

“X-GDF” — THE ISO MODEL OF GEOGRAPHIC INFORMATION FOR ITS

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ABSTRACT:

This paper reviews the first international release of the Geographic Data Files (GDF) ISO standard for the ITS industry and the ongoing follow-up work. The standard, GDF 4.0, has been created by ISO/TC204 Working Group 3. GDF 4.0 represents harmonized, application-independent global specifications for the modeling of geographic information for high-end map-dependent ITS applications and services, catering for map requirements of in-vehicle navigation, dynamic route guidance, location-based services (LBS), fleet management, public transport, road administration, etc. Through its vast dictionary of standardized semantic definitions, GDF 4.0 forms a foundation for interoperability between map-based ITS applications and services. Given that map data requirements of modern ITS applications are ever growing, while the room to pay for data and data handling increases at a far less rapid pace, GDF will continue its role as vehicle to share map data costs and to minimize data handling costs by providing a uniform basis for map data processing. It plays this role in an ever changing environment which explains the continual need for evolution. Such further development is carried out by WG3 under the project name X-GDF (eXtended GDF), addressing issues like convergence with other relevant standards (ISO/TC211), new map content requirements (3D mapping, temporality, multi-modality, Safety Applications), and alternative physical realizations in terms of XML, GML and SQL.

1. THE GEOGRAPHIC DATA FILES (GDF) STANDARD

A major standardization milestone in 2004 is the publication of the first internationalized version of the Geographic Data Files (GDF) standard, referred to as GDF version 4.0 or GDF 4.0 (ISO 14285:2004).

The standard specifies the conceptual and logical data model and the exchange format for geographic data bases for ITS. It includes a specification of potential contents of such databases (Features, Attributes and Relationships), a specification of how these contents shall be represented, and of how relevant information about the database itself can be specified (meta data).

The focus of the standard to-date is on ITS applications and emphasizes road and traffic related information. ITS applications, however, also require additional information. For example:

- Information about addressing systems in order to specify locations and/or destinations. Consequently information about the administrative and postal subdivisions of an area is essential.
- Map display is an important component of ITS applications. For proper map display, inclusion of contextual information such as land and water cover is essential.
- Point-of-Interest (POI) or service information is a key feature of traveler information. It adds value to end-user ITS applications.

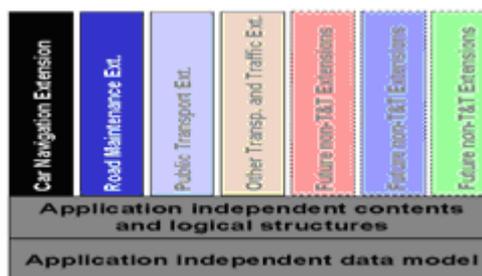


Figure 1. GDF 4.0 – An Application-Independent ISO Standard

In order to allow inclusion of both road & traffic related information as well as other types of information, the Conceptual Data Model of GDF has a broader focus than ITS applications only. Instead, it is application independent (see figure 1).

This has been very important for the success of the X-GDF harmonization work with the ISO/TC211 suite of standards for Geographic Information.

1.1 History of GDF

By the late 1980's, producers and users of digital road map data became increasingly aware of the need for a common data interchange standard. Lack of such a standard was seen as an impediment to the commercial growth and success of industries using such data. Before the advent of the Intelligent Transport

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Systems (ITS) industry, development of spatial data interchange standards was done mostly on a regional basis and not designed for the specialized requirements of road transport-related applications. Furthermore, the 1990s saw the expansion of the number of ITS application developers who needed map data vendors to supply their products in an economical, efficient and non-ambiguous manner. Moreover, the ITS applications suppliers and developers were largely deploying systems in Europe, Japan, or the USA, respectively, marking initially the need for standardization on a regional level. First standardization efforts therefore had a regional character. The roots of GDF were laid in Europe in the European projects Demeter, TFEDRM and EDRM2. Official standardization was continued in CEN/TC278 which resulted in the European pre-standard GDF3.0 (ENV ISO/TR 14825) in 1996. A large number of stakeholders contributed to this development including navigation system vendors, map providers, car manufacturers, road authorities and public transport organizations.

Globalization started in 1993 when ISO/TC204 was established. TC204 is divided into 16 working groups. Working Group 3 (WG3) was charged with the responsibility of developing standards to promote interchangeability of map data and interoperability of systems using map databases. Further development of GDF was undertaken in SWG3.1. The work of SWG3.1 started in 1994 with a review of the available regional standards documents. Considerable differences were identified. The Japanese standard developed by the Japan Digital Road Map Association (JDRMA) was oriented towards navigation applications with much emphasis placed on access speed and file size. The developments in the US had resulted in the Spatial Data Transfer Standard (SDTS), a highly generalized approach that provided a standard way of describing the contents of a geographic data set rather than on standardizing its content. GDF3.0 as developed by CEN was considered the most comprehensive model and consequently taken as a basis of the work which in the follow-up work was extended and adapted to fulfill requirements from the other regions as well as new requirements from Europe and elsewhere.

