DYNAMIC SPLINTING AFTER EXTENSOR TENDON REPAIR IN ZONES V TO VII

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This retrospective study evaluates a dynamic active motion protocol for extensor tendon repairs in zones V to VII. Fifty-eight patients with 87 extensor tendon injuries were examined. Using Geldmacher's and Kleinert and Verdan's evaluation systems, the results were graded as "excellent" and "good" in more than 94%, and as "satisfactory" in the remainder. The need for secondary tenolysis was low (6%), and no other surgical complication occurred.

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INTRODUCTION

The outcome of flexor tendon injuries was poor until special suture techniques were used in combination with active or passive motion rehabilitation techniques (Chow et al., 1989; Evans, 1995; Kleinert et al., 1967, 1973; Slater and Bynum, 1997; Verdan, 1966). Chow combined the essential parts of the Kleinert and the Duran and Houser protocols to produce a dynamic protocol frequently called the "Washington protocol" (Chow et al., 1987; Duran et al., 1976).

In contrast to flexor tendon injuries, extensor tendon lacerations are still frequently considered as simple injuries which are easy to treat. Consequently they have not been given the same clinical and scientific attention (Doyle, 1992; Elliott, 1970; Entin, 1960) and are often treated by younger or less experienced staff (Evans et al., 1995; Ip and Chow, 1997). Postoperative protocols traditionally consist of static immobilization in a forearm splint for 3-4 weeks, which frequently results in significant loss of flexion and extension lags of the metacarpophalangeal and interphalangeal joints, caused by tendon adhesions and joint capsule contractures (Blair and Steyers, 1992; Chow et al., 1989; Couch, 1939; Lee, 1984; Mason and Allen, 1941; Miller, 1942). Based on the excellent results in flexor tendon repair and supporting experimental data (Amiel et al. 1982, 1991; Becker and Diegelmann, 1984; Evans, 1986, 1995; Evans and Burkhalter, 1986; Evans and Thompson, 1992; Freehan and Beauchene, 1990; Gelbermann et al., 1980-1983, 1985, 1991; Gelbermann and Manske, 1985; Hitchcock et al., 1987; Rothkopf et al., 1991; Woo et al., 1980, 1981a,b, 1982), Evans and Chow introduced dynamic active range of motion protocols for extensor tendon repairs (Chow et al, 1989; Duran and Houser, 1975; Evans, 1995; Gelbermann et al., 1986; Ip and Chow, 1997). Little data has been published on the efficacy of these "reversed Washington" protocols.

PATIENTS AND METHODS

Eighty-five patients with simple extensor tendon injuries in Verdan's zones V to VII and no severe associated injuries were treated from 1995 until 1999. Fifty-eight of these 85 patients with a total of 87 injured digits (68% of the patient population) had complete follow-up data. The remaining 27 patients were excluded from the study because of poor compliance with therapy, or incomplete data. All the tendons were repaired with a modified Kirchmayr–Kessler suture or a horizontal mattress suture (Geldmacher and Köckerling, 1991; Newport and Williams, 1992).

Dynamic rehabilitation programme

The dynamic rehabilitation programme (Table 1) started on the second postoperative day, when a thermoplastic dorsal forearm splint (Fig. 1) was formed which held the wrist in 30° extension and the finger metacarpophalangeal joints in 10° hyperextension. Active flexion of the metacarpophalangeal joints to 15 or 30° was permitted in this splint depending on the intraoperative tension of the tendon repair. The permitted range of active flexion was constantly increased, in defined weekly steps, to 90° within 5 weeks. Active extension of the distal interphalangeal and proximal interphalangeal joints was commenced in the fourth week, and the splint was removed after 5 weeks.

The mean length of follow-up was 21 (range, 5–39) months, and outcome was then assessed by measuring the active ranges of motion (AROM) of all finger joints and the wrist, the pulp to palm distance, power grip (Jamar Dynamometer[™]), pinch grip (Pinchmeter[™]) and pain (Visual Analogue Scale). Patients' subjective perception of their outcome was also assessed using a grading scale (excellent, good, fair and poor). The functional results were evaluated with Geldmacher's (1991), Kleinert and Verdan's (1983) and Miller's (1942) systems, and graded into four categories: excellent,

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Table 1—Rehabilitation program for extensor tendons in Verdan zones \boldsymbol{V} to $\boldsymbol{V}\boldsymbol{I}\boldsymbol{I}$

