# A NOTE ON INTEGRABILITY OF ALMOST PRODUCT RIEMANNIAN STRUCTURES \*

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Riemann

Riemann

Yano-Ako

### ABSTRACT

Using the Yano-Ako operator, we give a new sufficient condition of integrability for almost product Riemannian structures on the differentiable manifold and apply this condition to the case of almost product Riemannian structures defined on the tensor bundle.

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#### **1. INTRODUCTION**

Let  $M_n$  be an almost product manifold with almost product structure F. In order that the almost product structure F be integrable, it is necessary and sufficient that it is possible to introduce a torsion-free affine connection  $\nabla$  with respect to which the structure tensor F is covariantly constant (see [3], [8]), *i.e.*  $\nabla F = 0$ . Also, we know that the integrability of F is equivalent to the vanishing of the Nijenhuis tensor  $N_F$  [9, p. 240]. In this paper we consider another possible sufficient condition of the integrability of almost product structures on Riemannian manifolds.

If  $M_n$  admits a Riemannian metric g such that

$$g(FX,Y) = g(X,FY)$$
<sup>(1)</sup>

for  $X, Y \in \mathfrak{I}_0^1(M_n)$ , then  $M_n$  is called an almost product Riemannian manifold [5], [11]. Sometimes, such metrics are said to be pure with respect to F [6], [7].

We define the operator  $\Phi_F : \mathfrak{T}_2^0(M_n) \to \mathfrak{T}_3^0(M_n)$  (see [10]) associated with F and applied to the pure metric g:

$$(\Phi_F g)(X, Y_1, Y_2) = (FX)(g(Y_1, Y_2)) - X(g(FY_1, Y_2)) + g((L_{Y_1}F)X, Y_2) + g(Y_1, (L_{Y_2}F)X),$$
(2)

where  $L_{Y_i}$ , i = 1, 2 denotes the Lie differentiation with respect to  $Y_i$ . By setting  $X = \partial_k$ ,  $Y_1 = \partial_i$ ,  $Y_2 = \partial_j$  in Equation (2), we see that the components  $(\Phi_F g)_{kij}$  of  $\Phi_F g$  with respect to a local coordinate system  $x^1, ..., x^n$  may be expressed as follows:

$$(\Phi_F g)_{kij} = F_k^m \partial_m g_{ij} - F_i^m \partial_k g_{mj} + g_{mj} (\partial_i F_k^m - \partial_k F_i^m) + g_{im} \partial_j F_k^m.$$

## 2. SUFFICIENT CONDITION OF THE INTEGRABILITY

Let there be given an almost product Riemannian manifold  $(M_n, F)$  with pure metric g. By virtue of (1) and  $\nabla g = 0$  we have

$$g(Z, (\nabla_{Y} F)X) = g((\nabla_{Y} F)Z, X),$$
(3)

Using (3) and  $[X, Y] = \nabla_X Y - \nabla_Y X$ , we have transform (2) as follows:

$$(\Phi_F g)(X, Z_1, Z_2) = -g((\nabla_X F)Z_1, Z_2) + g((\nabla_{Z_1} F)X, Z_2) + g(Z_1, (\nabla_{Z_2} F)X)$$
(4)

From this we have

$$(\Phi_F g)(Z_2, Z_1, X) = -g((\nabla_{Z_2} F)Z_1, X) + g((\nabla_{Z_1} F)Z_2, X) + g(Z_1, (\nabla_X F)Z_2)$$
(5)

If we add (4) and (5), we find

$$(\Phi_F g)(X, Z_1, Z_2) + (\Phi_F g)(Z_2, Z_1, X) = 2g(X, (\nabla_{Z_1} F)Z_2)$$
(6)

Putting  $\Phi_F g = 0$  in (6), we find  $\nabla F = 0$ 

On the other hand, we know that the integrability of the almost product structure F is equivalent to the existence of a torsion-free affine connection with respect to which the equation  $\nabla F = 0$  holds. Since the Levi–Civita connection  $\nabla$  of g is a torsion-free affine connection, we have

**Theorem 1.** Let  $(M_n, F)$  be an almost product Riemannian manifold with pure metric g. Then F is integrable if  $\Phi_F g = 0$ .

We note that, if  $\nabla F = 0$ , then the condition  $\Phi_F g = 0$  follows from (4) or (5). Thus we have

**Corollary.** For an almost product Riemannian manifold with pure metric g , the condition  $\Phi_F g = 0$  is equivalent to  $\nabla F = 0$ , where  $\nabla$  is the Levi-Civita connection of g.

An integrable almost product Riemannian manifold with structure tensor F is usually called a locally product Riemannian manifold. If the metric of a locally product Riemannian manifold  $M_n$  has the form

$$ds^{2} = g_{ab}(x^{c})dx^{a}dx^{b} + g_{\bar{a}\bar{b}}(x^{\bar{c}})dx^{\bar{a}}dx^{b}, \qquad a,b,c,... = 1,...,m, \quad \bar{a},\bar{b},\bar{c},... = m+1,...,m$$

that is  $g_{ab}$  are functions of  $x^c$  only,  $g_{a\overline{b}} = 0$  and  $g_{\overline{a}\overline{b}}$  are functions of  $x^{\overline{c}}$  only, then we call the manifold  $M_n$  a locally decomposable Riemannian manifold. On the other hand, we know that the locally product Riemannian manifold with structure tensor F is locally decomposable if and only if F is covariantly constant with respect to the Levi–Civita connection  $\nabla$  [11, p. 420].

