

# Self-Reducibility of Hard Counting Problems with Decision Version in $P^*$

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**Abstract.** Many NP-complete problems have counting versions which are  $\#P$ -complete. On the other hand,  $\#PERFECT\ MATCHINGS$  is also Cook-complete for  $\#P$ , which is surprising as  $PERFECT\ MATCHING$  is actually in  $P$  (which implies that  $\#PERFECT\ MATCHINGS$  cannot be Karp-complete for  $\#P$ ).

Here, we study the complexity class  $\#PE$  (functions of  $\#P$  with easy decision version). The inclusion  $\#PE \subseteq \#P$  is proper unless  $P = NP$ . Several natural  $\#PE$  problems (e.g.,  $\#PERFECT\ MATCHINGS$ ,  $\#DNF-SAT$ ,  $\#NONCLIQUES$ ) are shown to possess a specific self-reducibility property. This implies membership in class  $TotP$  [KPSZ98,PZ05]. We conjecture that all non-trivial problems of  $\#PE$  share this self-reducibility property.

## 1 Introduction

Traditional complexity classes ( $P$ ,  $NP$ ,  $PH$ , ...) contain decision problems, computed by TM acceptors. TMs can, of course, compute functions as well (in complexity classes such as  $FP$ ,  $FNP$ , ...). Here, we discuss counting functions: their values are numbers ( $\#$ ) of paths of polynomial-time bounded nondeterministic TM acceptors (PNTMs).

Valiant [Val79] has introduced  $\#P$  as the class of functions that count the number of accepting paths of a PNTM. This class contains several interesting counting problems, in particular counting variants of classical NP-search problems. Some complete problems for this class, and thus hard to compute, are  $\#SAT$ ,  $\#HAMILTONCYCLES$ , etc. A remarkable fact is that, while for these problems the decision (existence) version is NP-complete, there are other  $\#P$ -complete problems which have easy (polynomial-time) decision versions, e.g.,  $\#PERFECT\ MATCHINGS$ ,  $\#DNF-SAT$ , etc.

In this paper we investigate the complexity of such “hard-to-count-easy-to-decide” problems (term borrowed from [DHK00]). A key observation is that

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these latter problems are  $\#P$ -complete under Cook reductions — but cannot be  $\#P$ -complete under Karp reductions. It turns out that Cook reductions blur structural differences between counting problems and complexity classes (see also [KPZ99]). The reason is that  $\#P$  as well as several other classes is not closed under Cook reductions (under reasonable assumptions). Therefore, in an effort to characterize these problems, we look for subclasses of  $\#P$  — closed under Karp reduction — for which there is a possibility that (some of) these problems are Karp-complete.

$\#PE$  was introduced in [Pag01] as the subclass of  $\#P$  that consists of functions  $f$  such that for any input  $x$  the question ‘ $f(x) > 0$ ?’ is polynomial-time decidable. By definition,  $\#PE$  contains  $\#PERFECT\ MATCHINGS$  and  $\#DNF-SAT$  but not  $\#SAT$ , unless  $P=NP$ .

In this paper we explore  $\#PE$  problems with respect to having a specific self-reducibility property (SRP). Among others we show that  $\#PERFECT\ MATCHINGS$ ,  $\#DNF-SAT$ , and  $\#NONCLIQUES$  possess the SRP. Moreover we exhibit the existence of artificial  $\#PE$  problems that cannot have the SRP unless  $P = NP$ .

$TotP$  was introduced in [KPSZ98] as the class of functions that count the total number of computational paths of a PNTM; it was proved that this class is equivalent to  $\#P$  under Cook reductions. On the other hand, it was shown in [KPZ99] that  $\#P$  does not reduce to  $TotP$  under Karp reductions, i.e.,  $TotP$  is a proper subclass of  $\#P$  unless  $P = NP$ .

In [PZ05] we show that  $TotP$  contains those problems of  $\#PE$  that possess the SRP.

## 2 Preliminaries and Definitions

Our model of computation is the polynomial-time bounded nondeterministic Turing machine (PNTM), i.e., there is some polynomial  $p$  so that for any input  $x$ , all computation paths have length at most  $p(|x|)$ , where  $|x|$  is the length of the input (for a detailed definition of a PNTM see, e.g., [BDG88] or [Pap94]). A counting function  $\Sigma^* \rightarrow \mathbb{N}$  is associated with a PNTM  $M$ :

$$acc_M(x) = \#\text{accepting paths of } M \text{ on input } x$$

In his seminal paper [Val79] Valiant introduced the class of counting functions  $\#P$ :

$$\#P = \{acc_M \mid M \text{ is a PNTM}\}$$

Equivalently,  $\#P$  can be seen as the class of functions that count the number of solutions of NP-search problems:

$$\#P = \{f \mid \exists \text{ predicate } Q \in P, \forall x : f(x) = |\{y \mid Q(x, y)\}|\}$$

$\#P$  is a class of very high complexity. Toda showed [Tod91] that  $PH \subseteq P^{\#P[1]}$ , where  $PH$  is the whole Polynomial-time Hierarchy [Sto76].

