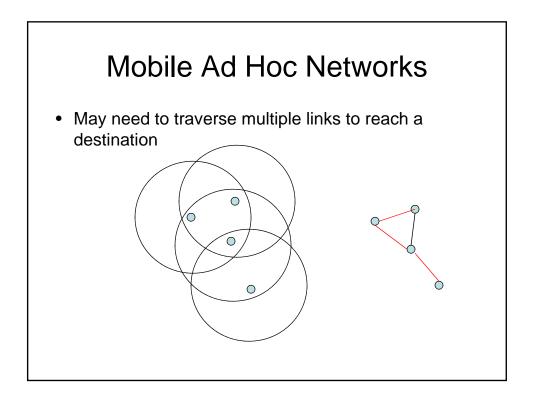
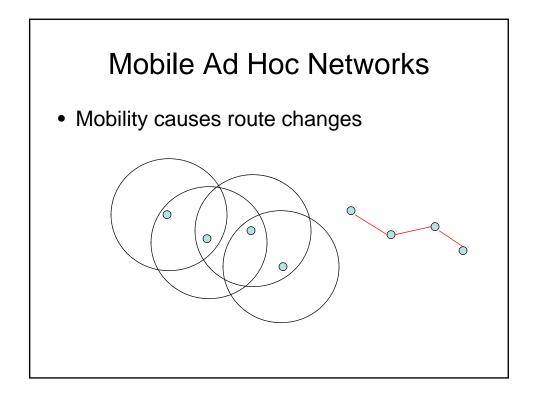
Lecture 4: Mobile Ad Hoc and Sensor Networks (I)

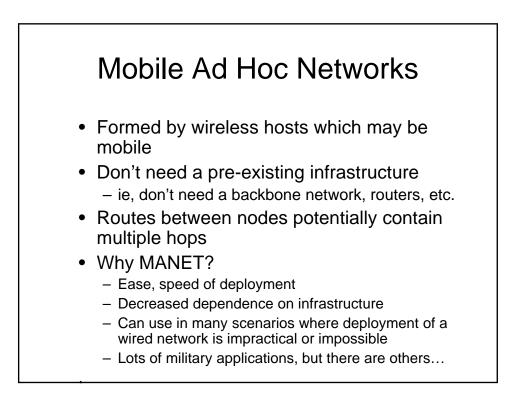
Ing-Ray Chen

CS 6204 Mobile Computing Virginia Tech

Courtesy of G.G. Richard III for providing some of the slides



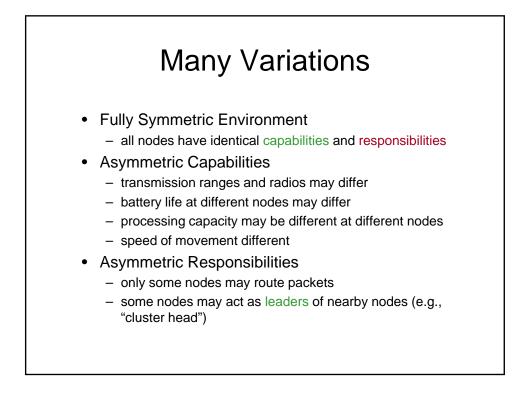




Many Applications

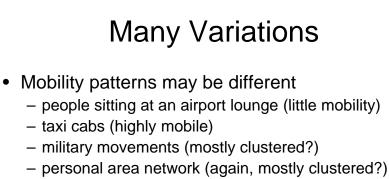
Personal area networking

- cell phone, laptop, ear phone, wrist watch
- Civilian environments
 - meeting rooms
 - sports stadiums
 - groups of boats, small aircraft (wired REALLY impractical!!)
- Emergency operations
 - search-and-rescue
 - policing and fire fighting
- Sensor networks
 - Groups of sensors embedded in the environment or scattered over a target area



Many Variations

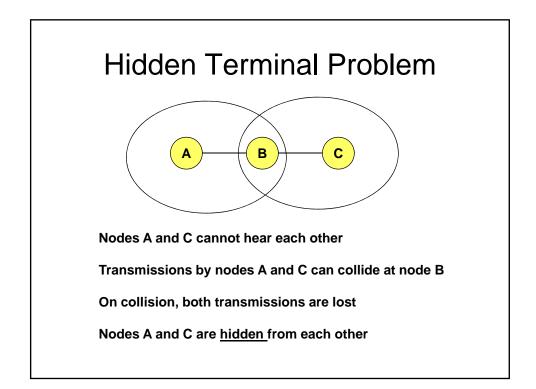
- Traffic characteristics may differ
 - bandwidth
 - timeliness constraints
 - reliability requirements
 - unicast / broadcast / multicast / geocast
- May co-exist (and co-operate) with an infrastructure-based network

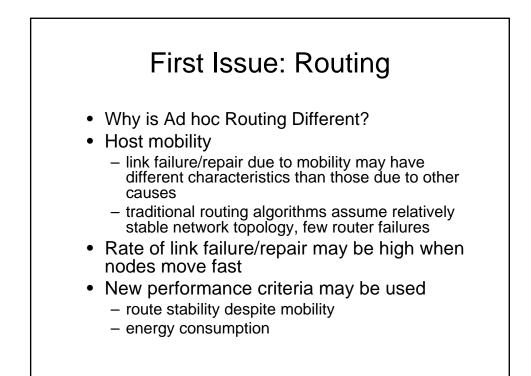


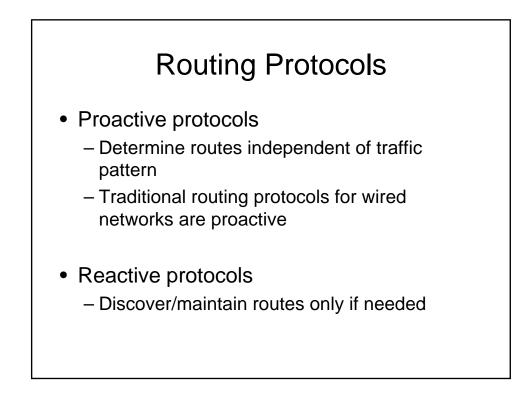
- Mobility characteristics
 - speed
 - predictability
 - direction of movement
 - pattern of movement
 - uniformity (or lack thereof) of mobility characteristics among different nodes

Challenges

- Limited wireless transmission range
- Broadcast nature of the wireless medium
- Packet losses due to transmission errors
- Environmental issues ("chop that tree!!")
- Mobility-induced route changes
- Mobility-induced packet losses
- Battery constraints
- Potentially frequent network partitions
- Ease of snooping on wireless transmissions (security hazard)
- Sensor networks: very resource-constrained!