Thus, by Theorem 1 and its corollary, we have

**Theorem 2.** Let  $(M_n, F)$  be an almost product Riemannian manifold with pure metric g. A necessary and sufficient condition for  $(M_n, F)$  to be a locally decomposable Riemannian manifold is that  $\Phi_F g = 0$ .

# **3.** DECOMPOSABILITY OF AN ALMOST PRODUCT RIEMANNIAN STRUCTURES ON TENSOR BUNDLE

Let  $T_q^p(M_n) = \bigcup_{p \in M_n} T_q^p(P)$  be a tensor bundle of type (p,q) over  $M_n$  with the natural projection  $\pi: T_q^p(M_n) \to M_n$ . If  $x^j$  are local coordinates on a neighborhood U of  $P \in M_n$ , then a tensor t at P, which is an element of  $T_q^p(M_n)$ , is expressible in the form  $(x^j, t_{j_1 \dots j_q}^{i_1 \dots i_p})$ , where  $t_{j_1 \dots j_q}^{i_1 \dots i_p}$  are components of t with respect to the natural base. We may consider  $(x^j, t_{j_1 \dots j_q}^{i_1 \dots i_p}) = (x^j, x^{\overline{j}}) = x^J$ ,  $j = 1, \dots, n$ ,  $\overline{j} = n + 1, \dots, n + n^{p+q}$ ,  $J = 1, \dots, n + n^{p+q}$  as local coordinates on a neighborhood  $\pi^{-1}(U)$ .

If  $\alpha \in \mathfrak{T}_p^q(M_n)$ , it is regarded, in a natural way, by contraction, as a function on  $T_q^p(M_n)$ , which we denote by  $\iota \alpha$ . If  $\alpha$  has local expression

$$\alpha = \alpha_{i_1 \dots i_n}^{j_1 \dots j_q} \partial_{j_1} \otimes \dots \otimes \partial_{j_n} \otimes dx^{i_1} \otimes \dots \otimes dx^{i_p}$$

on a coordinate neighborhood  $U(x^{j}) \subset M_{n}$ , then  $i\alpha = \alpha(t)$  has the local expression

$$\iota \alpha = \alpha_{i_1 \dots i_p}^{j_1 \dots j_q} t_{j_1 \dots j_q}^{i_1 \dots i_p}$$

with respect to the coordinates  $(x^{j}, x^{\bar{j}})$  on  $\pi^{-1}(U)$ .

Let  $A \in \mathfrak{T}_a^p(M_n)$ . Then there is a unique vector field  ${}^{V}A \in \mathfrak{T}_a^1(T_a^p(M_n))$  such that for  $\alpha \in \mathfrak{T}_a^q(M_n)$ 

$$^{V}A(\iota\alpha) = \alpha(A) \circ \pi = ^{V}(\alpha(A))$$

where  ${}^{v}(\alpha(A))$  is the vertical lift of the function  $\alpha(A) \in \mathfrak{T}_{0}^{0}(M_{n})$ . We call  ${}^{v}A$  the vertical lift of  $A \in \mathfrak{T}_{q}^{p}(M_{n})$  to  $T_{q}^{p}(M_{n})$  [1]. The vertical lift  ${}^{v}A$  has components of the form

$${}^{V}A = \left({}^{V}A^{j}, {}^{V}A^{\bar{j}}\right) = \left(0, A^{i_{1}...i_{p}}_{j_{1}...j_{q}}\right)$$

with respect to the coordinates  $(x^{j}, x^{\bar{j}})$  on  $T_{q}^{p}(M_{n})$ .

We define the horizontal lift  ${}^{H}X$  of X to  $T_{q}^{p}(M_{n})$  (see [4]) by  ${}^{H}X(\iota\alpha) = \iota(\nabla_{X}\alpha)$ , for all  $\alpha \in \mathfrak{T}_{p}^{q}(M_{n})$ . The horizontal lift  ${}^{H}X$  of  $X \in \mathfrak{T}_{0}^{1}(M_{n})$  to  $T_{q}^{p}(M_{n})$  has components

$${}^{H}X = \left(X^{j}, X^{s} \left(\sum_{\mu=1}^{q} \Gamma^{m}_{sj_{\mu}} t^{i_{1}...i_{p}}_{j_{1}...m..j_{q}} - \sum_{\lambda=1}^{p} \Gamma^{i_{\lambda}}_{sm} t^{i_{1}...m..i_{p}}_{j_{1}...j_{q}}\right)$$

with respect to the coordinates  $(x^{j}, x^{\overline{j}})$  on  $T_{q}^{p}(M_{n})$ , where  $\Gamma_{ij}^{k}$  are local components of  $\nabla$  on  $M_{n}$ .

