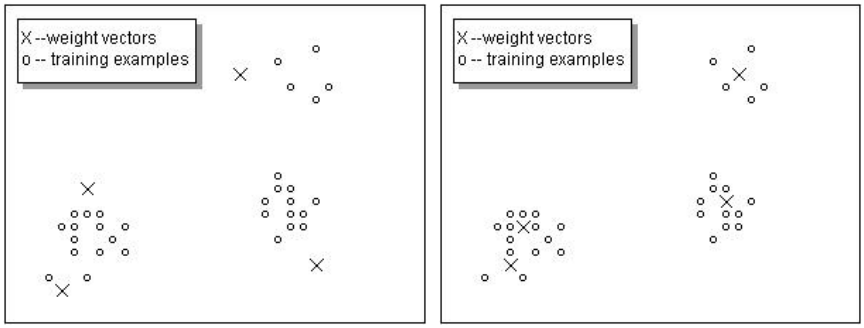
This section discusses our improved competitive neural network approach for detecting network intrusions. We derive the new approach from the Standard Competitive Learning Network (SCLN). After that, a brief review of the SOM is given since the new approach will be compared with the SOM.

4.1. The Improved Competitive Learning Network

The improved competitive learning network (ICLN) is based on the SCLN. The simplest SCLN is a single-layer neural network in which each output neuron is fully connected to the input nodes. In the SCLN, the output neurons of a neural network compete to become active. When a training example is presented to the network, the output neurons compete among themselves. If a neuron won the competition, its weight vector would be updated. According to the standard competitive learning rule, the weight update is calculated by the following update rule:

$$w_j(n+1) = w_j(n) + \eta(n)(x - w_j(n)) \qquad (1)$$

where η is the learning rate, and w_j is the weight vector of the winning neuron j. The essence of competitive learning



(a) initial weight vectors (b) clustering result

Figure 4. The shortage of SCLN

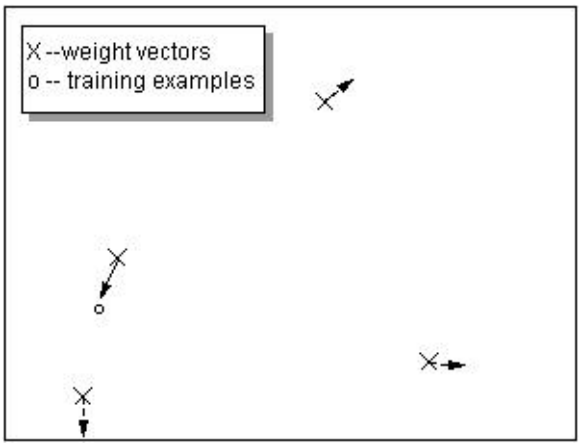


Figure 6. The effect of the ICLN update rules

is illustrated in Figure 3. The network initialized a number of neurons randomly. The initial neurons learn by shifting their synaptic weights towards the input nodes. After training, each output neuron should represent a cluster of the input data set by moving its own synaptic weight vector to the center of that cluster. This process shows that the SCLN has the ability of performing clustering. However, the performance of the SCLN is heavily dependent on the number of the output neurons and the initialization of their weight vectors. Once the number of the output neurons is set, the number of clusters is also determined regardless of the distribution of the data. On the other hand, different initial weight vectors may lead to different final clusters because the update function in Equation 1 only moves the weight vector of the winning neuron toward its local nearby examples. Figure 4 shows a scenario that reveals the limitations of the SCLN. In this scenario, two neurons are initialized in one cluster. The SCLN will result in four clusters although only three clusters are expected. A critical shortage of the SCLN is that it may split one cluster into many small clusters.