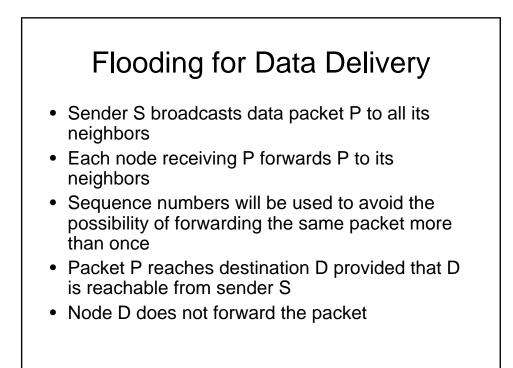


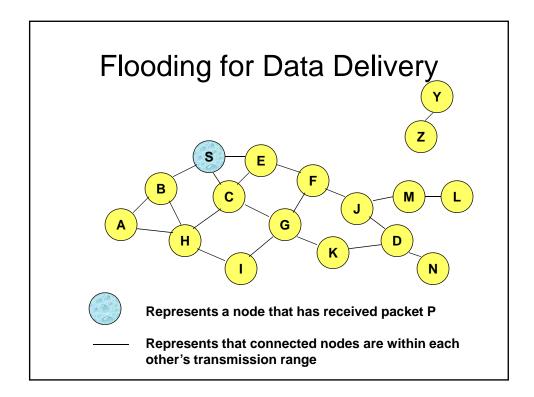


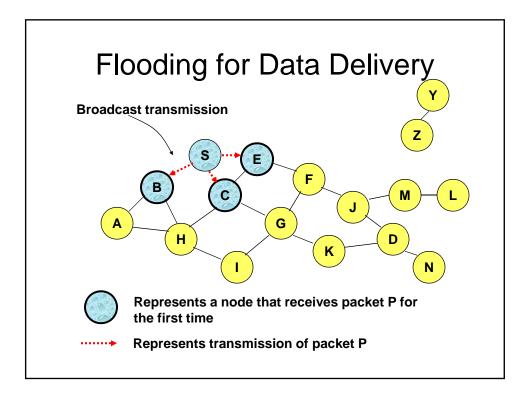


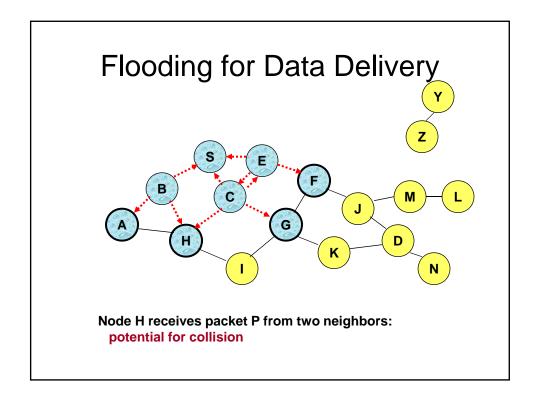
Trade-Off: Proactive vs. Reactive

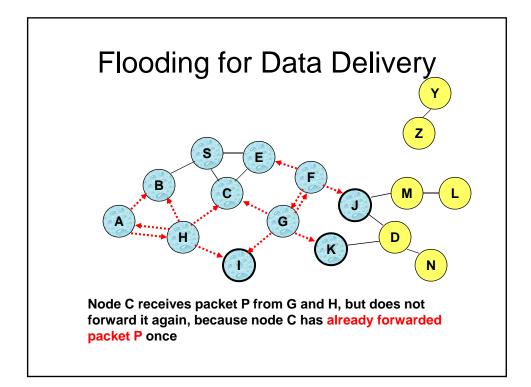
- · Latency of route discovery
 - Proactive protocols may have lower latency since routes are maintained at all times
 - Reactive protocols may have higher latency because a route from X to Y will be found only when X attempts to send to Y
- · Overhead of route discovery/maintenance
 - Reactive protocols may have lower overhead since routes are determined only if needed
 - Proactive protocols can (but not necessarily) result in higher overhead due to continuous route updating
- Which approach achieves a better tradeoff depends on the traffic and mobility patterns

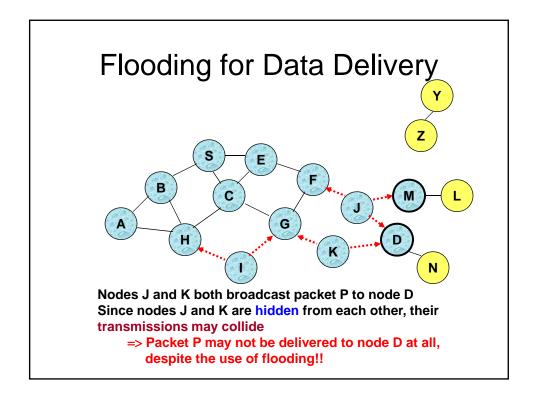


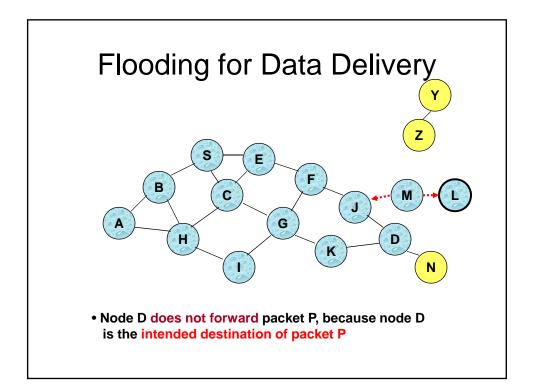


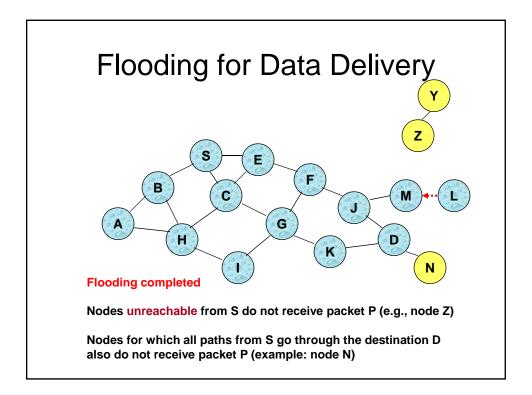


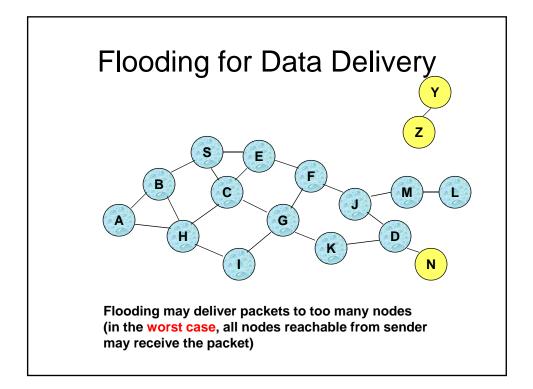






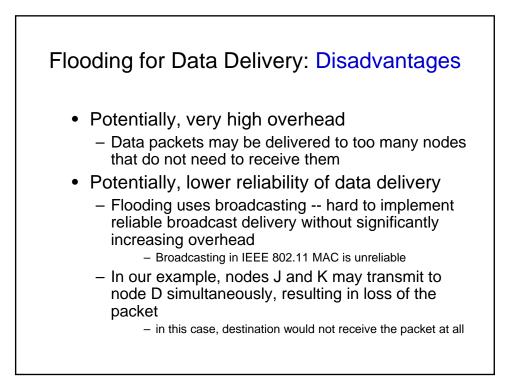






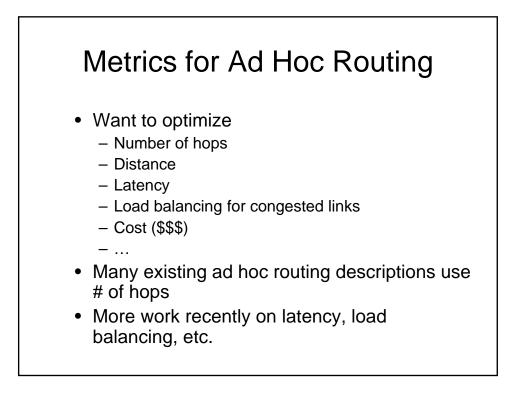
Flooding for Data Delivery: Advantages

- Simplicity
- More efficient than other protocols when the rate of information transmission is low enough that the overhead of explicit route discovery/maintenance incurred by other protocols is relatively higher
 - this scenario may occur, for instance, when nodes transmit small data packets relatively infrequently, and many topology changes occur between consecutive packet transmissions
- Potentially higher reliability of data delivery
 - Because packets may be delivered to the destination on multiple paths
- For high mobility patterns, it may be the only reasonable choice



Flooding of Control Packets

- Many protocols perform (potentially *limited*) flooding of control packets, instead of data packets
- The control packets are used to discover routes
- Discovered routes are subsequently used to send data packets without flooding
- Overhead of control packet flooding is amortized over data packets transmitted between consecutive control packet floods



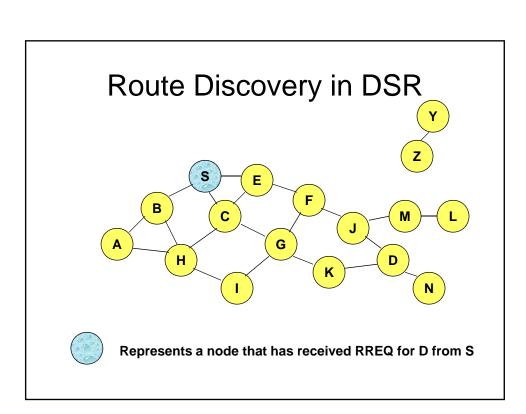
Dynamic Source Routing – DSR (Ref [9])

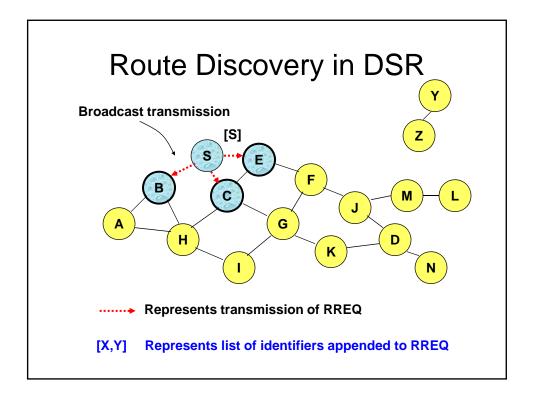
- When node S wants to send a packet to node D, but does not know a route to D, node S initiates a route discovery by flooding a Route Request (RREQ) packet
- Each node appends own identifier when forwarding RREQ
- A route if discovered will return from D to S
- When node S sends a data packet to D, the entire route is included in the packet header