For each  $P \in M_n$ , the extension of scalar product g (denoted also by g) is defined on the tensor space  $\pi^{-1}(P) = T_a^{p}(P)$  by

$$g(A,B) = g_{i_{1}t_{1}}...g_{i_{p}t_{p}}g^{j_{1}t_{1}}...g^{j_{q}t_{q}}A^{i_{1}...i_{p}}_{j_{1}...j_{q}}B^{t_{1}...t_{p}}_{t_{1}...t_{q}}$$

for all  $A, B \in T_q^p(P)$ . A Sasakian metric <sup>s</sup>g (or a diagonal lift of g) is defined on  $T_q^p(M_n)$  by the three equations

$${}^{s}g({}^{V}A, {}^{V}B) = {}^{V}(g(A, B)), A, B \in \mathfrak{I}_{q}^{p}(M_{n})$$
  
$${}^{s}g({}^{V}A, {}^{H}Y) = 0,$$
  
$${}^{s}g({}^{H}X, {}^{H}Y) = {}^{V}(g(X, Y)), X, Y \in \mathfrak{I}_{0}^{1}(M_{n})$$

These equations are easily seen to determine  ${}^{s}g$  on  $T_{q}^{p}(M_{n})$  with respect to which the horizontal and vertical distributions are complementary and orthogonal. On the other hand, let J be the almost product structure on  $T_{q}^{p}(M_{n})$  determining the vertical distribution consisting of distribution of the vertical vectors and the horizontal distribution determined by the Riemannian connection  $\nabla$ , *i.e.* 

$$J \stackrel{H}{X} = \stackrel{H}{X}, J \stackrel{V}{A} = -\stackrel{V}{A}$$

for any  $X \in \mathfrak{I}_0^1(M_n)$  and  $A \in \mathfrak{I}_q^p(M_n)$ . Then we easily obtain

$${}^{s}g(J {}^{V}A, {}^{V}B) = {}^{s}g({}^{V}A, J {}^{V}B),$$
  
$${}^{s}g(J {}^{V}A, {}^{H}Y) = {}^{s}g({}^{V}A, J {}^{H}Y),$$
  
$${}^{s}g(J {}^{H}X, {}^{V}B) = {}^{s}g({}^{H}X, J {}^{V}B),$$
  
$${}^{s}g(J {}^{H}X, {}^{H}Y) = {}^{s}g({}^{H}X, J {}^{H}Y)$$

for any  $X, Y \in \mathfrak{I}_0^1(M_n)$  and  $A, B \in \mathfrak{I}_q^p(M_n)$ . Thus  $(T_q^p(M_n), {}^sg, J)$  is an almost product Riemannian manifold.

The following equations are known [2]

$$\begin{bmatrix} {}^{v}A, {}^{v}B \end{bmatrix} = 0 \quad , \tag{7}$$

$$\begin{bmatrix} {}^{H}X , {}^{V}B \end{bmatrix} = {}^{V} (\nabla_{X} B) , \qquad (8)$$

$$\begin{bmatrix} {}^{H}X , {}^{H}Y \end{bmatrix} = \overline{D}_{R(X|Y)} + {}^{H}\begin{bmatrix} X , Y \end{bmatrix}$$
(9)

for all  $A, B \in \mathfrak{J}_q^p(M_n)$  and  $X, Y \in \mathfrak{T}_0^1(M_n)$ . Here  $\overline{D}_{R(X,Y)}$  means that a lift of derivation  $D_{R(X,Y)}$  defined by an endomorphism  $R(X, Y) \in \mathfrak{T}_1^1(M_n)$  (*R* - curvature tensor field of the connection  $\nabla$ ).

From (7) we see that the vertical distribution *V* is tangent to the fibres  $\pi^{-1}(x)$  of  $T_q^p(M_n)$  and is integrable, *i.e.*  $\begin{bmatrix} {}^{v}A, {}^{v}B \end{bmatrix} \in V$ . Moreover, this distribution is also totally geodesic, *i.e.*  $\nabla_{v_A} {}^{v}B \in V$ . In fact, using (8) we have

$$2^{s}g(\nabla_{v_{A}}{}^{v}B, {}^{H}X) = {}^{H}X {}^{v}(g(A, B)) - {}^{s}g([{}^{v}A, {}^{H}X], {}^{v}B) - {}^{s}g([{}^{v}B, {}^{H}X], {}^{H}A)$$
$$= {}^{v}(Xg(A, B) - g(\nabla_{x}A, B) - g(A, \nabla_{x}B))$$
$$= 0$$

From Equation (9) we see that the vertical part of  $\begin{bmatrix} {}^{H}X , {}^{H}Y \end{bmatrix}$  vanishes if and only if  $\overline{D}_{R(X,Y)} = 0$  for all  $X, Y \in \mathfrak{T}_{0}^{1}(M_{n})$ . It is easy to prove that this is equivalent to R = 0 if p + q > 0.

Thus, taking account of Theorem 2, we have

**Theorem 3.** The almost product Riemannian manifold  $(T_q^p(M_n), {}^sg, J)$  is locally decomposable if and only if  $M_n$  is locally flat.

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