The improved competitive learning network (ICLN) can

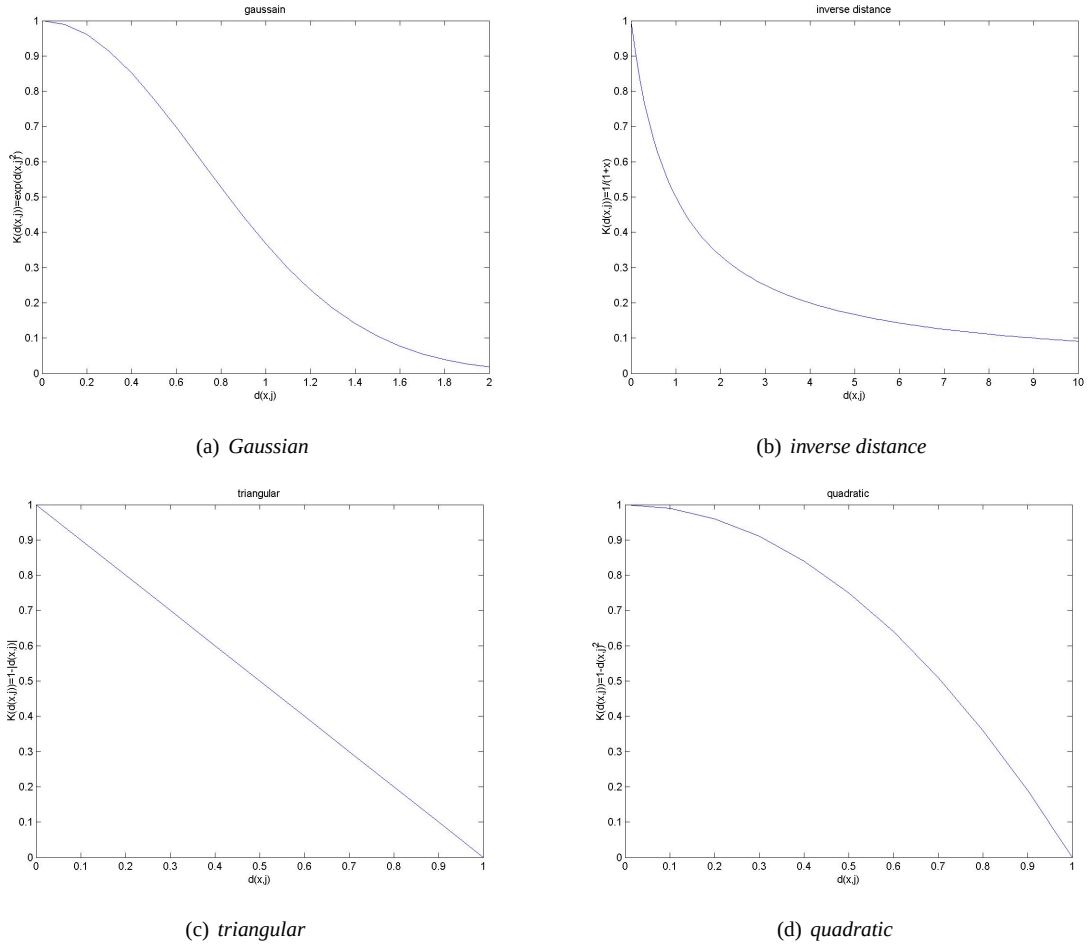
Input: $X = \{x_1, x_2, \ldots, x_n\}$: the input dataset
Output: $W = \{w_1, w_2, \ldots, w_k\}$: the weight vectors
BEGIN
1. Randomly initialize the weight vectors $w_j, j = 1, 2, \ldots, m$
2. Initialize the learning rates η_1 and η_2 for the winning neuron and the losing neurons, respectively. $0 < \eta_2 < \eta 1 < 1$.
3. Initialize the minimum weight update value γ
4. Kernel function: $K(d(x_i, w_j)) = e^{-d^2(x_i, w_j)}$
repeat
  for $x_i \in X$ **do**
    for $w_j \in W$ **do**
      compute the distances: $d(x_i, w_j) = \| x_i - w_j \|$
    end for
    $w_{win} = \min d(x_i, w_j)$
    /*Update the weight vector of the winning neuron:*/
    $w_{win} = w_{win} + \eta_1(x_i - w_{win})$
    /*Update the weight vectors of the other neurons:*/
    $w_j = w_j - \eta_2 K(d(x_i, w_j))(x_i - w_j)$, $\forall w_j \in W$ and $j \neq win$
  end for
until $|\triangle w_j| < \gamma$, $\forall w_j \in W$
Remove all weight vectors that have no associated input.
END

Figure 7. Algorithm: improved competitive learning network (ICLN)

overcome the shortages of the SCLN. Furthermore, the ICLN obtains a better performance regarding the computation time. In this approach, the winning neuron updates its weight vector by using the same update rule in Equation 1. At the same time, the other neurons also update their weight vectors based on the following equation:

$$w_j(n+1) = w_j(n) - \eta_2(n)K(d(x,j))(x - w_j(n)) \quad (2)$$

where η_2 is the learning rate, and $K(d(x,j))$ is a kernel function in which $d(x,j)$ is the distance between the neuron j and the input x. There are various choices of the kernel function [1], such as the inverse distance, the triangu-



(a) *Gaussian* (b) *inverse distance*

(c) *triangular* (d) *quadratic*

Figure 5. The curves of some kernel functions

lar kernel, the quadratic kernel, and the Gausian kernel. The *Gaussian Kernel* is a commonly chosen kernel function:

$$K(d(x,j)) = e^{-d^2(x,j)}$$

A kernel function obtains the maximum value at zero distance, and the value decays as the distance increases. The kernel functions reflect the influence of the distance to the update rule. Figure 5 shows the curves of some commonly used kernel functions. As a result, the updated value would be smaller if the distance between the neuron and the input were greater. The new update rule applied to the losing neurons moves the weight vectors of these neurons away from the input pattern. The effect of the above update rules is shown in Figure 6. This update process not only avoids the limitation of the SCLN but also makes the clustering much faster. The algorithm of the ICLN is outlined in Figure 7.