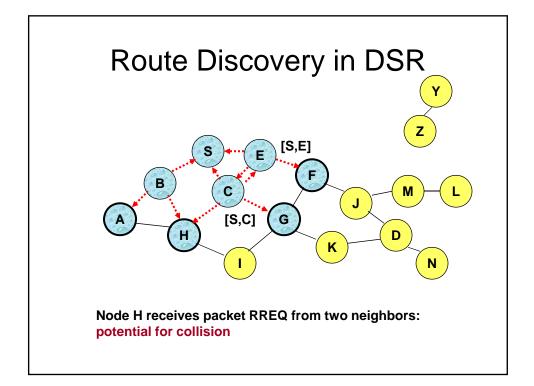
 hence the name source routing
- Intermediate nodes use the source route included in a packet to determine to whom a packet should be

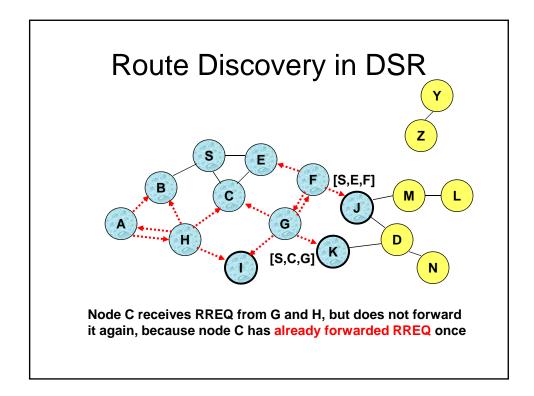
unavailable

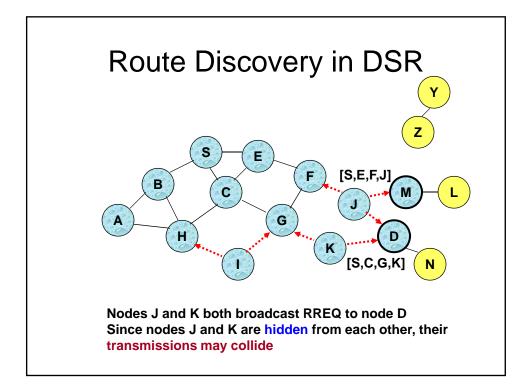
Reactive: Routes are discovered only when a node wants to send data and route to destination is