2. NEW FEATURES OF THE GDF4.0 STANDARD

Compared to the European GDF standard (GDF 3.0) the new ISO version has been upgraded in a multitude of ways. These can be categorized in two broad groups:

- *Conceptual changes* of the GDF core, relating to the Conceptual Data Model, Logical/Physical Data Structures & Meta Data.
- *Content definition changes*, relating to the Data Catalogues.

Each of the groups stated will below be shortly elaborated.

2.1 Conceptual Changes in GDF 4.0

2.1.1 Extended topological model: The objects defined in GDF have a spatial aspect. This spatial aspect has two different components, geometry (the coordinates) and topology (the spatial relations between objects).

In the European GDF standard, only one type of topology was allowed, called full topology. In full topology all spatial relations between the basic geometric elements (nodes, edges and faces) are explicitly defined. Full topology allows

maximum flexibility as far as describing the geometric characteristics of the objects. From a computing point of view it allows for the maximum amount of database integrity guarantee and quality control. As a drawback one can mention that it includes extra overhead and the fact that the flexibility is not required for a number of applications. In order to acknowledge these facts, two additional, less complete types of topology have been included in GDF4.0:

1. Connectivity topology in which the spatial relations between the nodes (point or 0-dimensional primitive) and the edges (line or 1-dimensional primitive) are fully defined. Faces do not exist in Connectivity topology.
2. Non-explicit topology in which no spatial relations between the between the basic geometric elements are defined. A typical application which can be served by non-explicit topology is map display.

2.1.2 Support of Two-Byte Character Sets: The European GDF standard was designed taking requirements of European languages into account. For these languages 1-byte character sets generally suffice. Extending the scope to include the requirements of virtually all the world languages including languages like Chinese, Japanese, Korean and Arabic introduced the need to also support the use of multi-byte character set, such as UNICODE. GDF4.0 has been extended accordingly.

2.1.3 Enhanced (Sub-) Attribute Model: The European GDF Standard already identified the need to model attribute information in a way, which is dependent on other attribute information. For example, it was identified that the different components of house number information only had relevance in relation to each other. For this, the concept of sub-attributes had been introduced. During the ISO work it however was identified the existing model was unable to model all situations. This basic sub-attribute model has been extended in GDF4.0 towards greater expressiveness (i.e. operating scope of compositions and validity restrictions).

2.2 Content Definition Changes in GDF

2.2.1 Extension to Include Non-Hierarchical Administrative Area structures: The model, with which Administrative Areas were defined in the European GDF standard, assumed a strictly hierarchical definition. This is in accordance with reality as far as most European countries are concerned. It however is not the case for countries from an Anglo-Saxon origin. Here the definition may be far less structured. GDF4.0 is extended in such a way to also include the proper definition of these kinds of Administrative Area Structures.

2.2.2 Enhanced Address Model: In the European GDF standard, Address information was not defined explicitly. Only the components like street name, postal code, house number etc. were identified. This led on the one hand to ambiguities how a specific address index in an application had to be defined and on the other hand posed limitations on the creation of these indexes. ISO-GDF has been extended in such a way to meet the requirements of address indexing.

a “transport” means of the GDF content. It might be less appropriate for direct access by an application. This work can provide the basis for the future development of one or more data loaders, each associated with a commercial database system, which would load data defined in the ASCII intermediate format definition into the commercial RDB schema, according to the specification defined above at # 1. Typically these loaders would support the addition of SQL-MM (ISO/IEC CD 13249-3) definitions which are absent in the intermediate ASCII definition. Here also the ASCII definition of the data records has been finalized and the complete definition will be available at the end of the year.

In the course of the work on XML the liaison with TC211 and corresponding contacts with OGC revealed the growing relevance of GML (Geographic Mark-up Language) (ISO/CD 19136). It also revealed the interest of the GML community to have their deployments populated with the vast amounts of geographic data available in GDF. It therefore was decided to also develop a GML realization of GDF. A joint activity between WG3 (Working Group 3 of TC204) and OGC experts led to the current situation where the GML realization of GDF is available for the data records. The complete realization will be available early 2006.

In developing a realization of GDF for the above mentioned schema languages (and the ASCII table definition) one can make a design choice to be more or less specific. Typical options here are to make a design on the conceptual level of GDF (see also figure 2) or on the more detailed logical level. One can refer to these different design options as the syntactic level and the semantic level. Typically, the syntactic level would be mainly fit for exchange purpose while the semantic level would also allow for direct access. The specifications of X-GDF will be on a syntactic level only. The semantic level is a future option.

Apart from these new realizations, GDF4.0 has the traditional Media Record Specifications. This specification will be retained in GDF with one important modification. In order to improve access and processing speed, backward references will be added to the records definition. This means that next to the pointing from Complex Feature to Simple Feature to Node/Edge/Face/Dot/Polyline/Polygon now also pointing from Node/Edge/Face/Dot/Polyline/Polygon to Simple Feature to Complex Feature is supported.