### 3 Classes of “Hard-to-Count-Easy-to-Decide” Problems: #PE and TotP

In [KPZ99] it was shown that while #P and TotP are equivalent under Cook reductions, this is not so under Karp reductions unless  $P = NP$ . The difference between Karp and Cook reductions is well reflected in the behavior of #P-complete problems. While there exist problems which are #P-complete under both reductions (namely, the counting versions of most NP-complete problems), there also exist problems which are #P-complete only under Cook reduction (unless  $P=NP$ ). These latter problems usually have a decision version in P and are sometimes called “hard-to-count-easy-to-decide” problems. Some examples: #PERFECT MATCHINGS, #DNF-SAT, #NONCLIQUES.

For each function  $f \in \Sigma^* \rightarrow \mathbb{N}$  we define a related language:

$$L_f = \{x \mid f(x) > 0\}$$

Note that for function problems this language represents a natural decision version of the problem. In particular, if a function  $f$  corresponds to the counting version of a search problem (i.e.,  $f$  counts how many solutions are there for a given instance) then  $L_f$  corresponds to the existence version.

The class #PE contains functions of #P whose related language is in P (i.e., the question “ $f(x) > 0$ ?” is polynomial-time decidable). In other words, #PE by definition contains all *hard-to-count-easy-to-decide* problems.

The definition of TotP involves a function associated with every PNTM  $M$ :

$$\text{tot}_M(x) = \#\text{paths of } M \text{ on input } x - 1$$

*Remark 1.* The ‘minus one’ in the definition of  $\text{tot}_M$  above was introduced so that the function can have a zero value.

TotP is defined as the class of all  $\text{tot}_M$  functions:

$$\text{TotP} = \{\text{tot}_M \mid M \text{ is a PNTM}\}$$

TotP and #PE have several similarities — and some differences.

In the remaining of the paper we discuss some #PE problems that possess the following *Self-Reducibility Property (SRP)*: An instance of the problem can be reduced to two simpler instances of the same problem. Thus, computing the number of solutions can be represented by a recursive tree. In other words, there exists a non-deterministic algorithm, the computation tree of which has as many paths as solutions (plus one: this technicality is necessary for the no-solution case).

### 4 #PE-complete Problems that Possess the SRP

In this section we show that important #PE problems possess the SRP.

**Theorem 1.** *#PERFECT MATCHINGS possesses the SRP.*

*Proof.* Given a graph  $G = (V, E)$  let  $e = (u, v)$  be an edge of  $G$ . Let also

$$G_0 := (V - \{u, v\}, E - \{\text{all edges incident to } u \text{ or } v\}), \quad G_1 := (V, E - \{e\}).$$

Clearly, there is a 1-1 correspondence between perfect matchings of  $G$  that contain  $e$  and perfect matchings of  $G_0$ ; moreover, each perfect matching of  $G$  that does not contain  $e$  is also a perfect matching in  $G_1$ , and vice versa. Hence:

$$\#PM(G) = \#PM(G_0) + \#PM(G_1)$$

□

The SRP gives rise to a recursive algorithm for #PERFECT MATCHINGS that works in non-deterministic polynomial time and has  $\#PM(G) + 1$  computation paths, because the question “ $\#PM(G_i) > 0$ ?” can be decided in polynomial time. In other words, #PERFECT MATCHINGS is in TotP (see also [PZ05]). More specifically:

If  $G$  has no perfect matchings, this can be tested in polynomial time and the recursion can be terminated (one computation path). It remains to show that for any graph  $G$  with *at least one perfect matching*, the recursion leads to exactly  $\#PM(G)$  computation paths. We show this by induction on the number of edges. Note that the extra computation path required by the definition of class TotP can be easily added as a “dummy” computation.