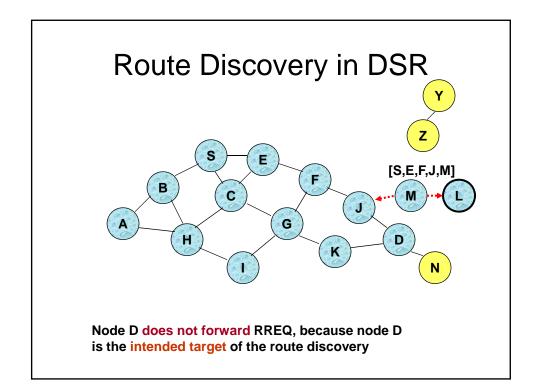


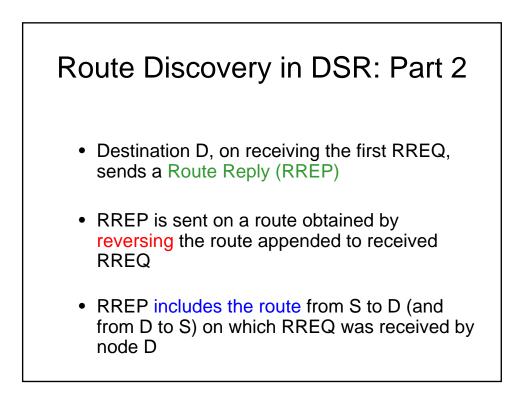


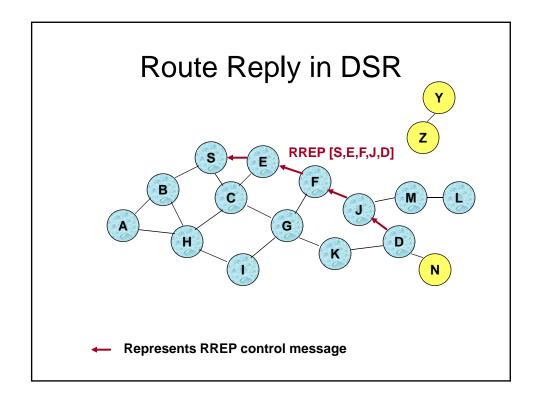


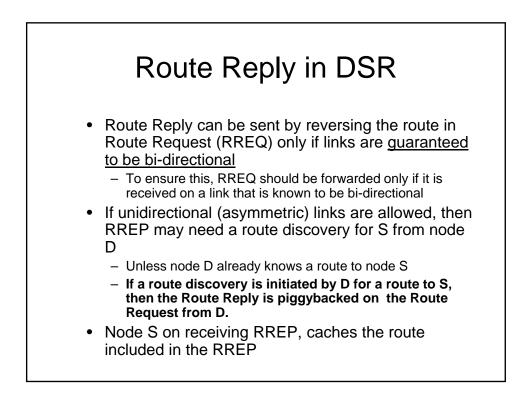


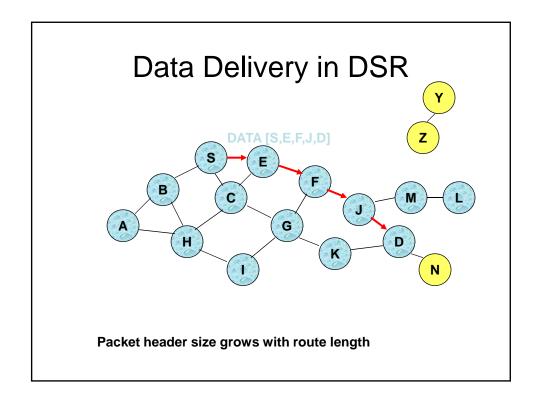


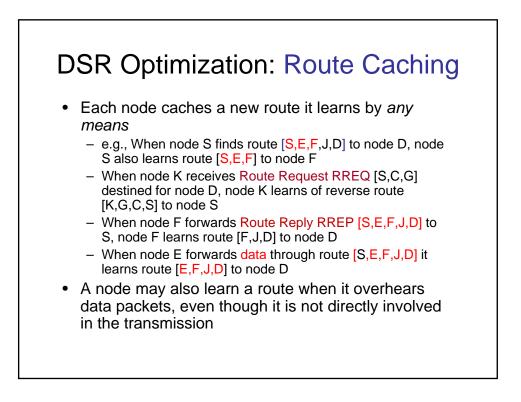


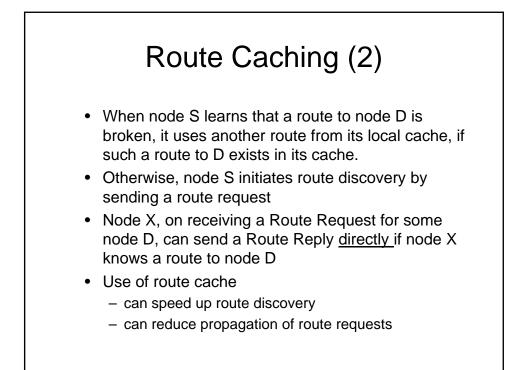


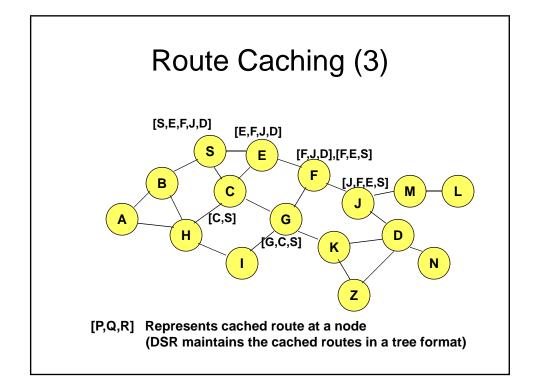


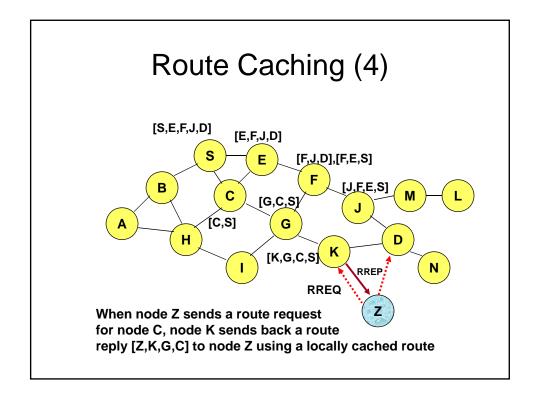


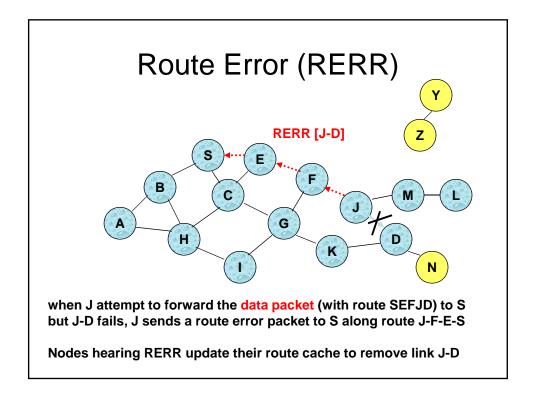






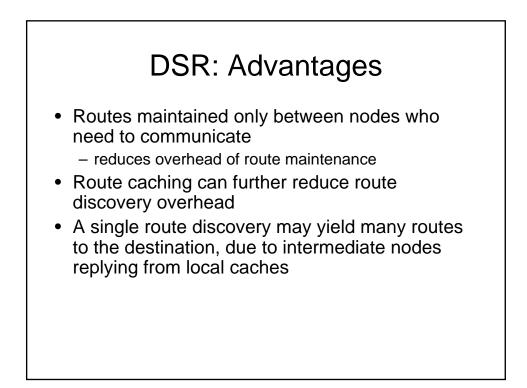


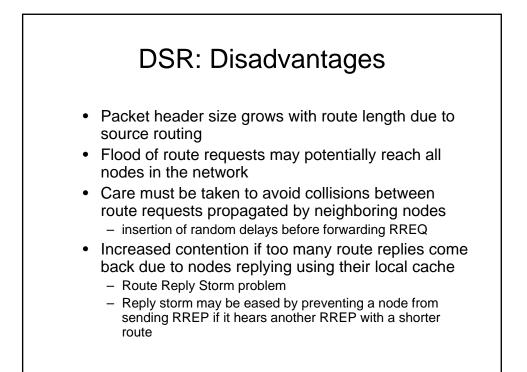


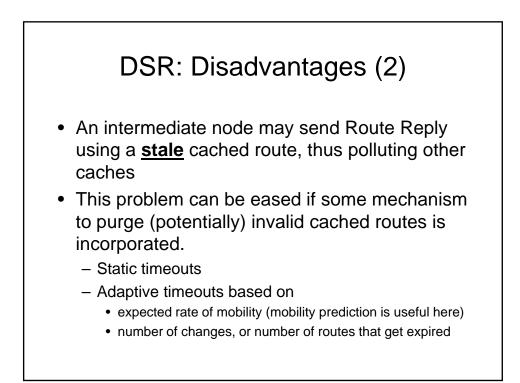


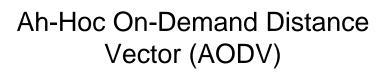
Route Caching: Beware!

- Stale caches can adversely affect performance
- With passage of time and host mobility, cached routes may become invalid
- A sender host may try several stale routes (obtained from local cache, or replied from cache by other nodes), before finding a good route
- It may be <u>more expensive</u> to try several broken routes than to simply discover a new one!
- RERR messages are unreliable, so news of broken routes may not even propagate completely!

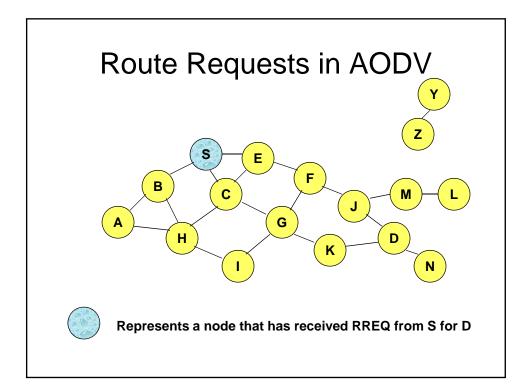


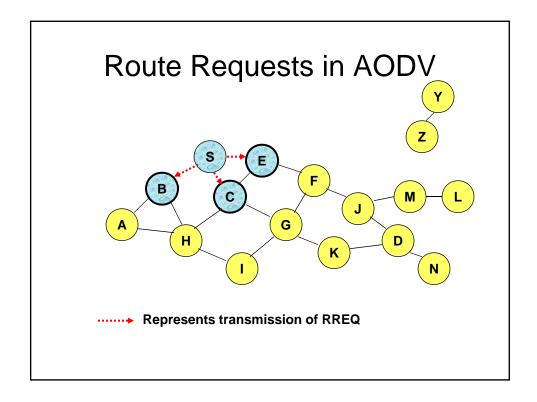


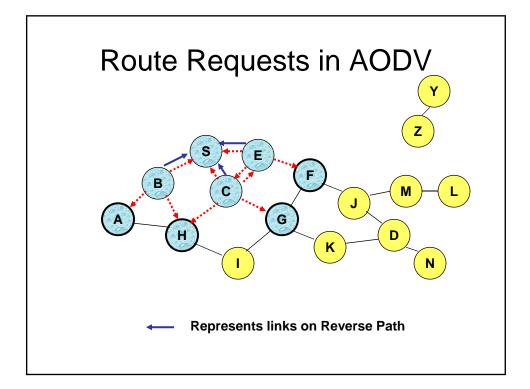


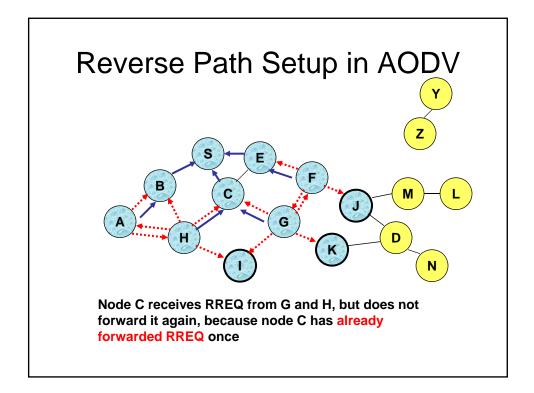


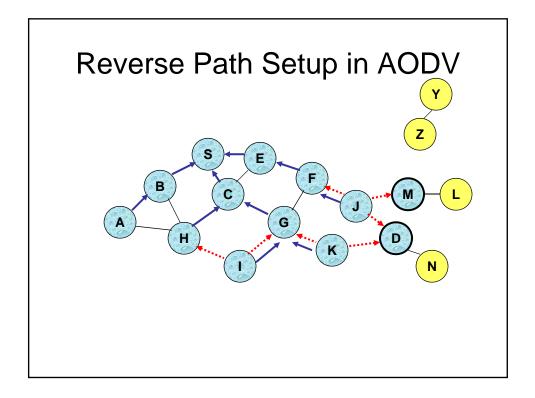
- Distance vector-based routing for ad hoc networks
- Significantly more complicated protocol than DSR, because avoiding routing loops is much more difficult
 - Loop elimination easy in DSR because entire route is available!
- The following pictorial does <u>not</u> expose the complexity of AODV—just to give a basic idea