Day	Rehabilitation program	
Day 0	Extensor tendon repair	
Day 3	Forearm-based dorsal splint Wrist: 30° extension MPJ: 10° hyperextension PIP/DIPJ: free	
	<i>Exercise programme: (10 timeslh)</i> Active flexion of MPJ to 30° (15°)	
Week 2	Active flexion of MPJ to 45° (30°)	
Week 3	Active flexion of MPJ to 60° (45°)	
Week 4	Active flexion of MPJ to 90° (60°) Active extension of PIP/DIPJ Fist (if possible)	
Week 5	Active flexion of MPJ to 90°	
Week 6	Splint removed Physical therapy against resistance	
Week 7–12	Physical therapy against increased resistance	

MPJ – metacarpophalangeal joint; PIPJ – proximal interphalangeal joint; DIPJ – distal interphalangeal joint.

good, fair and poor. The results for our patients were then compared with a historical group of patients treated with static immobilization (Geldmacher et al., 1986; Kleinert and Verdan, 1983; Miller, 1942).

RESULTS

Only five patients (9%) were women, and the mean age of the group was 37 years (range, 12–67 years). Forty-one (71%) of the 58 sustained a right hand injury, and

29 patients (50%) had an injury to the middle finger. Nineteen hands (33%) with 48 digits had more than one (two to four) extensor tendon lacerations. One patient required split-thickness skin graft to cover a soft tissue defect on the dorsum of the hand. Thirty-one of the 58 injuries (53%) were occupational injuries. Patients returned to their previous work status after a mean of 10 weeks (range, 5-30 weeks), and no patient had a residual impairment that interfered with his/her activities of daily life. Five (6%) digits in four patients required tenolysis because of tendon adhesions. The split-thickness skin graft that was performed in one case had no effect on finger function. The mean total active range of motion (TAM) of the 87 digits was 237° (range, 155–330°), representing 94% of the uninjured hand. The total extension lag of the fingers was 6° (range, 0–50°), with 62 of the injured fingers having no extension lag. The mean total active ranges of motion of the proximal and distal interphalangeal joints were 94° (range, 50-145°) and 63° (range, $0-100^\circ$), respectively. A mean loss of metacarpophalangeal joint flexion of 8° (range, 0-55°) occurred. One patient with more than one injured extensor tendon had a loss of 55° flexion in one metacarpophalangeal joint. The mean metacarpophalangeal extension lag was only 2° (range, 0-20°). Fortyseven patients (81%) were able to make a full fist; and the mean pulp to palm distance was 0.2 cm (range, 0-3.5 cm). Only three patients had a pulp to palm distance of greater than 2 cm. A mean 5% (range, 0–50%) loss of wrist extension and a 6% (range, 0-40%) loss of flexion, in comparison to the uninjured hand, was noted. Grip strength averaged 91% (range, 50-116%) of the unaffected hand, with 17 patients (29%) regaining their pre-injury grip strength (Table 2). All patients who sustained injuries to up to three extensor tendons regained more than 80% of the grip strength of the unaffected hand. Pinch grip strength ranged from 25% to 140% (mean, 78%) of the uninjured hand and the

Total active motion	236°	(range 155–330°)
Extension lag of all joints	6.°	(range $0-50^{\circ}$)
Flexion lag of all joints	3°	(range $0-50^{\circ}$)
Range of motion MPJ	78°	(range 30–120°)
Extension lag MPJ	3°	(range $0-20^{\circ}$)
Flexion lag MPJ	8°	(range 0–55°)
Range of active motion PIPJ	94°	(range 50–145°)
Extension lag PIPJ	3°	(range $0-50^{\circ}$)
Flexion lag PIPJ	4°	(range $0-40^{\circ}$)
Range of active motion DIPJ	63°	(range 0–100°)
Extension lag DIPJJ	1°	(range $0-25^{\circ}$)
Flexion lag DIPJ	5°	(range $0-45^{\circ}$)
Extension lag wrist	5°	(range $0-40^{\circ}$)
Flexion lag wrist	6°	(range $0-80^{\circ}$)
Pulp to pulm distance	0.2 cm	(range 0–3.5)
Grip strength	91% of uninjured hand	(range 50–116%)
Pinch grip strength	78% of uninjured hand	(range 25–140%)
Pain (VAS 1–10)	0.2	(range 0–5)