- If  $G$  has only one edge  $e = (u, v)$ , and  $\#PM(G) > 0$ , then  $G$  contains no other nodes except  $u$  and  $v$  and  $\#PM(G) = 1$ . Therefore,  $G_0$  is the empty graph while  $G_1$  contains only nodes  $u$  and  $v$  with no edge between them. Hence,  $\#PM(G_0) = 1$  (the empty matching) and  $\#PM(G_1) = 0$ . The algorithm can terminate having executed a unique computation path.
- Assume that the claim is true for all graphs with  $\leq k$  edges for some  $k > 0$ . Consider a graph  $G$  with  $k + 1$  edges and  $\#PM(G) > 0$ . Select an edge and construct two subgraphs of  $G$  as explained above, namely  $G_0$  and  $G_1$ , both having  $\leq k$  edges; i.e.  $\#PM(G) = \#PM(G_0) + \#PM(G_1)$ . If both  $\#PM(G_0) > 0$  and  $\#PM(G_1) > 0$ , the algorithm continues recursively executing itself for  $G_0$  and for  $G_1$ . Due to the induction hypothesis, the former leads to a computation tree with exactly  $\#PM(G_0)$  leaves while the latter leads to a tree with exactly  $\#PM(G_1)$  leaves. Hence, the whole computation tree has  $\#PM(G)$  leaves. On the other hand, if only one of the  $G_i$ 's has a perfect matching, then this can be tested in polynomial time and only the corresponding call is performed, leading to a computation tree with the correct number of leaves. Note also that it cannot happen that both  $\#PM(G_0) = 0$  and  $\#PM(G_1) = 0$  since we have assumed that  $G$  has at least one perfect matching.

The second problem that we examine is #DNF-SAT: a Boolean formula in DNF is given and we want to count the number of satisfying assignments.

**Theorem 2.** *#DNF-SAT possesses the SRP.*

*Proof.* This can be done because it is possible to select a variable  $x$  and construct formulae  $\phi_0 := \phi|_{x=0}$  and  $\phi_1 := \phi|_{x=1}$ . Clearly:

$$\#\text{DNF-SAT}(\phi) = \#\text{DNF-SAT}(\phi_0) + \#\text{DNF-SAT}(\phi_1)$$

□

As before, we can show that the SRP — together with the fact that “ $\#\text{DNF-SAT}(\phi_i) > 0$ ?” can be decided in polynomial time — makes it possible to describe a polynomial time non-deterministic algorithm that on input  $\phi$  has  $\#\text{DNF-SAT}(\phi) + 1$  computation paths (see [PZ05]).

Finally, we show that the problem  $\#\text{NONCLIQUES}$  also possesses the SRP. The problem is defined as follows: given a graph  $G = (V, E)$  and an integer  $k > 1$ , find the number of subsets of  $V$  of size  $k$  which are not cliques. Note that the problem is in  $\#\text{PE}$  since  $\#\text{NonCl}(G, k) > 0$  if and only if  $G$  is not a complete graph. Besides, it is  $\#\text{P}$ -complete in the Cook sense because one call to the  $\#\text{NONCLIQUES}$  oracle suffices in order to compute the number of cliques of a graph. More specifically for a graph  $G$  with  $n$  nodes:

$$\#\text{Cliques}(G, k) = \binom{n}{k} - \#\text{NonCl}(G, k)$$

**Theorem 3.** *#NONCLIQUES possesses the SRP.*

*Proof.* For a graph  $G = (V, E)$ , let  $\#\text{NonCl}(G, k)$  denote the number of non-cliques of size  $k$  in  $G$ . Select a node  $v$  and let  $u_1, \dots, u_l$  be the nodes that are not adjacent to  $v$ . Let also

$$\begin{aligned} G_0 &:= (V - \{v\}, E - \{\text{all edges incident to } v\}), \\ G_1 &:= (V - \{v, u_1, \dots, u_l\}, E - \{\text{all edges incident to } v, u_1, \dots, u_l\}). \end{aligned}$$

A careful counting reveals that  $\#\text{NonCl}(G_0, k)$  is equal to the number of non-cliques of size  $k$  in  $G$  that do not contain  $v$ ;  $\#\text{NonCl}(G_1, k - 1)$  is equal to the number of non-cliques of size  $k$  in  $G$  that contain  $v$  but none of the  $u_i$ 's; finally,  $\sum_{i=2}^l \binom{n-i}{k-2}$  is equal to the number of non-cliques of size  $k$  in  $G$  that contain  $v$  and at least one of the  $u_i$ 's. Hence:

$$\#\text{NonCl}(G, k) = \#\text{NonCl}(G_0, k) + \#\text{NonCl}(G_1, k - 1) + \sum_{i=2}^l \binom{n-i}{k-2}$$

Besides, for any graph  $G$ ,  $\#\text{NonCl}(G, 1) = 0$  and  $\#\text{NonCl}(G, k) = 0$  if  $k > n$ .

□

Again, a polynomial time non-deterministic algorithm with number of computation paths equal to  $\#\text{NonCl}(G, k) + 1$  exists because the question  $\#\text{NonCl}(G, k) > 0$  can be decided in polynomial time.

Using similar arguments it can be shown that several other  $\#\text{PE}$ -complete problems possess the SRP.