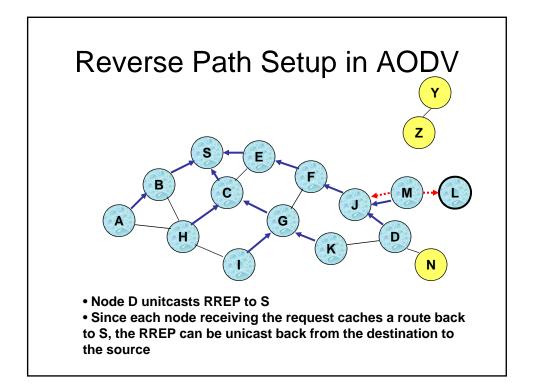


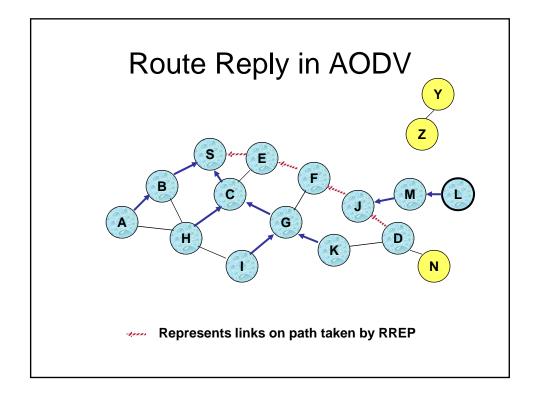


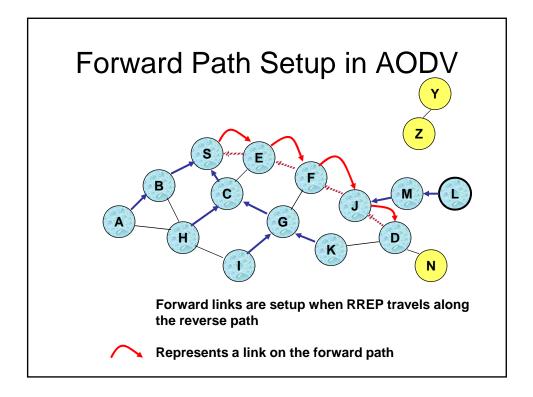


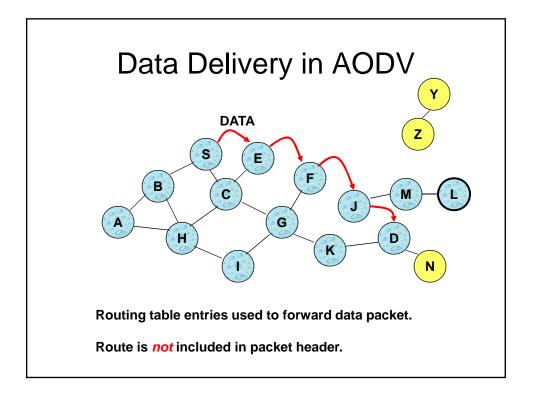


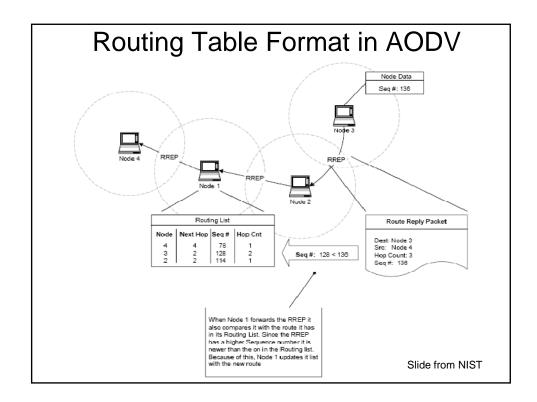


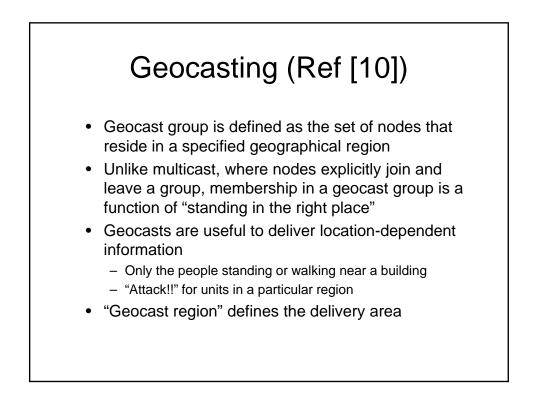


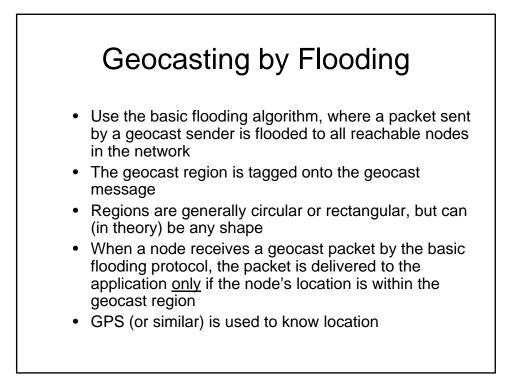


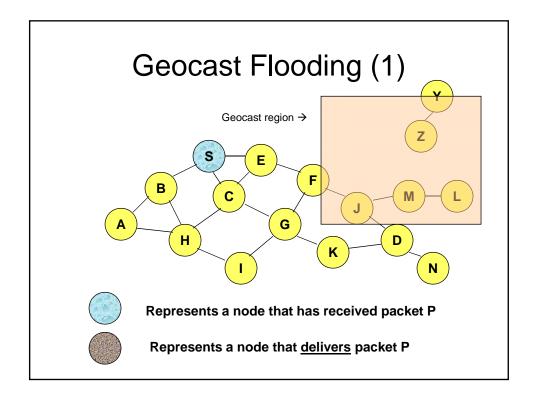


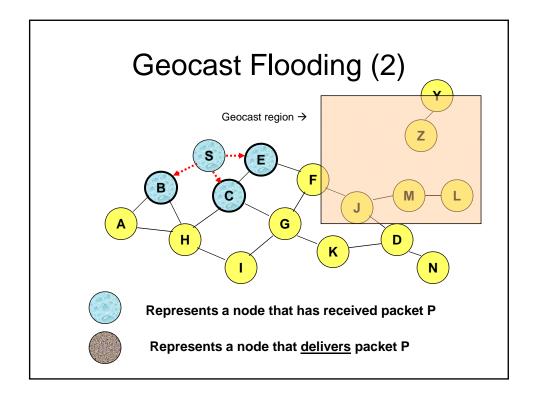


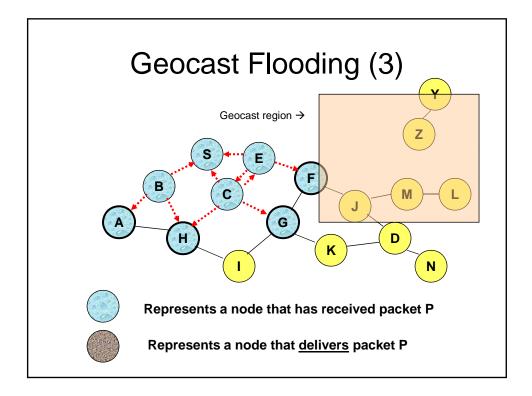


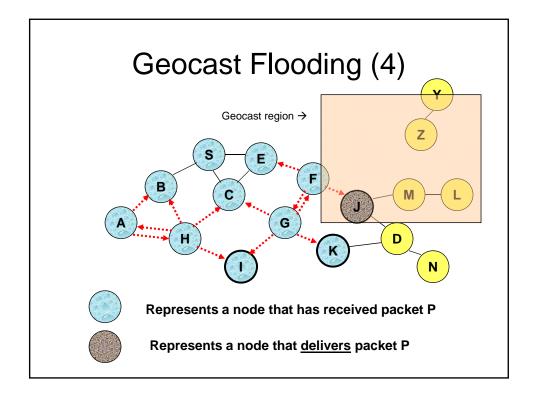


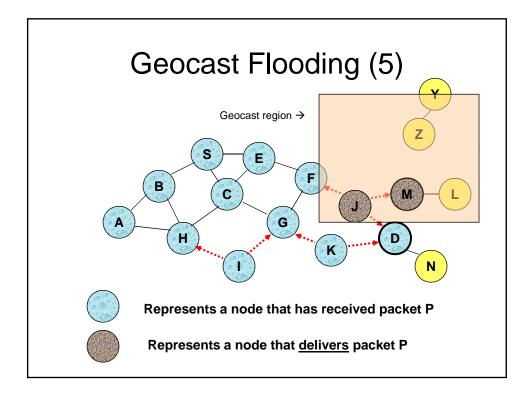


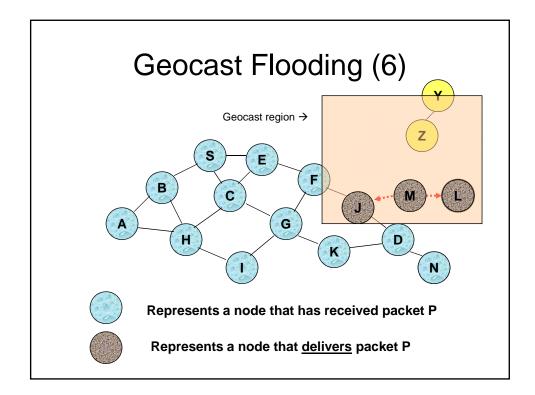


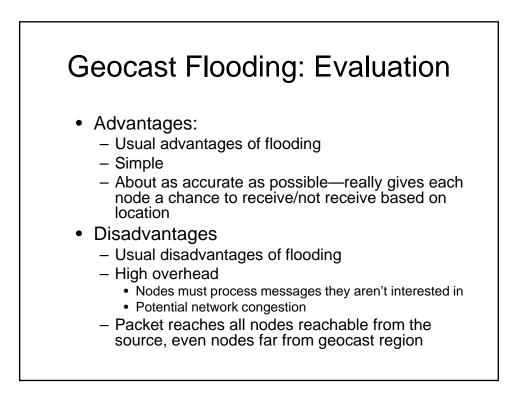


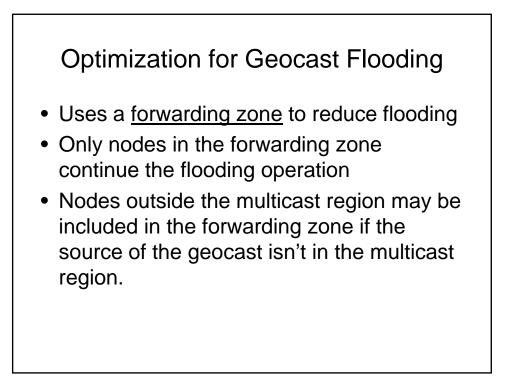


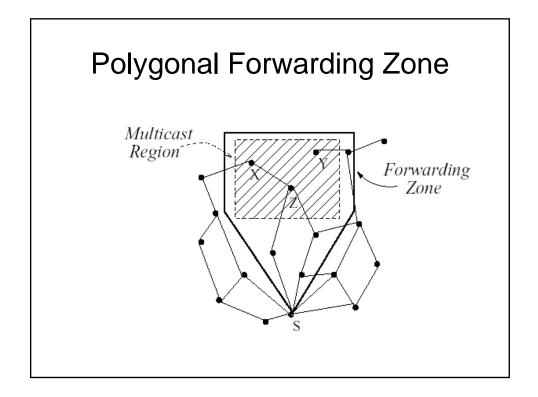


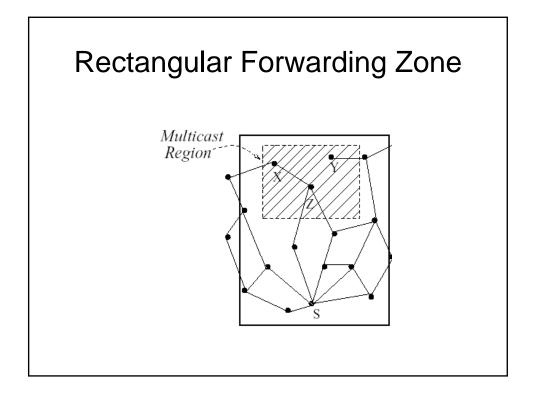