Table 3—Different grading systems

	Geldmacher	Miller	Kleinert
Excellent	61 (70%)	11 (13%)	24 (28%)
Good	21 (24%)	38 (44%)	58 (67%)
Fair	5 (6%)	32 (37%)	5 (6%)
Poor	0	6 (7%)	0

mean pain value on the Visual Analogue Scale (VAS 1–10) was 0.2 (range, 0–5). Only four patients reported increased pain at work and subjective patient satisfaction was high. Forty-three (74%) of the patients graded their results as excellent, 12 as good and only five as fair. One patient rated the result as fair although the measured function of the digit was excellent. None of the patients were dissatisfied with the result. The outcomes according to the various grading systems are shown in Table 3.

DISCUSSION

Although early active motion protocols are considered the gold standard for flexor tendon injuries, they have not gained widespread acceptance for extensor tendon injury rehabilitation. The purpose of this study was to evaluate the efficacy of a dynamic active motion protocol following extensor tendon repairs in zones V to VII in a clearly defined group of patients. The main weakness of this study is the lack of a control group. The study was commenced as a pilot project in 1994, but the preliminary results were so convincing that it was not considered ethical to treat a group of patients with tendon repair and immobilization. Thomas et al. (1996) reported on 88 injured extensor tendons in zones V to VII in a homogenous patient group after early dynamic mobilization and found that 61% had regained a full range of motion after 1 year. Ip and Chow (1997) reported on zones IV to VIII injuries treated with dynamic splintage and observed a total active range of motion (TAM) of 242° , which represented a loss of 23° of active finger motion compared to a normal Chinese population. Our data compare favourably with these results with 66 percent of all digits recovering more than 90% of the TAM of the unaffected side. Only few studies compare the results of immobilization and active motion protocols (Chow et al., 1989; Evans, 1989, 1995; Purcell et al., 2000). Evans (1989) had to perform tenolyses in 30% of the treated digits and Chow et al. (1989) in 17% after immobilization and Kelly (1959) reported 20% poor results following 4 weeks of immobilization. Geldmacher and Köckerling (1991) found that only 76% of 145 extensor tendon repairs achieved good or excellent results: 24% were rated as fair to poor.

Grip strength in our patients was 91% of the contralateral hand. The loss of active range of motion and grip strength following treatment with early motion protocols is low and should only slightly impair the patient's activities of daily living (Chow et al., 1989). Eighty-one per cent of our patients could make a full fist and they considered that as important as grip strength.

Associated injuries significantly worsen the results of extensor tendon repair (Hauge, 1954; Ip and Chow, 1997; Kelly, 1959; Newport et al., 1990) which is why patients with associated injuries were excluded from this study. Newport demonstrated an average range of motion of 89% of the healthy hand after mostly static splinting for 3–4 weeks. This series also included injuries in zones I to IV and there were sometimes associated digital injuries, so that it is not comparable with our study (Newport et al., 1990). However, even the comparison of the functional outcomes of simple injuries remains difficult, since authors use different evaluation systems that yield different outcome results (Browne and Ribik, 1989; Elliott, 1970, Evans, 1995; Ip and Chow, 1997; Newport et al., 1990; Newport and Shukla, 1992; Slater and Bynum, 1997; Sylaidis et al., 1997; Thomas et al., 1996). Almost 94% of our patients rated their results as excellent (74%) or good (20%) and thought that the rehabilitation programme was easy to learn. Intensive individual care by the therapists, and the ability to return to their pre-injury occupation probably account for the high satisfaction level. The surgeon factor is apparently not so crucial with these types of follow-up protocol as, although the extensor tendon repairs were performed by numerous surgeons with different operative experiences, our data were comparable to those of groups where only small numbers of surgeons were involved (Evans, 1995; Kerr and Burczak, 1989). Dynamic rehabilitation protocols are expensive and labour intensive (Crosby and Wehbe, 1996, Purcell et al., 2000) and require individually tailored splints for each patient. In addition the patient has to be seen on a regular basis by a competent hand therapist. Thus, although beneficial, these therapeutic protocols may have to be confined to hand surgery units that are able to provide the necessary infrastructure (Evans, 1995). Our data suggest that better results are achieved with active motion protocols than with immobilization treatment regimes. We consider that active early motion protocols should be considered as the standard for extensor tendon repairs in zones V to VII.

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