4.2. The Self-Organizing Maps

The SOM is one of the most popular neural network models. It is a fully connected, single-layer neural network [8]. It maps a multi-dimensional data set onto a one- or two-dimensional space. In the SOMs, data are clustered by using soft competition, which is the term opposite to hard competition [13]. In hard competition, there is only one winner: in each competition, only one node is active, and all of the others are inactive. Soft competition allows not only the winner but also its neighbors to be active. That is, after competing for the presented inputs, the winner and its neighbor nodes have their weights updated by the following rule:

$$w_j(n+1) = w_j(n) + \eta(n) h_{j,i(x)}(n)(x - w_j(n)) \quad (3)$$

where $w_j(n)$ denotes the weight vectors of the winning neuron and its neighbors at time n, $\eta(n)$ denotes the learning rate at time n, and $h_{j,i(x)}(n)$ is the neighborhood function centered at the winning node. The Gaussian function is

No. of initial neurons	No. of clusters	Elapsed time	Accuracy	Precision	Recall
9	8	1057s	97.80%	98.31%	98.96%
15	10	2162s	97.89%	98.41%	98.97%
18	12	2507s	97.82%	98.33%	98.97%
20	15	3308s	97.89%	98.41%	98.97%

Table 1. The performance of SOM

commonly used as the neighborhood function:

$$h_{j,i(x)}(n) = e^{-d_{j,i}^2/2\delta^2(n)}$$

where i is the center, $\delta^2(n)$ denotes the variance at time n, and $d_{j,i}$ represents the distance between the winning neuron i and its neighbor node j. This update process moves the winning neuron and its neighbors to the input vector. The effect of applying the neighborhood function is that the closer neighbors obtain the greater updates. After training, the output layer is expected to reflect the topology or density of the input data set.

It has excellent capabilities for visualizing high-dimensional data onto a 1-or 2-dimensional space. One drawback of the SOMs is that the number of neurons affects the performance of the clustering. To obtain a better clustering result, various numbers of nodes have to be evaluated. Increasing the number of nodes could increase the resolution of the map. However, it could increase the computation time dramatically [7].

	Cluster				
	1	2	3	4	5
normal	69413	26	5776	869	1422
buffer_overflow				2	
loadmodule				1	
perl				1	
neptune					
smurf					
ipsweep	1		11	20	
back	59				

	Cluster				
	6	7	8	9	10
normal	54	70	1	77	180
buffer_overflow					
loadmodule					
perl					
neptune				30	
smurf					22093
ipsweep	33			859	
back				2	

Table 2. The result of the 3×5 SOM

5. Experiments and Results

In this section, we experiment with the SOM and the ICLN by using the KDD-99 data [9] and compare the results of these two methods.

The KDD-99 dataset was used for the Third International Knowledge Discovery and Data Mining Tools Competition. This dataset was acquired from the 1998 DARPA intrusion detection evaluation program. There were 4,898,431 connection records, of which 3,925,650 were attacks. From this data set, 501,000 records were chosen as our experimental data. The selected connections were further split into the training set and the test set, containing 101,000 and 400,000 connections respectively.

There were 21 types of intrusions in the test set, but only 7 of them were chosen in the training set. Therefore, the selected data also challenged the ability to detect the unknown intrusions. The same data sets were used in the experiments to evaluate the performance of the SOMs and the ICLN in the same environment.

5.1. Data Preparation

In the KDD-99 data set, each connection is labelled as "normal" or a particular type of the attacks. A connection is represented by 41 features, which include the basic features of the individual TCP connections, the content features within a connection suggested by the domain knowledge, and the traffic features computed by using a two-second time window [9]. The features in columns 2, 3, and 4 of the KDD-99 data set are the protocol type, the service type, and the flag, respectively. The value of the protocol type may be tcp, udp, or icmp; the service type could be one of the 70 different network services such as http and smtp; and the flag has 11 possible values such as SF or S2. These qualitative features are mapped into quantitative values in the preparation process for calculating the similarities of the connections.