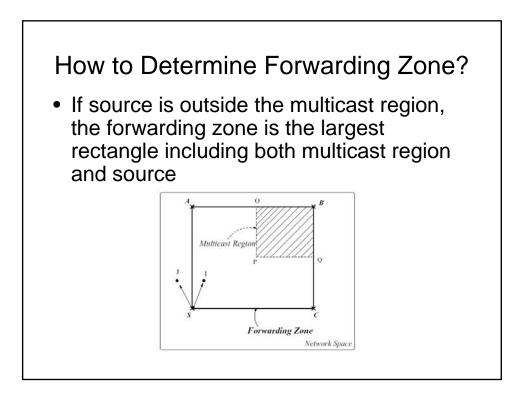


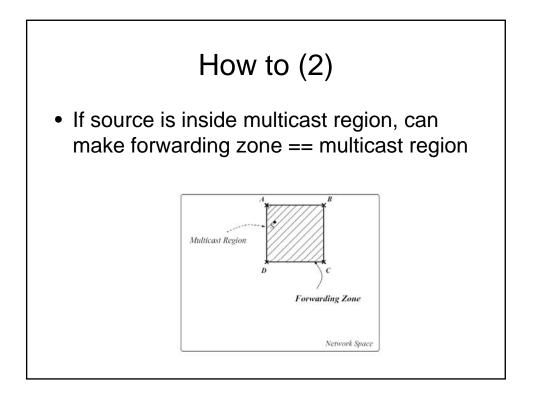


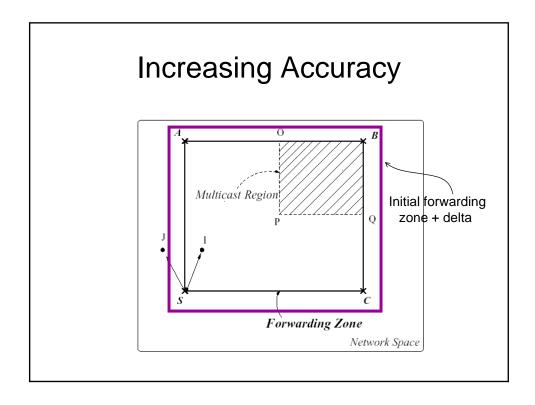


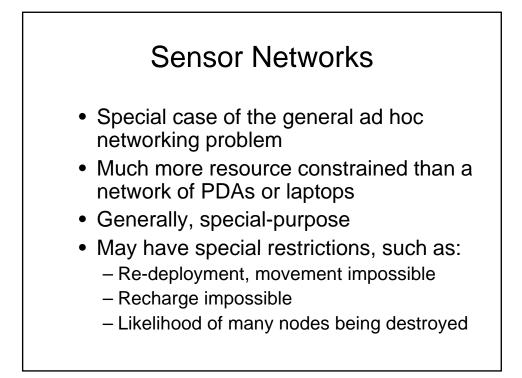


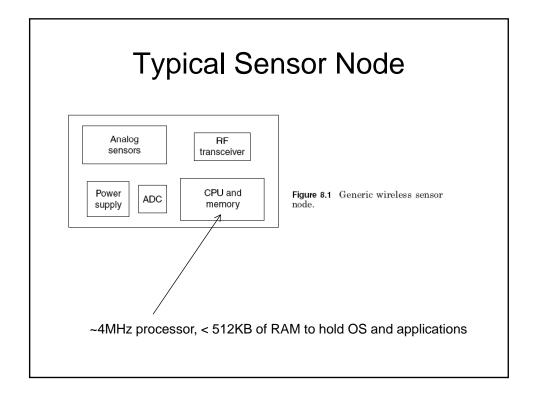










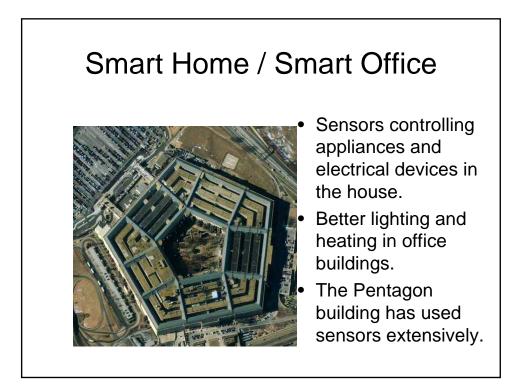


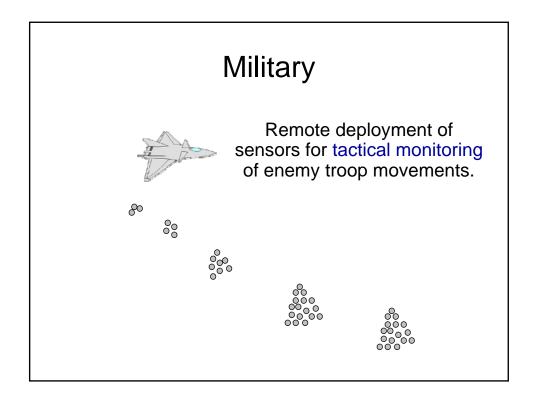


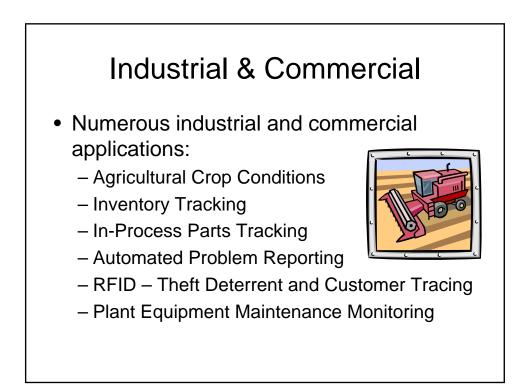
- A sensor node has:
 - Sensing Material
 - Physical Magnetic, Light, Sound
 - Chemical CO, Chemical Weapons
 - Biological Bacteria, Viruses, Proteins
 - Integrated Circuitry (VLSI)
 - A-to-D converter from analog sensor to circuitry
 - Packaging for environmental safety
 - Power Supply
 - Passive Solar, Vibration
 - Active Battery power, RF Inductance