3.3 New contents requirements

Status of work on the four major areas of work can be summarized as follows:

- Two approaches towards the introduction of spatio-temporal definition of geographic objects have been subject to discussion. One which builds further on the existing time concepts in GDF like Validity Period and Construction Status and which is referred to as the *attribute time model* and one which builds further on a coordinate –based approach, referred to as the *coordinate time model* whereby two additional coordinates (i.e. the 4th dimension) specify the start time of a feature and the end time of a feature. Current thinking goes in the direction of accepting both approaches as allowable options whereby restrictions might be formulated relative to the type of topology which is supported in a data set.

The *attribute time model* foresees the introduction of the following two new attributes:

1. *Status*, providing a time interval during which the feature exists in a particular (construction) state.
2. *Proposal* providing a means to distinguish between several alternative proposal state of the “Construction Status“ value “Proposed”.

The attribute time model focusses on feature temporality. It however will also be applied for attributes and relationships. It does not support topology temporality. The topological primitives (node, edge, and if appropriate, face) will not be temporalized. Instead, it temporalizes the relationship between feature and topology. The topology network would continue to be dissected over time to be able to represent any of the features at any point in time.

The *coordinate model* is offering the clearest benefits in relation to non-explicit topological networks. One of the considered implementation consequences for the GDF4.0 delivery format is the use of specialized coordinate records (per number of spatio-temporal dimensions supported). This would represent a reversal of a GDF3.0-to-GDF4.0 change which facilitated the referencing between records (Complex Features references Simple Features, Simple Features references the geometric primitives face, edge and node, while these reference the coordinates) by removing one indirection to increase processing speed. The new flexibility gained in the spatio-temporal model is however regarded to outweigh the former demerit.

- Support for safety applications has been realized by the acceptance of the map data specifications formulated by European project NextMap. With some minor modifications all NextMap specifications have been accepted. In addition work has been done on the optional increase of the resolution of some existing safety relevant attributes. Work on curve modeling is still due. Also, an interface with the European ADASIS forum has been established. It is yet unclear whether additional requirements will be formulated from this forum before the final closing date of the work on X-GDF.
- Support for multi-modal passenger transport including pedestrian navigation has been finalized. New items include the Feature Pathway plus some additional attributes to specifically cater for movement of pedestrians and other non-motorized vehicles.
- Another important extension is the support for 2D and 3D map display. This includes support for 2D City Maps, Block Models, Facades and Roof Extension, Landmarks and Digital Terrain Models (DTM’s).

2D city maps refer to the inclusion of items usually associated with a tradition large-scale paper map like building footprints, side walk and traffic island outlines. A final specification has been agreed upon. The block model extension refers to the extension of a building outline with a height attribute. This allows 3D building visualization in the form of blocks. The facade and roof extension refers to the addition of facade textures and roof types via the existing GDF concept of MIME references to building blocks to enable a more natural map display. Also here a final specification has been agreed upon. In the block

model specification important input was obtained from the European COMPOSE project.

Landmarks are high resolution virtual reality representation of objects. They are typically used to represent important buildings and landmarks. Inclusion of landmarks is supported in X-GDF by embedding them via MIME references.

With respect to the DTM's, a general concept has been agreed upon and current work focuses on the compilation of the detailed proposal. The concept is adopting elements from different surface model specifications like GML, Land XML, and ISO/TC211 Spatial Schema. It supports Raster representation, representations through Triangular Irregular Networks (TIN's), and Iso-Hyp Lines (contour lines) representation.

4. CONCLUSION

In 2004, GDF4.0, developed by ISO/TC204 WG3 was released as the first ISO standard for Geographic Information for ITS applications. It represents a harmonized, application-independent global specifications for the modeling of geographic information for high-end map-dependent ITS applications and services, serving requirements of in-vehicle navigation, dynamic route guidance, location-based services (LBS), fleet management, public transport, road administration, etc. Through its extensive dictionary of standardized semantic definitions, GDF 4.0 forms an excellent foundation for interoperability between map-based ITS applications and services.

Currently, GDF4.0 is further developed within WG3 under the name X-GDF to comply with the ever changing market requirements. Focal points include:

1. Harmonization with ISO/TC211 standards
2. Improvement of the physical record layout with special attention to SQL, XML and GML.
3. New contents requirements incl. spatio-temporal enhancements, support for safety and multi-model passenger applications and 2D and 3D map display.

We are now in 2005 and a long way in realizing X-GDF definitions to accommodate these requirements.

In a situation where map data requirements of modern ITS applications are ever growing, while the room to pay for this data and the associated data handling increases at a far less rapid pace, GDF will continue its role as vehicle to share map data costs between applications and to minimize data handling costs by providing a uniform physical basis for map data processing. Ongoing developments and convergence efforts with related technology will ensure that GDF remains state-of-the-art, i.e. a clear conceptual base for the sharing of map data between systems.

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