No. of initial neurons	No. of clusters	Elapsed time	Accuracy	Precision	Recall
9	6	454s	97.89%	98.42%	98.97%
15	6	608s	97.89%	98.42%	98.97%
18	6	682s	97.89%	98.42%	98.97%
20	6	723s	97.89%	98.42%	98.97%

Table 3. The performance of ICLN

5.2. Experiment 1: the SOMs

In this experiment, we investigate both the accuracy and elapsed time of the SOMs. In the training phase, the SOMs were used to cluster the training data. After training, each cluster was labelled according to the majority type of data in this cluster. For instance, if more than 50% of the connections in a cluster were intrusions, the cluster and its centroid weight vector would be labelled as intrusion. In the test phase, each test connection was assigned to its closest neuron, which was the center of a cluster, and this connection was identified by the label of that cluster. Table 1 shows the effect of using various number of initial neurons.

The detail of the clustering result of the 3×5 SOM was further investigated. After training, 5 of the 15 initial weight vectors were removed because they did not have any associated data to identify the connection types. The remaining 10 weight vectors were labelled as the majority types of the data in their group. The labelled weight vectors were used to detect the connections in the test data set. The detail of clustering result generated by a 3×5 SOM on the training data is shown in Table 2.

5.3. Experiment 2: the ICLN

The performance of the ICLN was also investigated by using various number of the initial neurons. The results of various trials are summarized in Table 3, in terms of the final number of the clusters discovered by the ICLN. In all of the trials, 6 clusters were discovered after training regardless the number of initial neurons. Moreover, the performances of the ICLN in these trials are similar. This result implies that the clustering result is unaffected by the number of the initial neurons in the ICLN algorithm.

The detailed clustering result of the training data generated by a 15 neuron ICLN is shown in Table 4. After training, 6 clusters were detected. The weight vectors of these clusters were used to identify the connections in the test data set.

5.4. Discussion

While obtaining similar accuracy, the ICLN requires less computation time. Figure 8 shows the computation time of the SOM and ICLN algorithms in the training phase. The elapsed time of the SOM increases rapidly when the number of initial neurons increases. The results demonstrate that the ICLN uses much less time than the SOM.

	Cluster					
	1	2	3	4	5	6
normal	1422	70	75260	180	878	78
buffer_ overflow					2	
loadmodule					1	
perl					1	
neptune						30
smurf				22093		
ipsweep			12		53	859
back			59			2

Table 4. The result of the ICLN

Interestingly, the ICLN discovered clusters similar to those discovered by the SOMs. The clusters 1, 2, and 4 in Table 4 are exactly the same as the clusters 5, 7, and 10

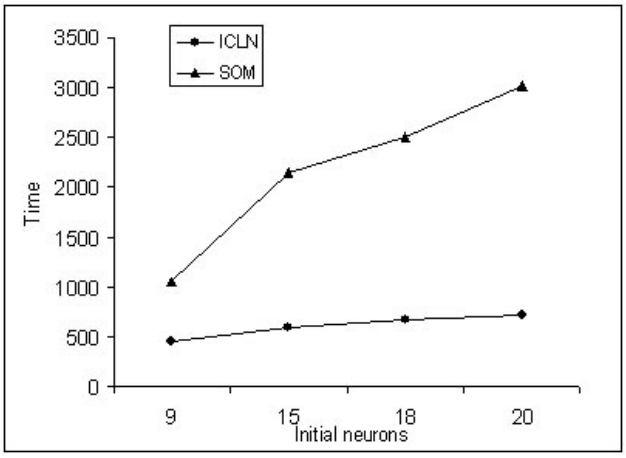


Figure 8. The elapsed time of the SOM and ICLN

in Table 2. The cluster 8 in the SOM contains only one instance. This instance moves to the nearest neighbor, cluster 9, when the weight vector of cluster 8 is removed. The reconstructed cluster becomes the same as the cluster 6 in the ICLN.

The above experiments confirmed that the performance of the ICLN is unaffected by the number of the initial output neurons. The results also suggest that this approach has the ability to detect unseen network attacks.

6. Conclusion

A novel approach for detecting network intrusions is proposed in this paper. The proposed approach obtains a significant improvement in speed. The experiments also show that the proposed approach has the ability to detect the unknown intrusions by clustering the connections based on their similarities. Specifically, we compared the performance of this approach with the SOM. The proposed approach obtains a similar accuracy as the SOM does whereas it only uses one forth of the computation time of the SOM. In addition, the clustering result of the proposed approach is independent of the number of initial neurons. The experimental results on the KDD-99 data set demonstrates that the developed algorithm is successful in terms of not only accuracy but also efficiency in network intrusion detection.

7. Acknowledgments

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