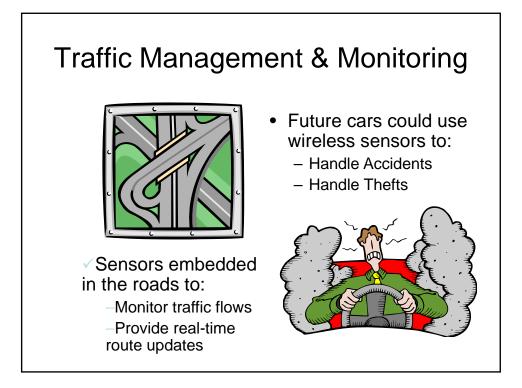
Advar		Wirele: lodes	ss Sen	sor
Consider	Multiple G	enerations	of Berkele	ey Motes
Model	Rene	Mica	Mica-2	Mica-Z
Date	1999	2002	2003	2004
CPU	4 MHz	4 MHz	4 MHz	4 MHz
Flash Memory	8 KB	128 KB	128 KB	128 KB
RAM	512 B	4 KB	4 KB	4 KB
Radio	10 Kbps	40 Kbps	76 Kbps	250 Kbps

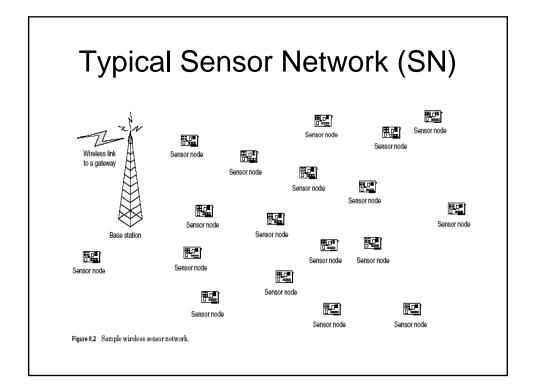
	storical Comparisor	
Model	Honeywell H-300	Mica 2
Date	6/1964	7/2003
CPU	2 MHz	4 MHz
Flash Memory	None	128 KB
RAM	32 KB	4 KB

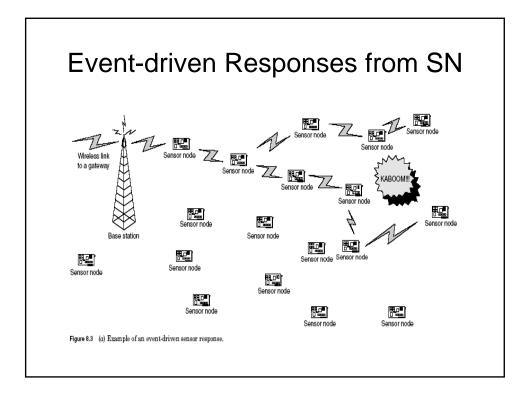


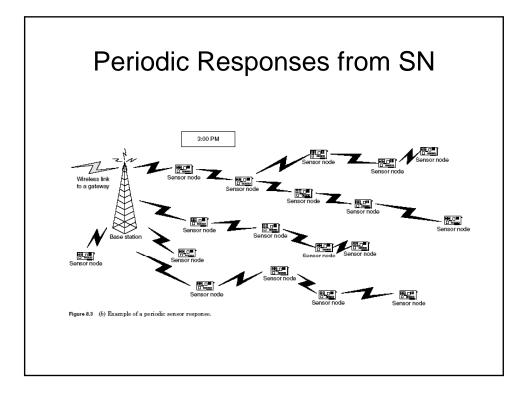






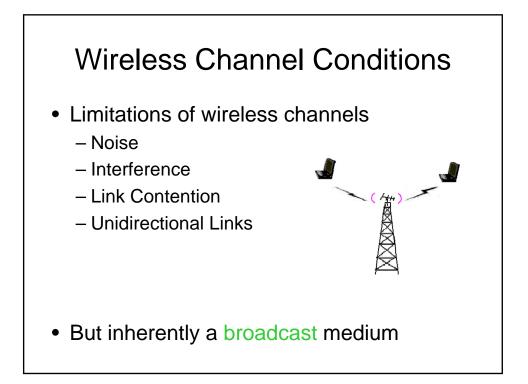


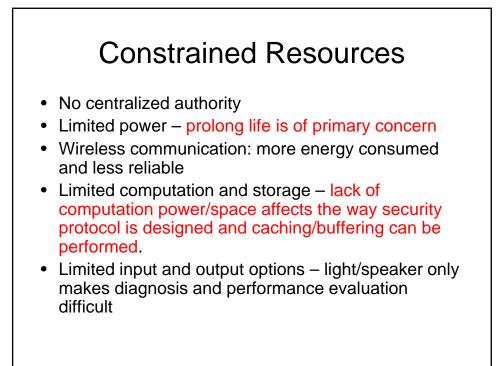


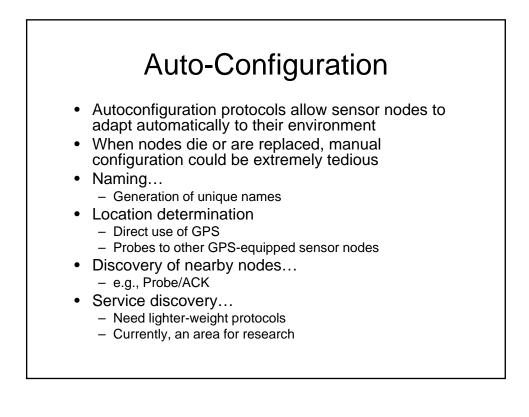


Sensor Network Tasks

- Neighbor discovery
- Self configuration
- · Sensing, sensor data processing
- Data aggregation, storage, and caching
- Target detection, target tracking, and target monitoring
- Topology control for energy savings
- Localization
- Time synchronization
- Routing
- Medium access control

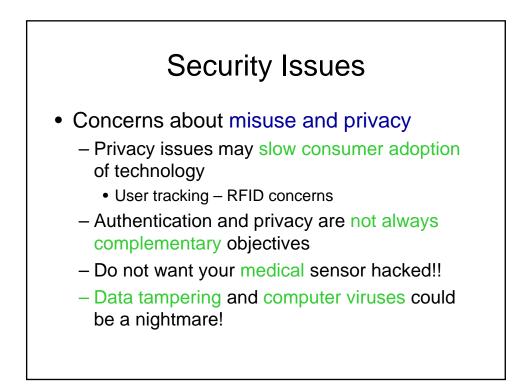


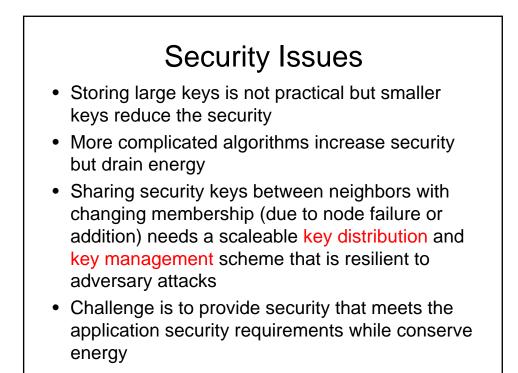


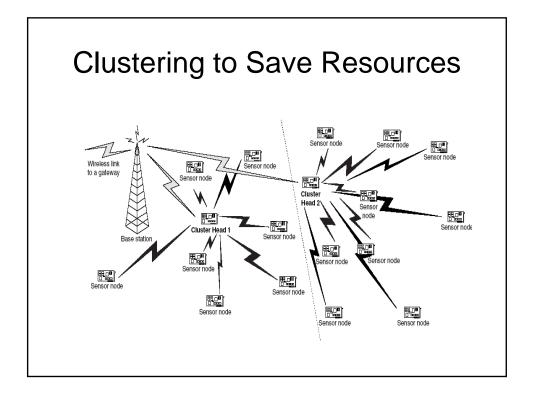


Need a Standardized Interface

- Automated interaction between sensors implies some standard mechanism for communication!
 - Requires compatible wireless technology
 - Standardization a common theme
 - TCP/IP for the Internet
 - Java for Internet programming
 - Jini, SLP, etc. for 802.11 wireless devices
- Need a service discovery protocol
 - Enables standard interface among sensors