## 5 Self-reducibility: Generalization and Formalization

In the previous section we saw that several important #PE problems have the SRP. Recall that SRP for all these problems is the possibility of reducing them to other instances of the same problem. Let us now formalize this notion:

**Definition 1.** A function  $f : \Sigma^* \rightarrow \mathbb{N}$  is called poly-time self-reducible if there exist polynomial time computable functions  $h_0, h_1 : \Sigma^* \rightarrow \Sigma^*$  and  $g : \Sigma^* \rightarrow \mathbb{N}$  such that for all  $x \in \Sigma^*$ :

- (a)  $f(x) = f(h_0(x)) + f(h_1(x)) + g(x)$ ,
- (b) there exists polynomial  $q$  such that  $f(y) = 0$  for  $y = (h_{i_{q(|x|)}} \circ \dots \circ h_{i_1})(x)$ ,  $i_j \in \{0, 1\}$ .

In the above definition, (a) states that  $f$  can be processed recursively by reducing  $x$  to  $h_0(x)$  and  $h_1(x)$ , and (b) states that the recursion terminates after at most polynomial depth.

*Remark 2.* A broader notion of self-reducibility could have been used instead of (a) in Definition 1:  $f(x) = g(x) + \sum_{i=0}^{r(|x|)} g_i(x) f(h_i(x))$ , where  $r$  is a polynomial and  $h_i, g_i \in \text{FP}$ ,  $0 \leq i \leq q(|x|)$  and  $g \in \text{FP}$ . We have chosen to use the simpler notion since it suffices for our purposes.

We have recently proven the following:

**Theorem 4 ([PZ05]).** TotP is exactly the closure under Karp reductions ( $\leq_m^p$ ) of the class of #PE problems that possess the SRP.

Therefore, results of the previous section imply that all three problems #PERFECT MATCHINGS, #DNF-SAT and #NONCLIQUES belong to TotP. Moreover, several other counting problems can now be easily shown to be in TotP. For example, consider the problem #NONINDEPENDENTSETS: given a graph  $G = (V, E)$  and an integer  $k > 1$ , find the number of subsets of  $V$  of size  $k$  which are not independent. Note that the problem is in #PE since the number of non-independent subsets of  $V$  of size  $k$  is non-zero if and only if  $|E| \neq 0$ , i.e.  $G$  has at least one edge. This problem is also #PE-complete under Cook reductions using an analogous argument as that used for #NONCLIQUES.

**Corollary 1.** #NONINDEPENDENTSETS is in TotP.

*Proof.* The number of non-independent sets of size  $k$  in  $G$  is equal to the number of non-cliques of size  $k$  in the complement graph  $\bar{G}$ . This implies a Karp reduction of #NONINDEPENDENTSETS to #NONCLIQUES. Using Theorem 4 the claim follows.

Of course, it is not too hard to show directly that #NONINDEPENDENTSETS has the SRP and therefore is in TotP, again using Theorem 4; the above example illustrates an alternative, often simpler technique for obtaining membership in TotP.

On the other hand, not all #PE problems possess the SRP, unless  $P = NP$ . Consider for example the problem #SAT<sub>+1</sub>: for any input CNF formula  $\phi$ , return the number of satisfying assignments plus one. Problem #SAT<sub>+1</sub> is trivially in #PE since it is in #P (simulate a PNTM for SAT and add one computation path) and for any Boolean formula  $\phi$ , #SAT<sub>+1</sub>( $\phi$ ) > 0. If #SAT<sub>+1</sub> possesses the SRP then by Theorem 4 it is in TotP, hence  $\exists$  PNTM  $M$ :

$$\#SAT(\phi) + 1 = \#\text{paths of } M(\phi) - 1$$

i.e., it would be decidable in polynomial time whether #SAT( $\phi$ ) > 0 by simply checking whether  $M$ 's computation on input  $\phi$  has more than two computation paths or not; this would therefore imply  $P = NP$ . However, #SAT<sub>+1</sub> is an artificial and a trivial problem, i.e., the corresponding decision version has always a 'yes' answer. It is an interesting open question whether there exist non-trivial #PE problems which do not possess the SRP under some reasonable complexity assumption.

## 6 Conclusions

In this paper we have investigated the *Self-Reducibility Property* (SRP) of counting functions with easy decision version (class #PE [Pag01]). We have shown that important counting problems such as #PERFECT MATCHINGS, #DNF-SAT, and #NONCLIQUES, have the SRP. An interesting consequence of our results is that all these functions — and several other, e.g. #NONINDEPENDENTSETS — belong to the complexity class TotP. This in turn implies that they can be described by means of an alternative computational model; namely, for each of them there is a PNTM that on a given input, executes as many computation paths as the function value on that input (see also [PZ05]). We expect that this characterization will help discover new properties of such problems.

We have also shown that there exist problems in #PE that do not possess the SRP unless  $P = NP$ ; however, such problems are *trivial*, that is, the corresponding decision version has always a 'yes' answer. We conjecture that all non-trivial problems of #PE possess the SRP.

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