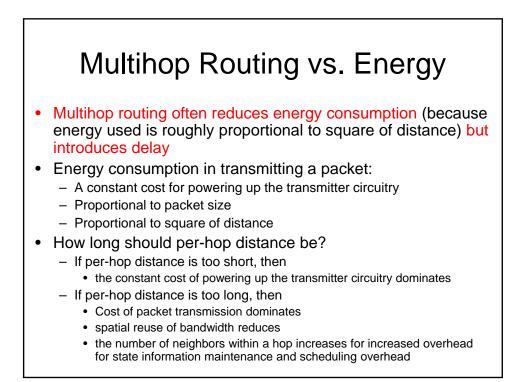


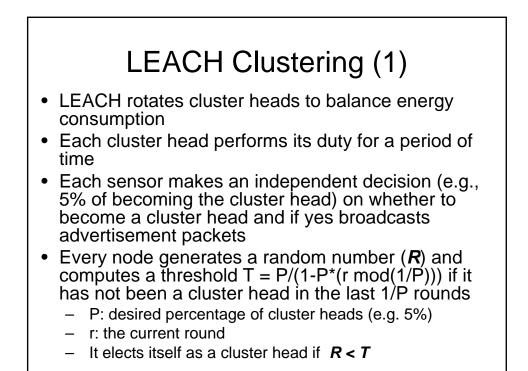


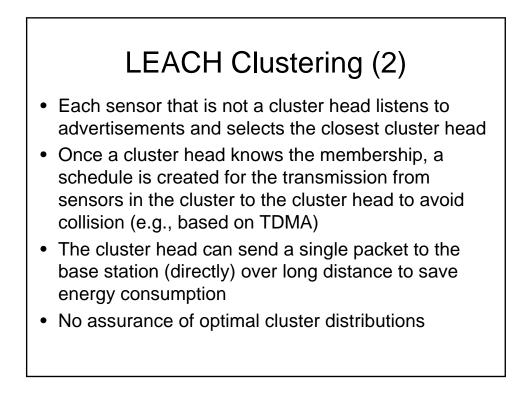


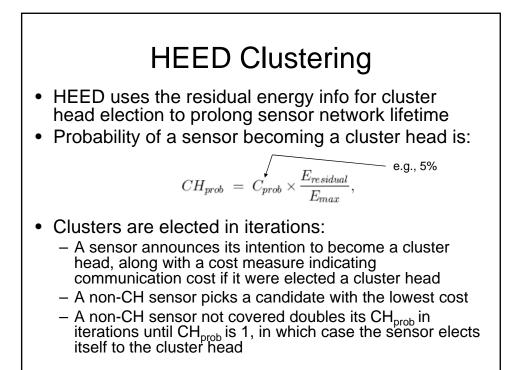
Clustering

- Divide the network into a number of equal clusters each ideally containing the same # of nodes
- · Cluster heads form a routing backbone
- Clustering is NP-complete
- Mobility may make a good clustering become bad later
- Data aggregation: Combining cluster data readings into a single packet can save energy





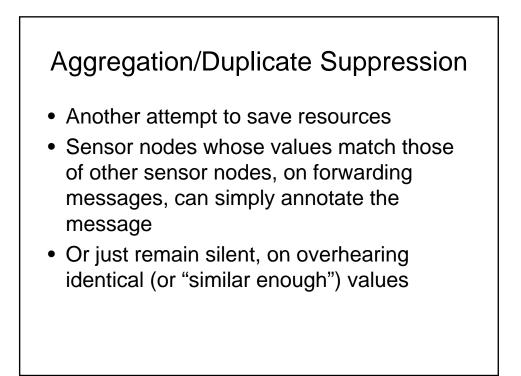




I. Initialize		II. Main Processing	
	$S_{nbr} \leftarrow \{v: v \text{ lies within my cluster range}\}$	Repe	eat
2.	Compute and broadcast cost to $\in S_{nbr}$	1.	If $((S_{CH} \leftarrow \{v: v \text{ is a cluster head}\}) \neq \phi)$
3,	$CH_{prob} \leftarrow max(C_{prob} \times \frac{E_{rasidual}}{E_{max}}, p_{min})$	2.	$my_cluster_head \leftarrow least_cost(S_{CH})$
4.	is_fi nal $CH \leftarrow FALSE$	З.	If $(my. cluster. head = NodeID)$
		4.	$lf(CH_{prob} = I)$
III. Finalize		5.	Cluster_head_msg(NodeID_fi nal_CH,cost)
	If (is_fi nal_CH = FALSE)	6.	is fi nal CH \leftarrow TRUE
2.	If $((S_{CH} \leftarrow \{v: v \text{ is a fi nal cluster head}\}) \neq \phi)$	7.	Else
8.	$my_cluster_head \leftarrow least_cost(S_{CH})$	8.	Cluster_head_msg(NodeID, tentative_CH,cost)
4.	join_cluster(cluster_head_ID, NodeID)	9.	Elself ($CH_{prob} = 1$)
5.	Else Cluster_head_msg(NodeID, fi nal. CH, cost)	10.	Cluster_head_msg(NodelD_fi nal CH,cost)
5.	Else Cluster_head_msg(NodelD, fi naL CH, cost)	11.	is fi nal CH \leftarrow TRUE
		12.	Elself Random(0,1) $\leq CH_{prob}$
		13.	Cluster_head_msg(NodeID,tentative_CH,cost)
		14.	$CH_{previous} \leftarrow CH_{prob}$
		15.	$CH_{prob} \leftarrow \min(CH_{prob} \times 2, 1)$
		Unti	$CH_{previous} = 1$

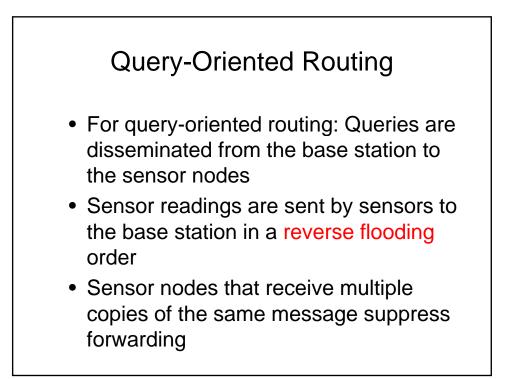
PEGASIS A chain of sensors is formed for data transmission (could be formulated by base station) Finding the optimal chain is NP-complete Sensor readings are aggregated hop by hop until a single packet is delivered to the base station: effectively when aggregation is possible Advantages: No long-distance data transmission; no overhead of maintaining cluster heads Disadvantages: Significant delay: Can use tree instead Disproportionate energy depletion (for sensors near

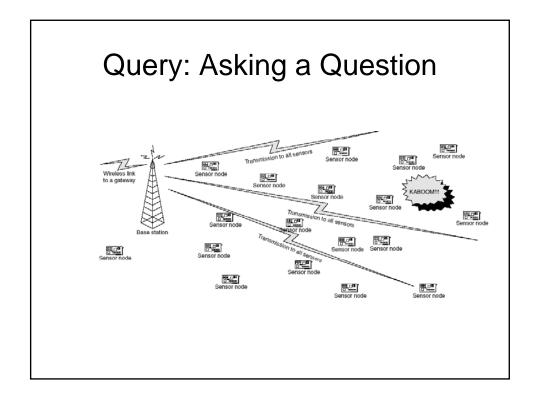
the base station): Can rotate parent nodes in the tree

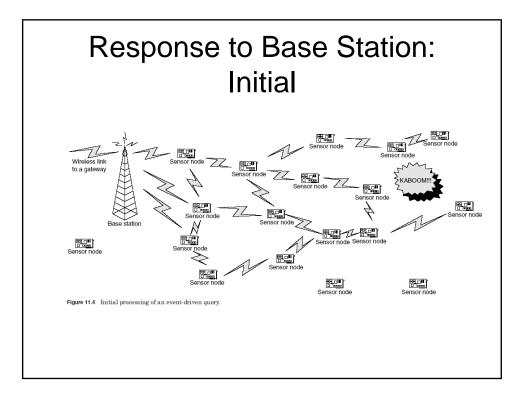


Asking a Sensor Network a Question (Querying)

- Can have sensor nodes periodically transmit sensor readings
- More likely: Ask the sensor network a question and receive an answer
- Issue: Getting the request out to the nodes
- Issue: Getting responses back from sensor nodes who have answers
- Routing:
 - Directed Diffusion Routing
 - Geographic Forwarding (related to geocasting)







Directed Diffusion Routing

- Direction: From source (sensors) to sink (base station)
- Positive/negative feedback is used to encourage/discourage sensor nodes for forwarding messages toward the base station
 - Feedback can be based on delay in receiving data
 - Positive is sent to the first and negative is sent to others
- A node sends with low frequency unless it receives positive feedback
- This feedback propagates throughout the sensor network to suppress multiple transmissions
- Eventually message forwarding converges to the use of a single path with data aggregation (for energy saving) from the source to the base station

